

Pentadsolver, a scalable batch-pentadiagonal solver library for ADI applications

Gábor Dániel Balogh, István Reguly

Pázmány Péter Catholic University
Faculty of Information Technology and Bionics

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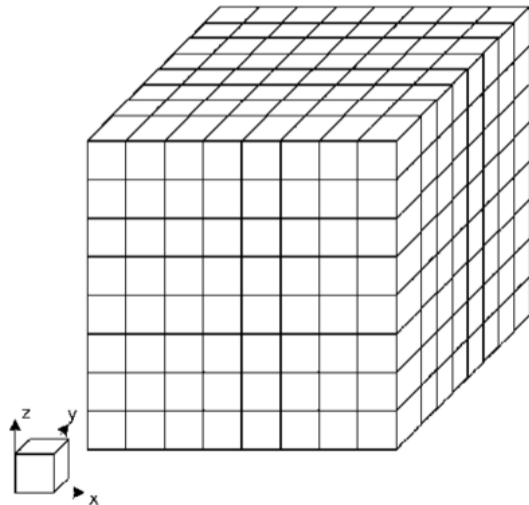


- 1 What is a pentadiagonal system and where to find them?
- 2 Pentadsolver library implementation considerations
- 3 Performance

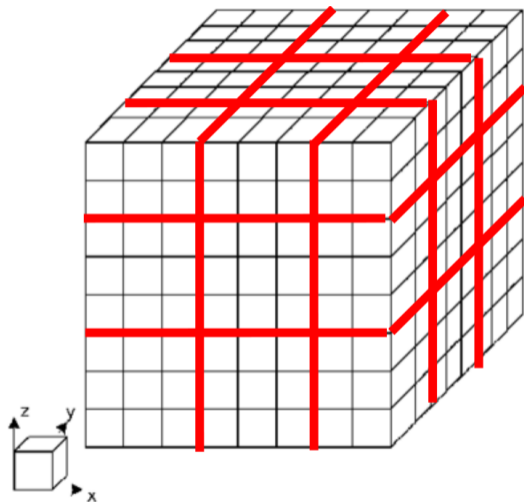
- We worked on a distributed batch-tridiagonal solver library
- In a CFD context, pentadiagonal systems have the potential to offer more flexibility and more accuracy.
- This work is a follow up on that library.

Batching & Higher dimensions

- Solving a single 1D system is easy
- Higher dimensional problem:
Alternating Direction Implicit method
 - E.g. flow solvers based on implicit high-order finite-difference schemes
 - Solve along x direction, then y direction, then z
 - Coefficients & unknowns laid out on 3D mesh

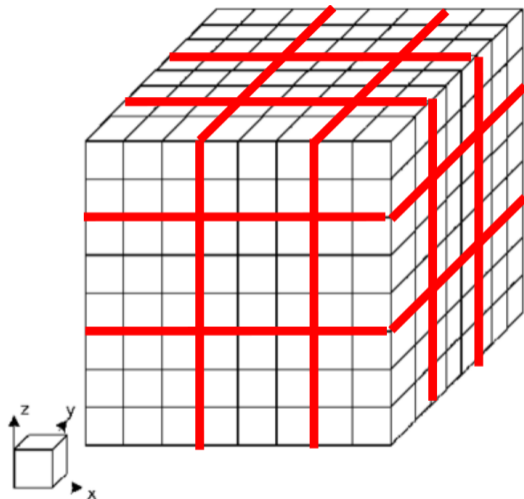


- Grid is decomposed along all the axes, processes only hold a block of any given pentadiagonal system
- Within each partition:
Thomas + PCR/Jacobi Hybrid



Pentadsolver

- Grid is decomposed along all the axes, processes only hold a block of any given pentadiagonal system
- Within each partition:
Thomas + PCR/Jacobi Hybrid
- Distributed reduced system solve options:
 - Allgather, solve, backsubstitute
 - One large comm step
 - PCR-X
 - Multiple smaller messages to increasingly distant processes
 - Approximate solution with Jacobi iteration
 - Multiple smaller messages to neighbors

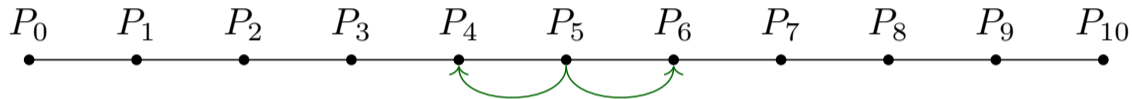


Pentadsolver - Tomas Hybrid

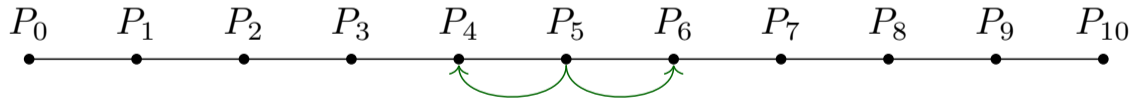
$$\left[\begin{array}{cccccc} d_0 & u_0 & w_0 & & & \\ l_1 & d_1 & u_1 & w_1 & & \\ s_2 & l_2 & d_2 & u_2 & w_2 & \\ & s_3 & l_3 & d_3 & u_3 & w_3 \\ & & s_4 & l_4 & d_4 & u_4 & w_4 \\ & & & s_5 & l_5 & d_5 & u_5 & w_5 \\ \hline & & & & s_6 & l_6 & d_6 & u_6 & w_6 \\ & & & & & s_7 & l_7 & d_7 & u_7 & w_7 \\ & & & & & & s_8 & l_8 & d_8 & u_8 & w_8 \\ & & & & & & & s_9 & l_9 & d_9 & u_9 & w_9 \\ & & & & & & & & s_{10} & l_{10} & d_{10} & u_{10} & w_{10} \\ & & & & & & & & & s_{11} & l_{11} & d_{11} & u_{11} & w_{11} \\ \hline & & & & & & & & & & s_{12} & l_{12} & d_{12} & u_{12} & w_{12} \\ & & & & & & & & & & & s_{13} & l_{13} & d_{13} & u_{13} & w_{13} \\ & & & & & & & & & & & & s_{14} & l_{14} & d_{14} & u_{14} & w_{14} \\ & & & & & & & & & & & & & s_{15} & l_{15} & d_{15} & u_{15} \\ & & & & & & & & & & & & & & s_{16} & l_{16} & d_{16} \end{array} \right] \left[\begin{array}{c} x_0 \\ x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \\ \hline x_6 \\ x_7 \\ x_8 \\ x_9 \\ x_{10} \\ x_{11} \\ \hline x_{12} \\ x_{13} \\ x_{14} \\ x_{15} \\ x_{16} \end{array} \right] = \left[\begin{array}{c} b_0 \\ b_1 \\ b_2 \\ b_3 \\ b_4 \\ b_5 \\ \hline b_6 \\ b_7 \\ b_8 \\ b_9 \\ b_{10} \\ b_{11} \\ \hline b_{12} \\ b_{13} \\ b_{14} \\ b_{15} \\ b_{16} \end{array} \right]$$

Communication in the reduced solve: Jacobi iterations

Iteration 1

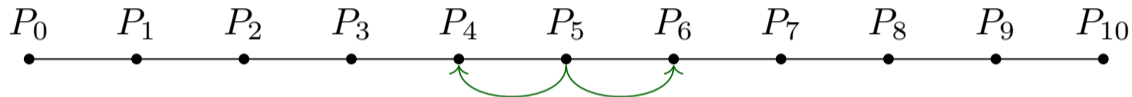


Iteration 2

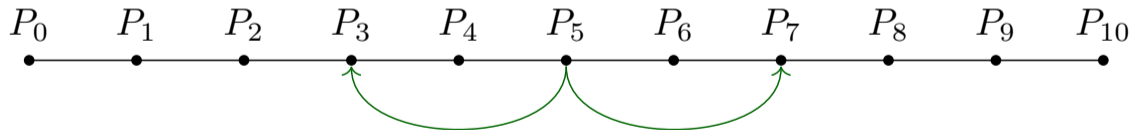


Communication in the reduced solve: PCR with blocks

Iteration 1

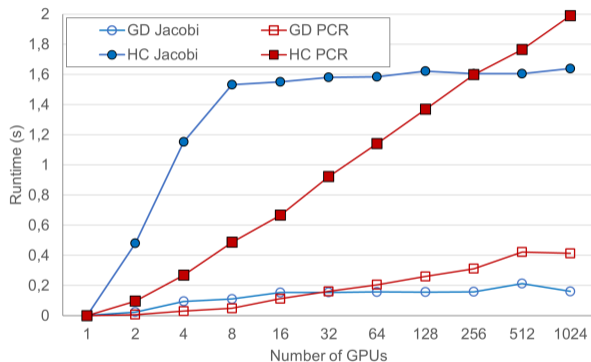


Iteration 2

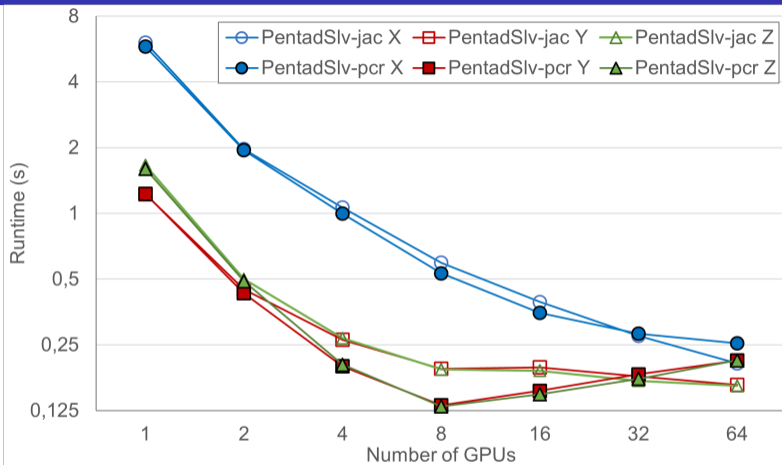


- LUMI
- AMD Trento CPU, 64 cores
- 4x AMD MI250X per node (8 GPUs per node)
- 10 iterations for Jacobi solver
- All MPI ranks in the solve direction

- All other parts of the solver trivially scales
- **Host Copy vs GPU Direct**
- Fix 10 Jacobi iterations
 - Performance change on GPU and node borders
- PCR with blocks shows the cost of each additional iteration as well

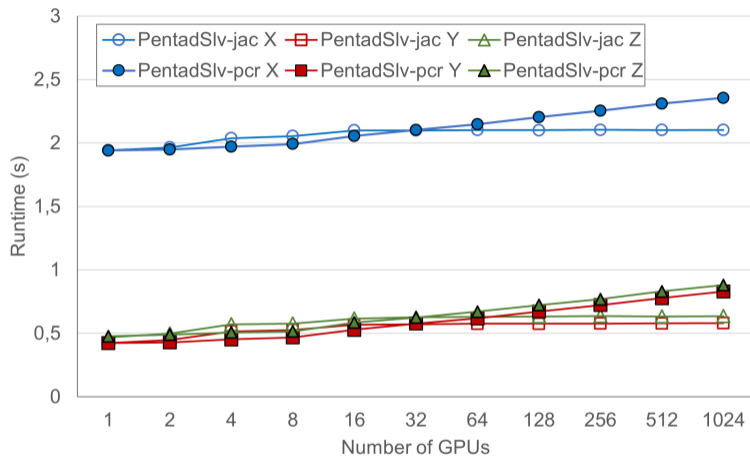


Pentadsolver - Strong Scaling $1024 \times 512 \times 512$



- 80% Scaling efficiency until 8 GPUs ($128 \times 512 \times 512$)
- After 8 GPUs the problem is just too small

Pentadsolver - Weak Scaling 512³



- Jacobi: 92% (X) and 73% (Y, Z) scaling efficiency to 1024 GPUs
- PCR: 98% (X), 80% (Y, Z) scaling efficiency to 8, 82% (X), 51% (Y,Z) to 1024 GPUs

Conclusions

- Parallelization of batch pentadiagonal system solves: across systems
- Can be used in distributed memory systems
- Scaling behavior determined by the reduced solve
 - Close communication is much cheaper
 - Small cost of each iteration of the reduced solve adds up

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