

Mixed precision: when is it worth it?

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November 10, 2021



Floating point representation

IEEE-754 FP64 double, double precision

11 bits

52 bits

IEEE-754 FP32 float, single precision

8 bits

23 bits

IEEE-754 FP16 half, half precision

5

10 bits

NVIDIA TF32

8 bits

10 bits

Google BFLOAT16

8 bits

7 bit

Signed bit

Range

Precision

Key challenges of exascale computing

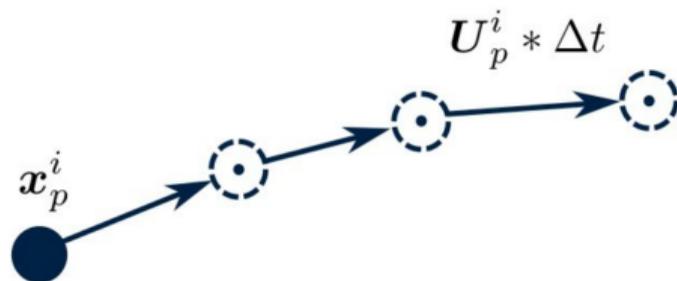
In 2008 Exascale Study Group (ESG) issued a report: Technology Challenges in Achieving Exascale Systems [8]

- 1 power consumption
 - 600 MW \rightarrow 20 MW
- 2 speed and energy of data movement
 - time of data movement $>$ time of FLOP
- 3 fault tolerance
 - Failures happen faster, than checkpointing a job.
- 4 extreme parallelism
 - To compute at a rate of 1 exaflop requires 1 billion floating point units performing 1 billion calculations per second each

Wide interest in mixed precision

- Less communication
 - Reduce memory traffic
 - Reduce network traffic
- Reduce memory footprint
- More Flop per second
 - Reduced energy consumption
 - Reduced time to compute
- Gordon Bell Prize winner climate simulation [9]
- Gordon Bell Prize winner opioid addiction research [7]
- Best paper at ISC'19 GPUMixer [10]
- Earthquake simulation [6]
- Mixed precision in-memory computing [11]
- AI, Deep learning [13], [12]
- Linear solvers, numerical methods [1], [2], [4]

Particle method



Position: FP64
Displacement: FP32

Machine learning [12]

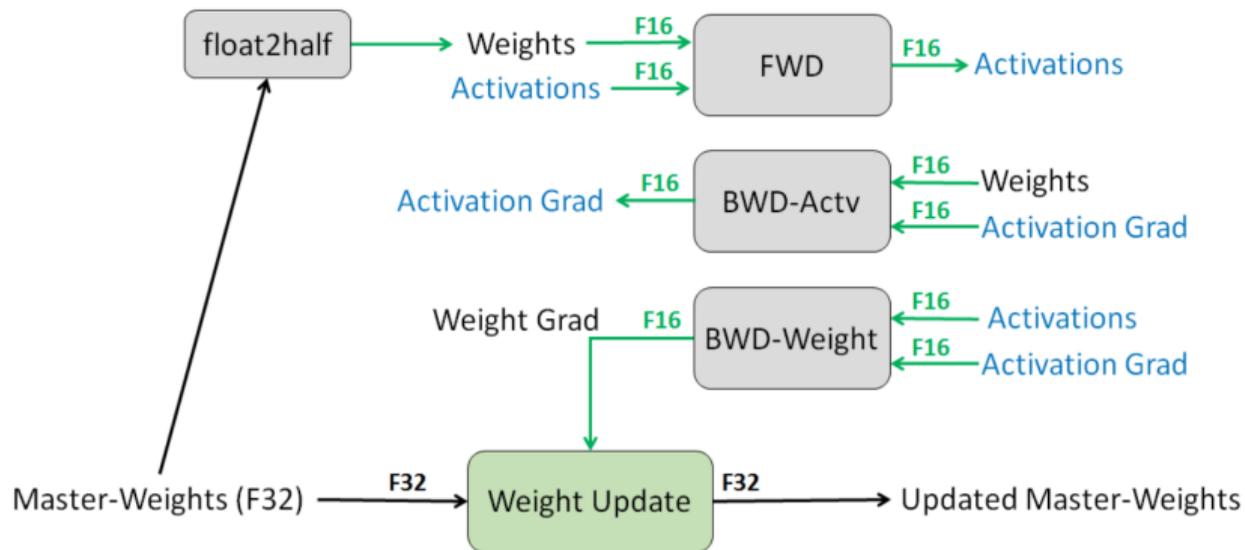


Figure: Mixed precision training iteration for a layer. Memory consumption of deep learning models nearly halved.

Linear solver in Ginkgo[3]

Linear system $Ax=b$

Rule of thumb [5]:

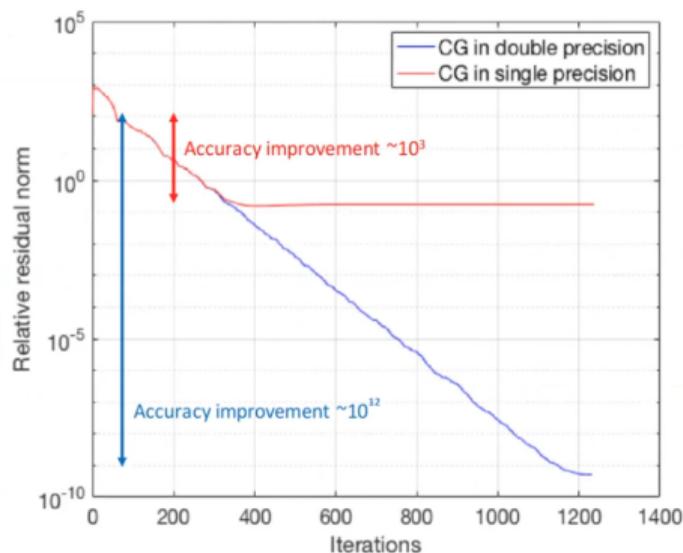
$$\text{relative residual accuracy} = (\text{unit round-off}) * (\text{linear system's condition number})$$

Linear solver in Ginkgo[3]

Linear system $Ax=b$ with $\text{cond}(A)=4$

Rule of thumb [5]:

relative residual accuracy = (unit round-off) * (linear system's condition number)

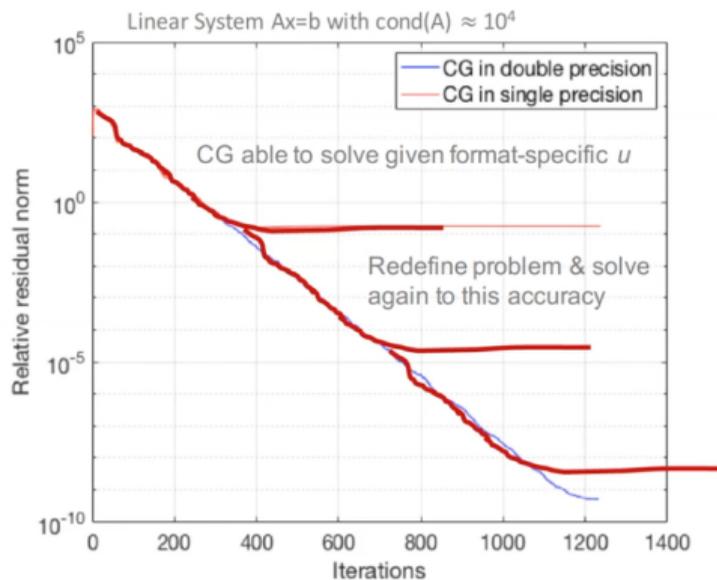


Linear solver in Ginkgo[3]

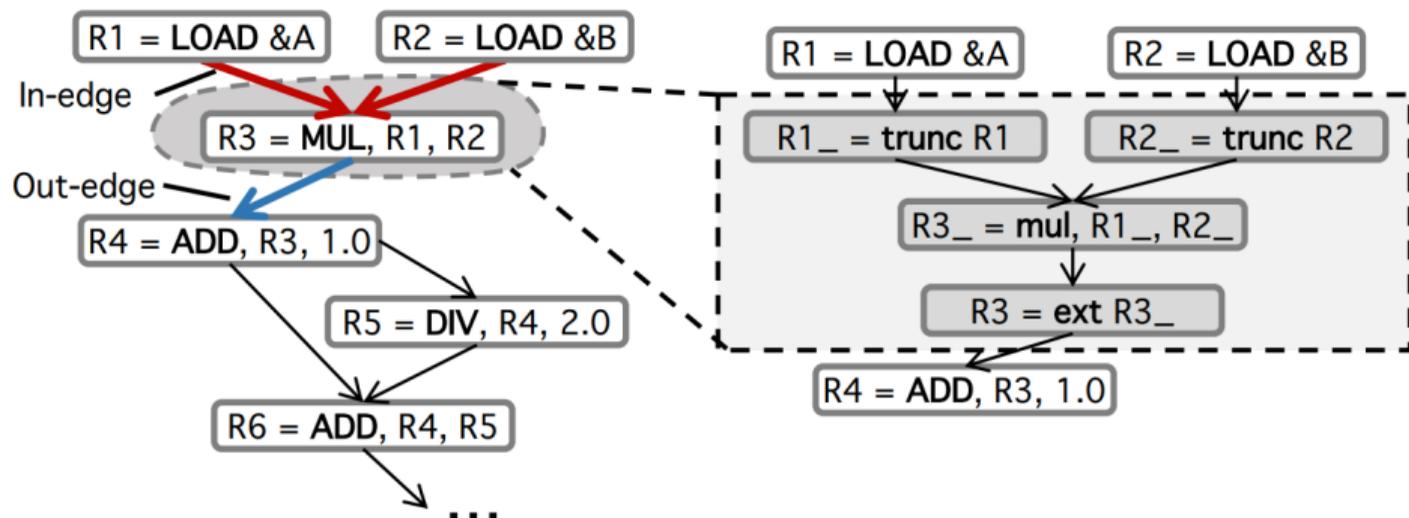
Linear system $Ax=b$ with $\text{cond}(A)=4$ 16% runtime improvement

Rule of thumb [5]:

relative residual accuracy = (unit round-off) * (linear system's condition number)



GPUMixer [10]



Step 1: Arithmetic-to-Cast Operations Ratio = 1:3

Figure: Illustration of the algorithm to find Fast Imprecise Sets (FISets)

GPUMixer [10]

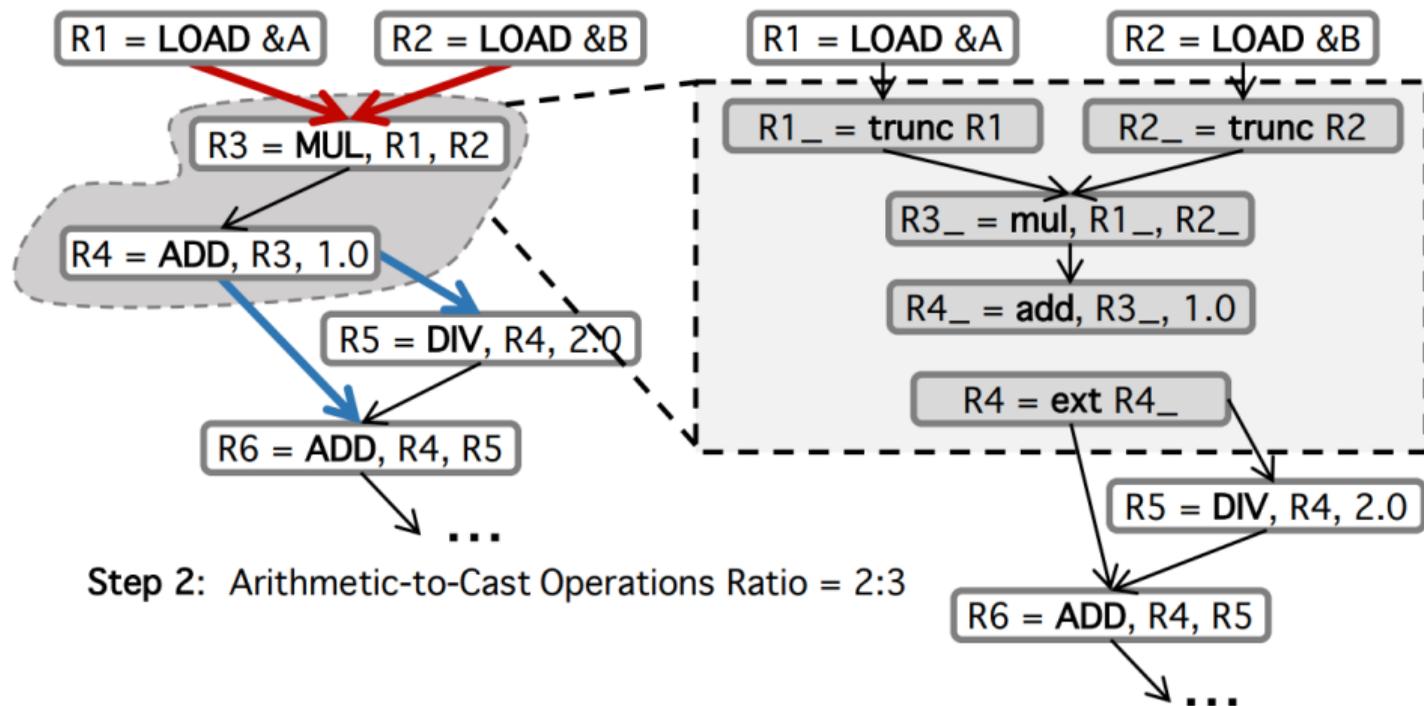
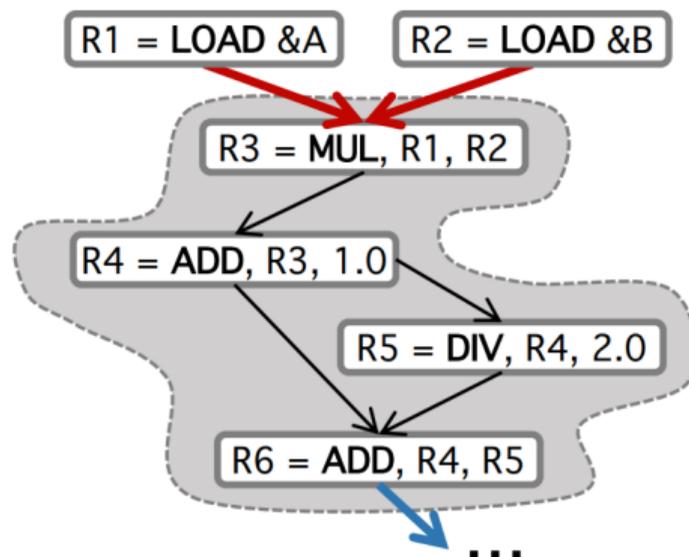


Figure: Illustration of the algorithm to find Fast Imprecise Sets (FISets)

GPUMixer [10]

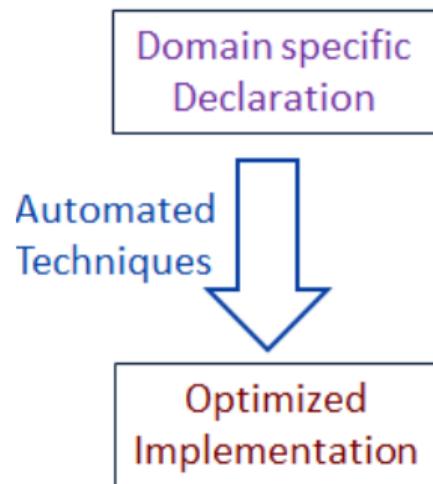


Step N: Arithmetic-to-Cast
Operations Ratio = 4:3

Figure: Illustration of the algorithm to find Fast Imprecise Sets (FISets) 46.4% of the ideal speedup

One approach to develop future proof HPC applications is the use of domain specific high-level abstractions (HLAs)

- Provide the application developer with a domain specific abstraction
 - To declare the problem to be computed
 - Without specifying its implementation
 - Use domain specific constructs in the declaration
- Create a lower implementation level
 - To apply automated techniques for translating the specification to different implementations
 - Target different hardware and software platforms
 - Exploit domain knowledge for better optimisations on each hardware system



OP2

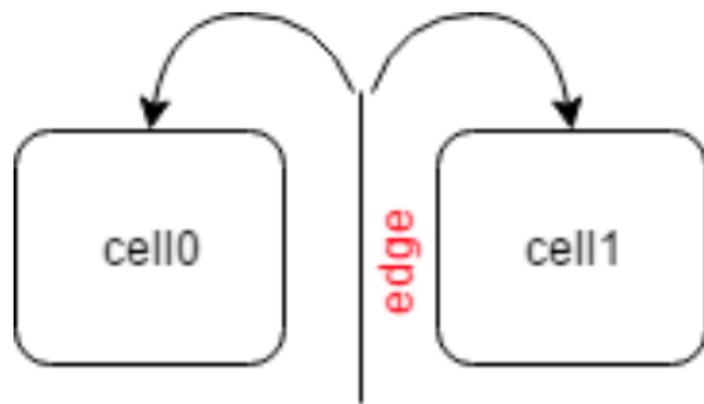
- Open Source project
- OP2 based on OPlus (**O**xford **P**arallel **L**ibrary for **U**nstructured **S**olvers), developed for CFD codes on distributed memory clusters
- Separate high level description from parallel implementation
- Looks like a conventional library, but uses code transformations (source to source translator) to generate parallel codes
- Support application codes written in C++ or FORTRAN

OP2 loop over edges

```

void res(double* edge,
        double* cell0,
        double* cell1){
    *cell0 += *edge;
    *cell1 += *edge;
}

```



```

op_par_loop(res, "residual_calculation", edges,
            op_arg(dedges, -1, OP_ID, 1, "double", %OP_READ),
            op_arg(dcells, 0, pecell, 1, "double", OP_INC),
            op_arg(dcells, 1, pecell, 1, "double", OP_INC));

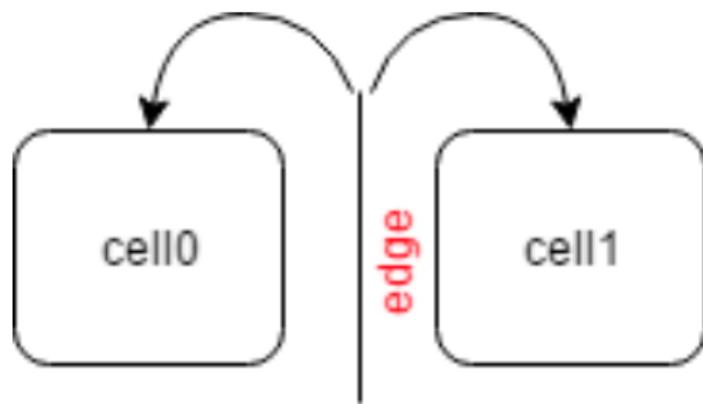
```

OP2 loop over edges

```

void res(double* edge,
         float* cell0,
         float* cell1){
    *cell0 += *edge;
    *cell1 += *edge;
}

```



```

op_par_loop(res, "residual_calculation", edges,
            op_arg(dedges, -1, OP_ID, 1, "double", %OP_READ),
            op_arg(dcells, 0, pecell, 1, "float", OP_INC),
            op_arg(dcells, 1, pecell, 1, "float", OP_INC));

```

Example test

- CPU related environment
 - Intel(R) Xeon(R) Gold 6226R CPU @ 2.90GHz with 64 processes
- GPU related environment
 - dgx-station with 2 Nvidia V100 GPUs
- Test application
 - **Airfoil**, a standard finite volume CFD benchmark code with a 2.8M mesh size

Environment	FP64	FP32	Mixed	speedup - mixed	speedup - float
Intel	14.44s	8.22s	12.76s	1.13	1.76
Nvidia	2.17s	1.51s	1.97s	1.1	1.44

Contact

- **OP-DSLs:** <https://op-dsl.github.io/>
- **OP2:** <https://github.com/OP-DSL/OP2-Common>
- siklosi.balint@itk.ppke.hu



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MINISZTERIUM

SUPPORTED BY THE ÚNKP-21-3 NEW NATIONAL EXCELLENCE PROGRAM OF THE MINISTRY FOR INNOVATION AND TECHNOLOGY FROM THE SOURCE OF THE NATIONAL RESEARCH, DEVELOPMENT AND INNOVATION FUND.

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