



# Reinforcement Learning in Bayesian Hamiltonian Tracking for Noise-Driven Coherent Rotation of a Spin Qubit



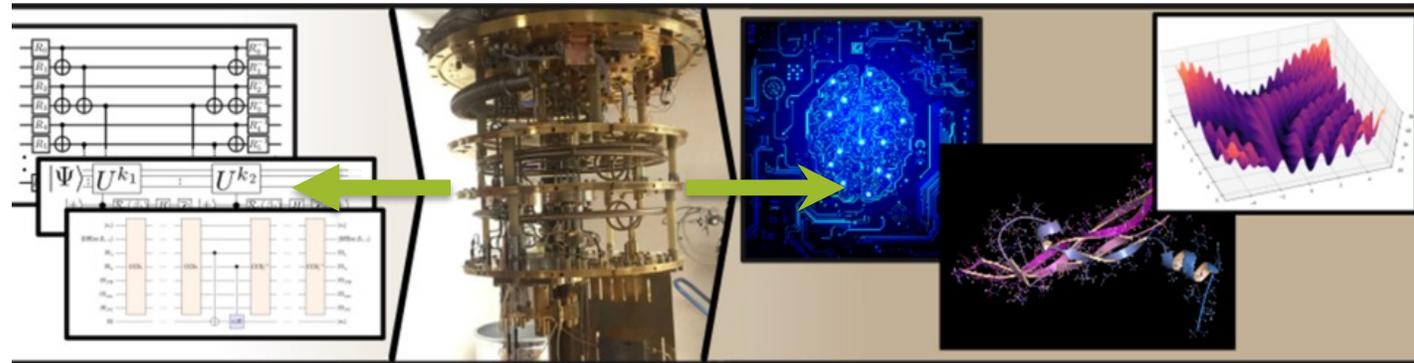
Evert van Nieuwenburg

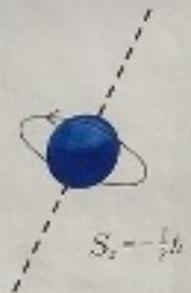
Jan A. Krzywda | Budapest 20.06.2024

$\langle aQa^L \rangle$



Universiteit  
Leiden  
The Netherlands





$$S_z = -\frac{1}{2} h$$

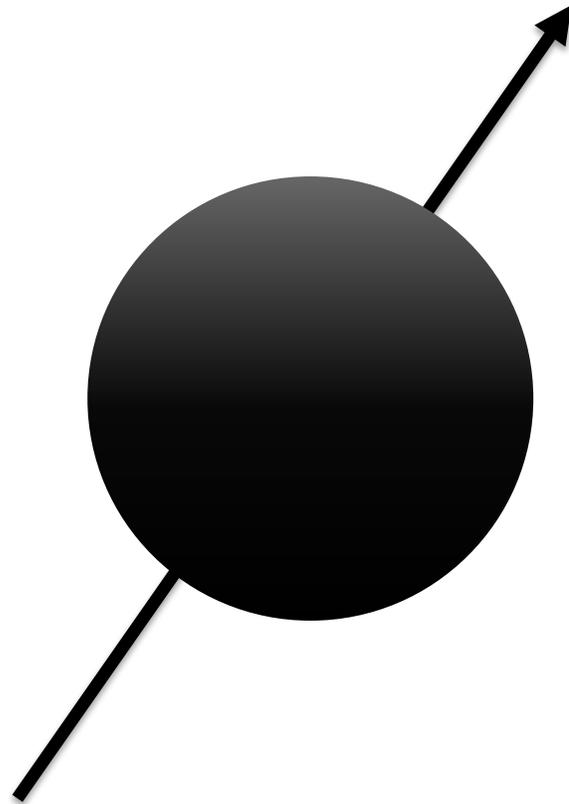
Een sikkten draait linksom of...  
KUNST IN LINDEN 2001-2002



$$S_z = +\frac{1}{2} h$$

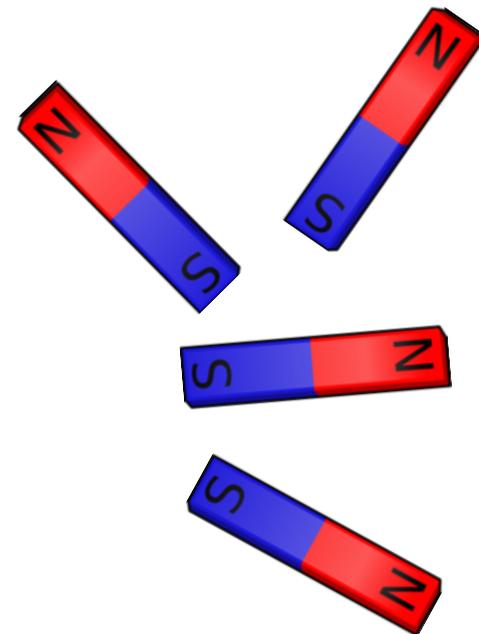
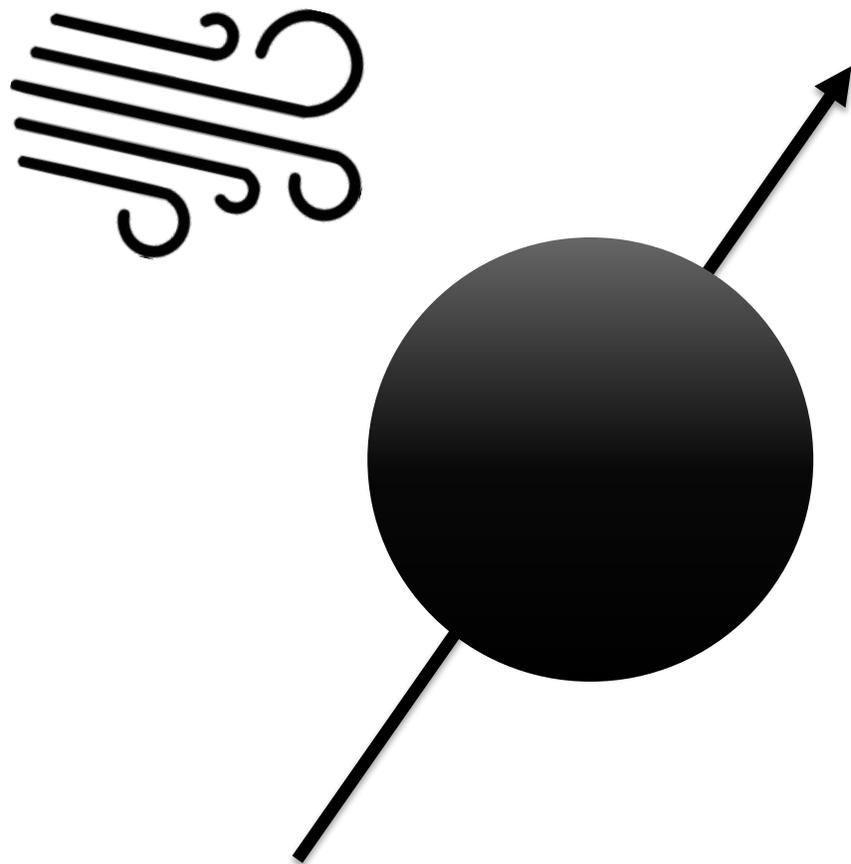
..... het draait rechtsom  
SAMUEL JOHNSON (1791-1850)  
i. v. v.

# Idea



$$H = \omega S_z$$

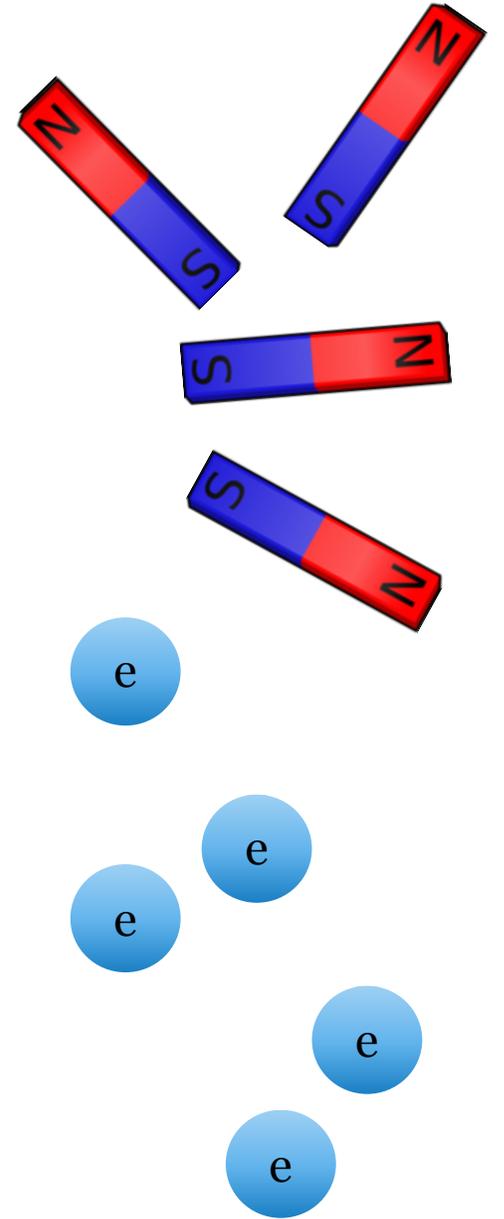
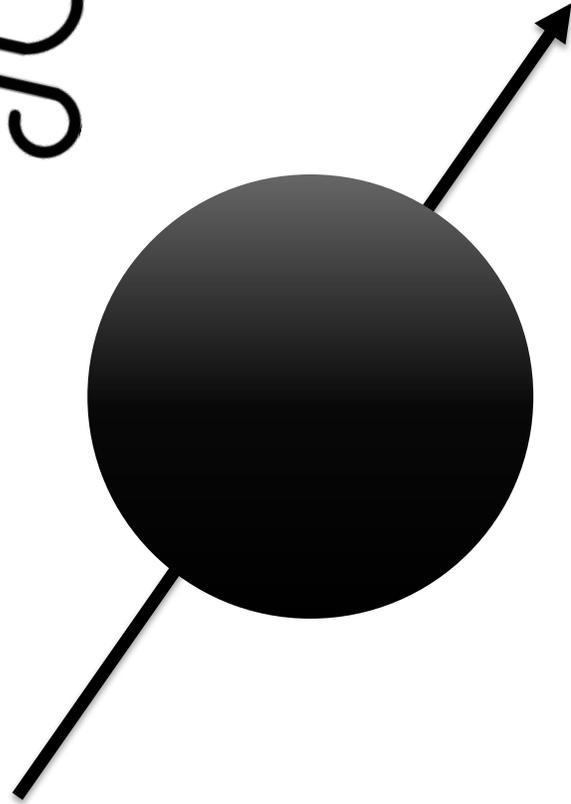
# Idea



$$H = [\omega + \delta\omega(t)]S_z$$

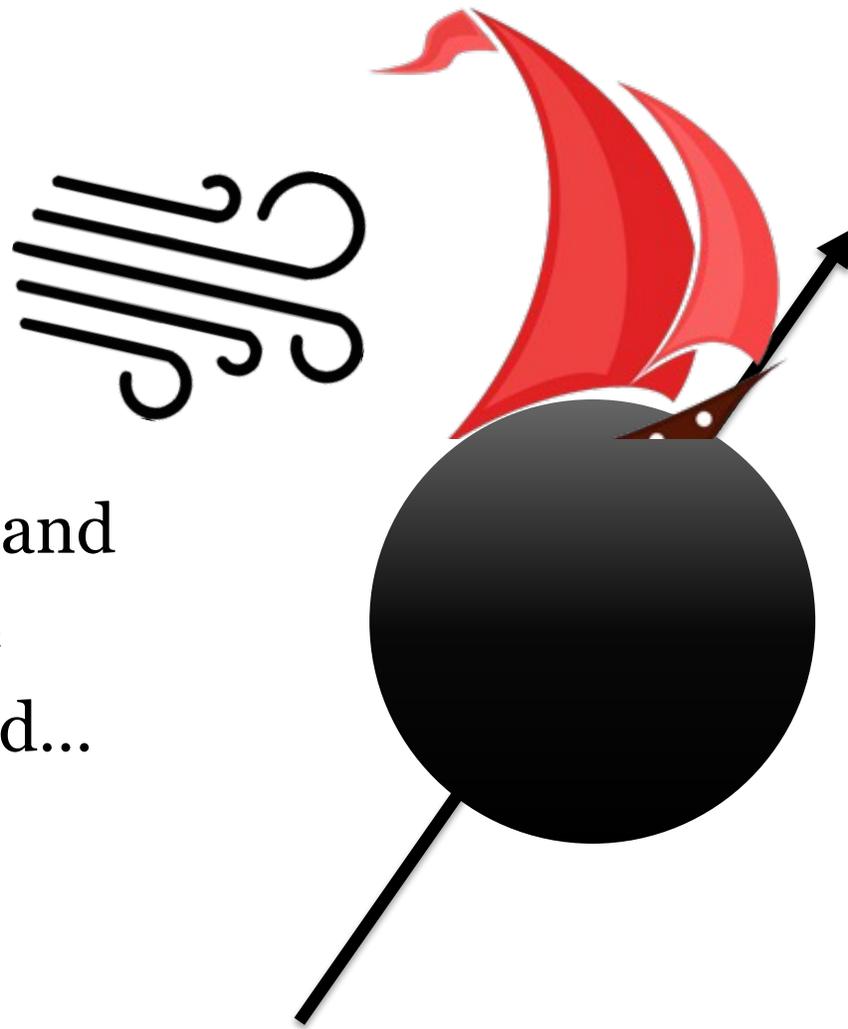
# Idea

Because noise and control are interconnected...



$$H = [\omega + \delta\omega(t)]S_z$$

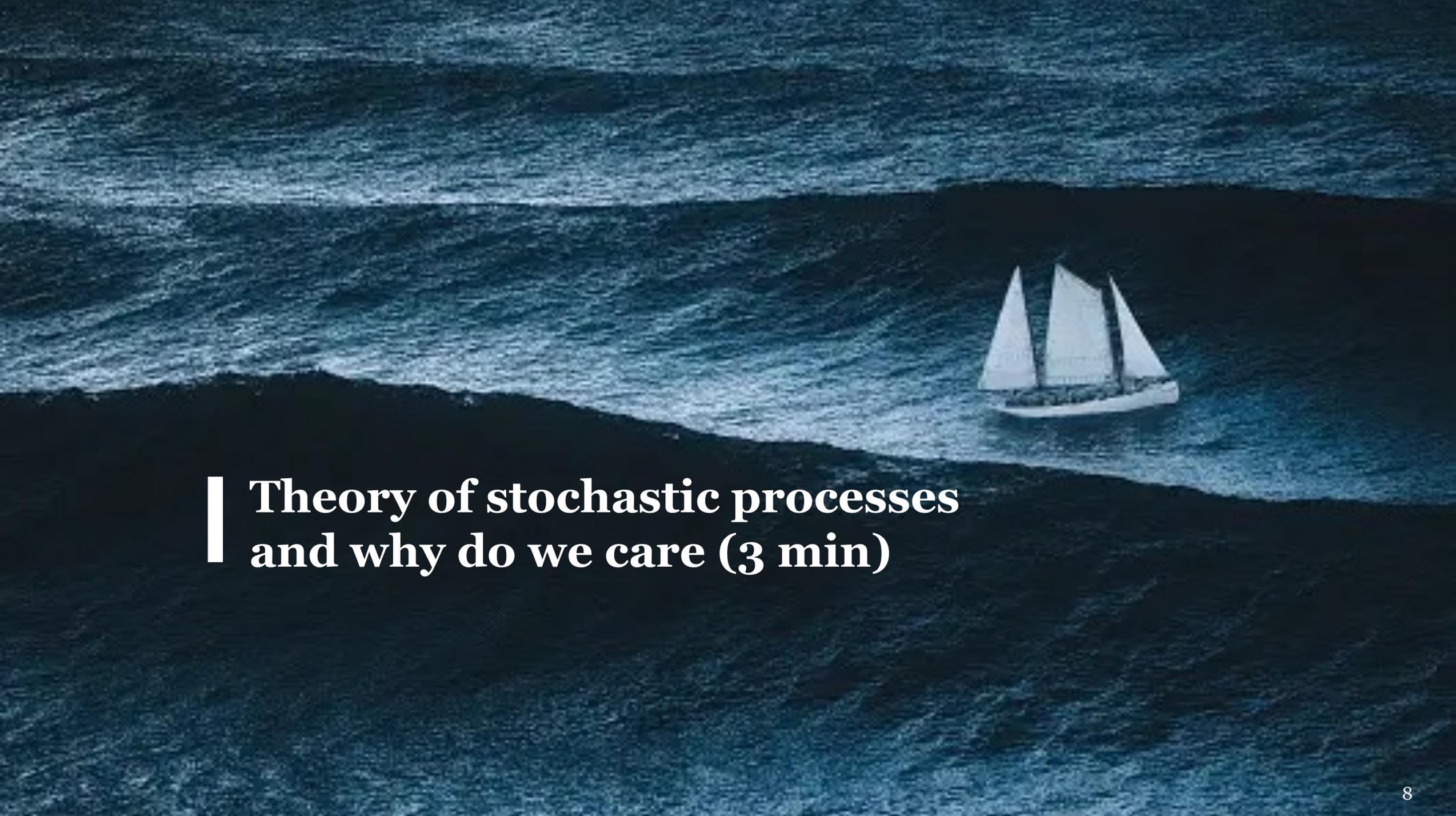
# Idea



Because noise and control are interconnected...

...why not use the noise for coherent control?

$$H = [\omega + \delta\omega(t)]S_z$$

A blue-tinted photograph of a sailboat on the ocean. The sailboat is white with three sails and is positioned in the middle-right of the frame. The water is dark blue with some whitecaps. The overall mood is serene and somewhat somber due to the monochromatic color scheme.

**| Theory of stochastic processes  
and why do we care (3 min)**

# Colors of Noise

Markovian  
(Quantum optimal control,  
Master equation, QEC, QEM)

## White Noise

White noise equally contains all frequencies across the spectrum of audible sound.



Fans



Television Static



Vacuum Humming



$$\rho(t + s) = e^{Ls} \rho(t)$$

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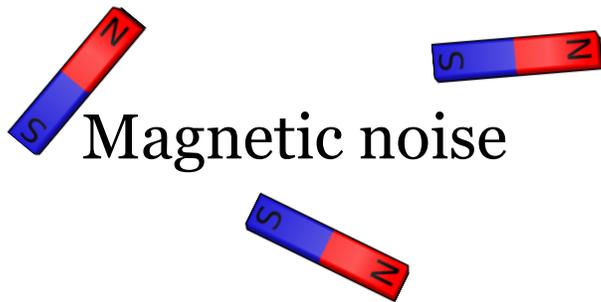
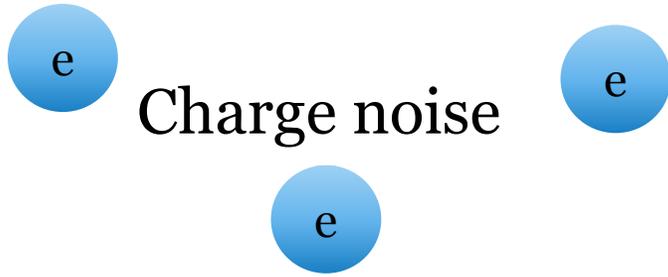
Vacuum Humming

At the level of specific open challenges, the **question how reachability differs for non-Markovian compared to Markovian dynamics remains largely unexplored**

Koch, Christiane P., et al. "Quantum optimal control in quantum technologies. Strategic report on current status, visions and goals for research in Europe." *EPJ Quantum Technology* 9.1 (2022): 19.

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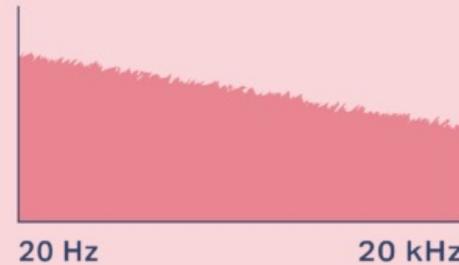
Television Static



Vacuum Humming

## Pink Noise

Pink noise frequencies decrease in power with each higher octave to create a lower pitch.



Light Rain



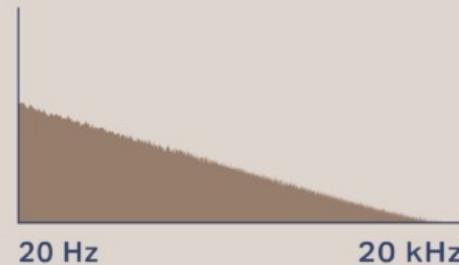
River



Wind

## Brown Noise

Brown noise is deep pitched, and the power behind frequencies decreases twice as much as pink noise.



Rumbling Thunder



Waterfall



Heavy Rainfall

# Colors of Noise

## White Noise

White noise equally contains all frequencies across the spectrum of audible sound.



Fans



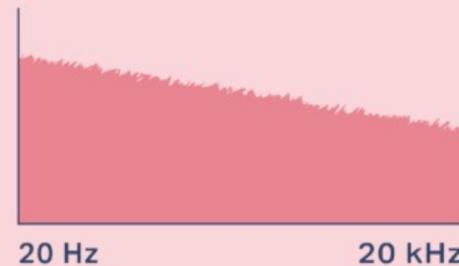
Television Static



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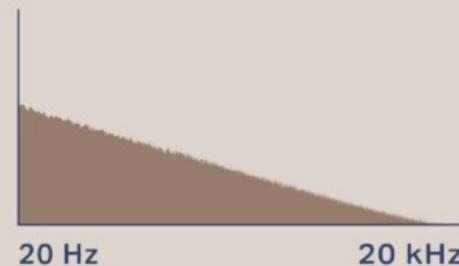
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Wind

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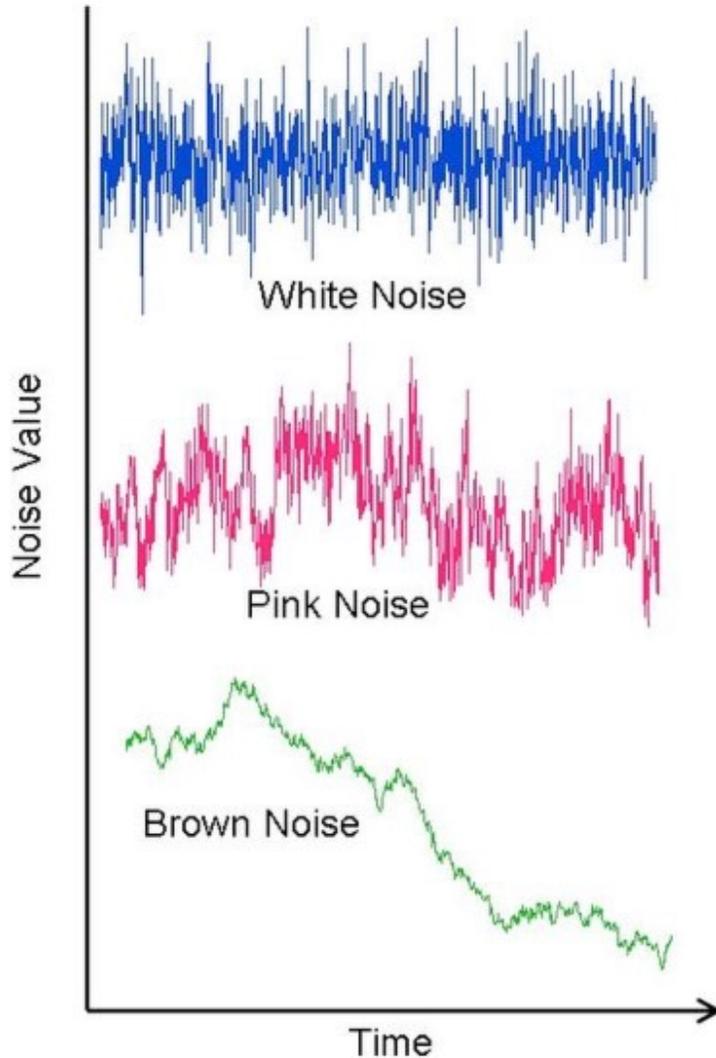
Rumbling Thunder



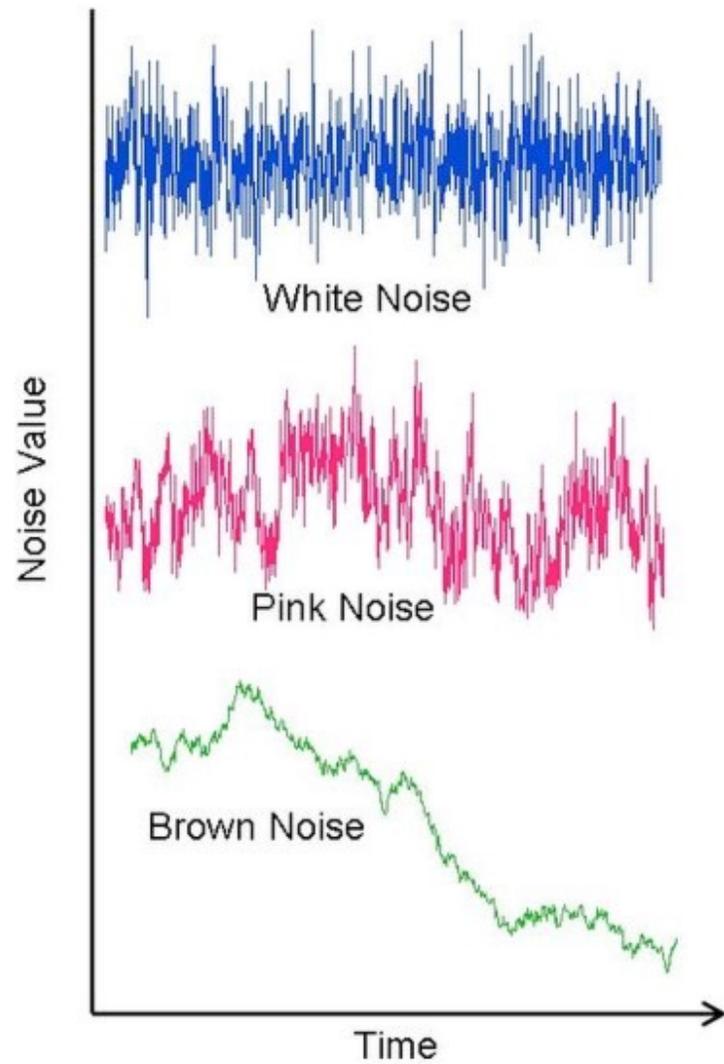
Waterfall



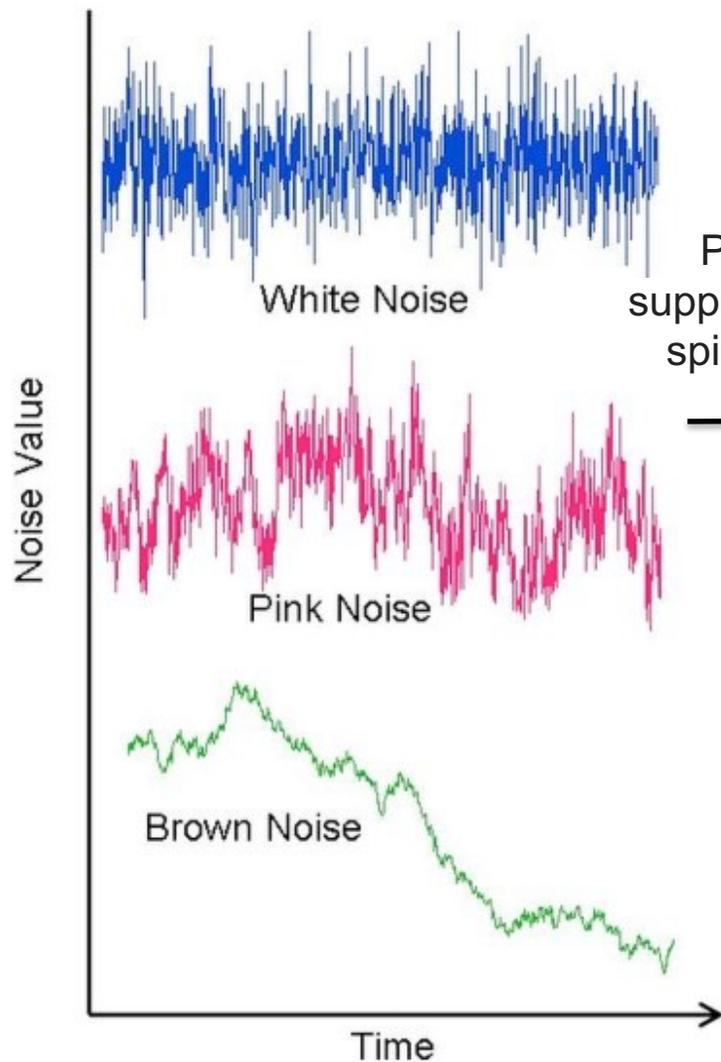
Heavy Rainfall



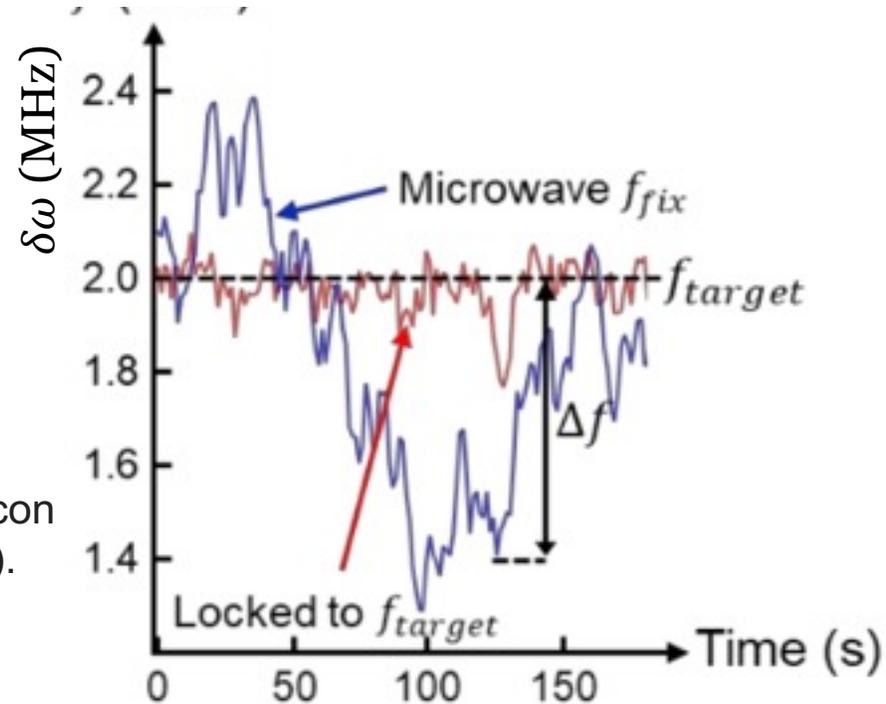
# We rely on the trajectory



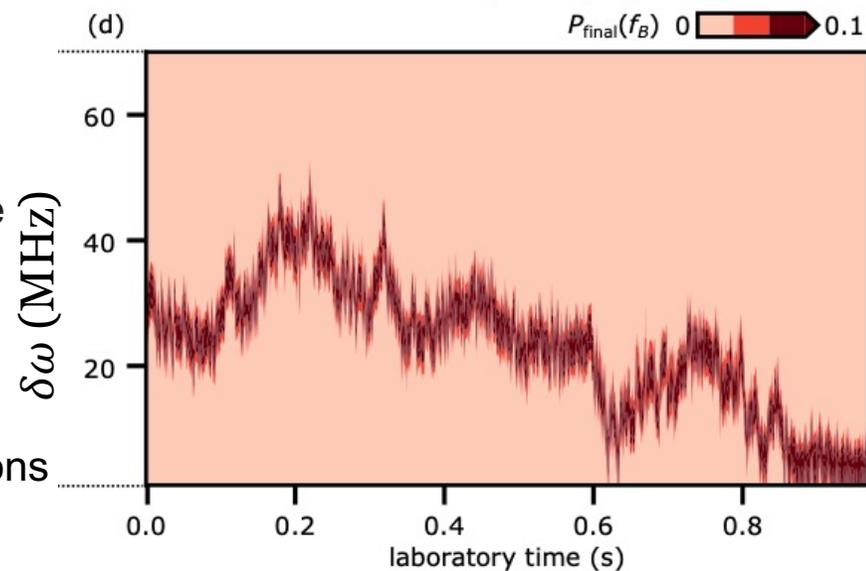
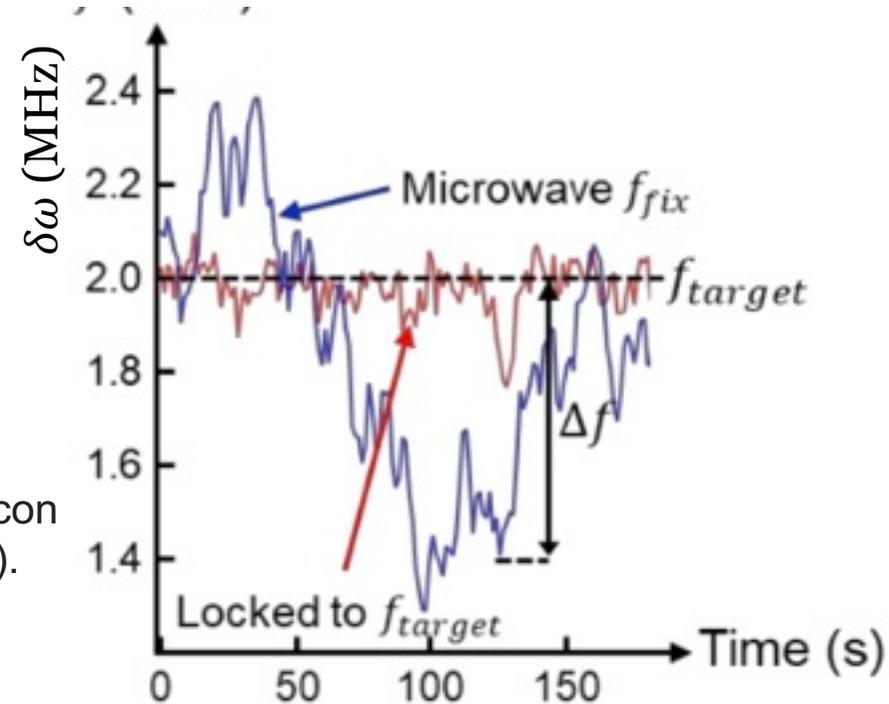
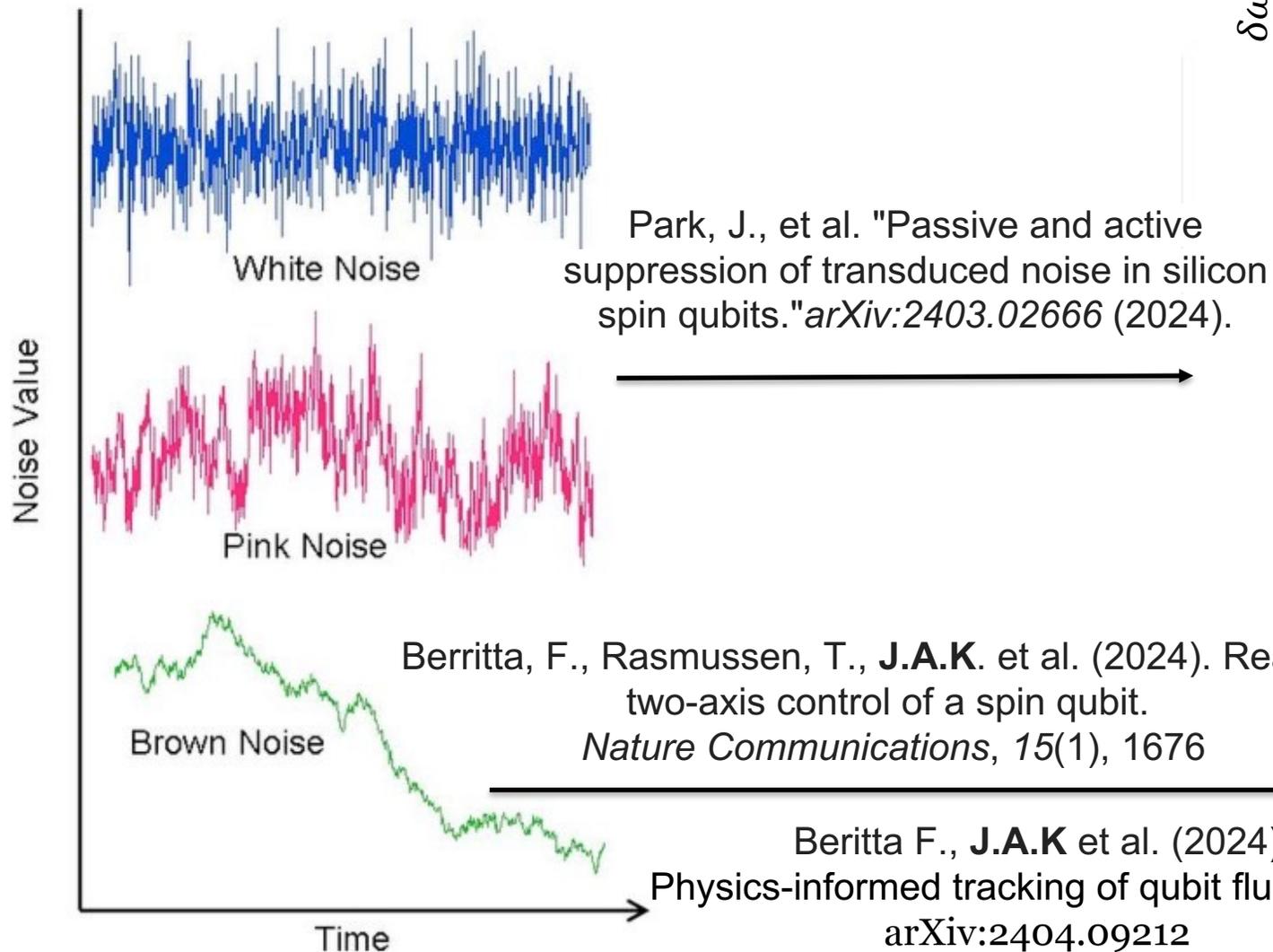
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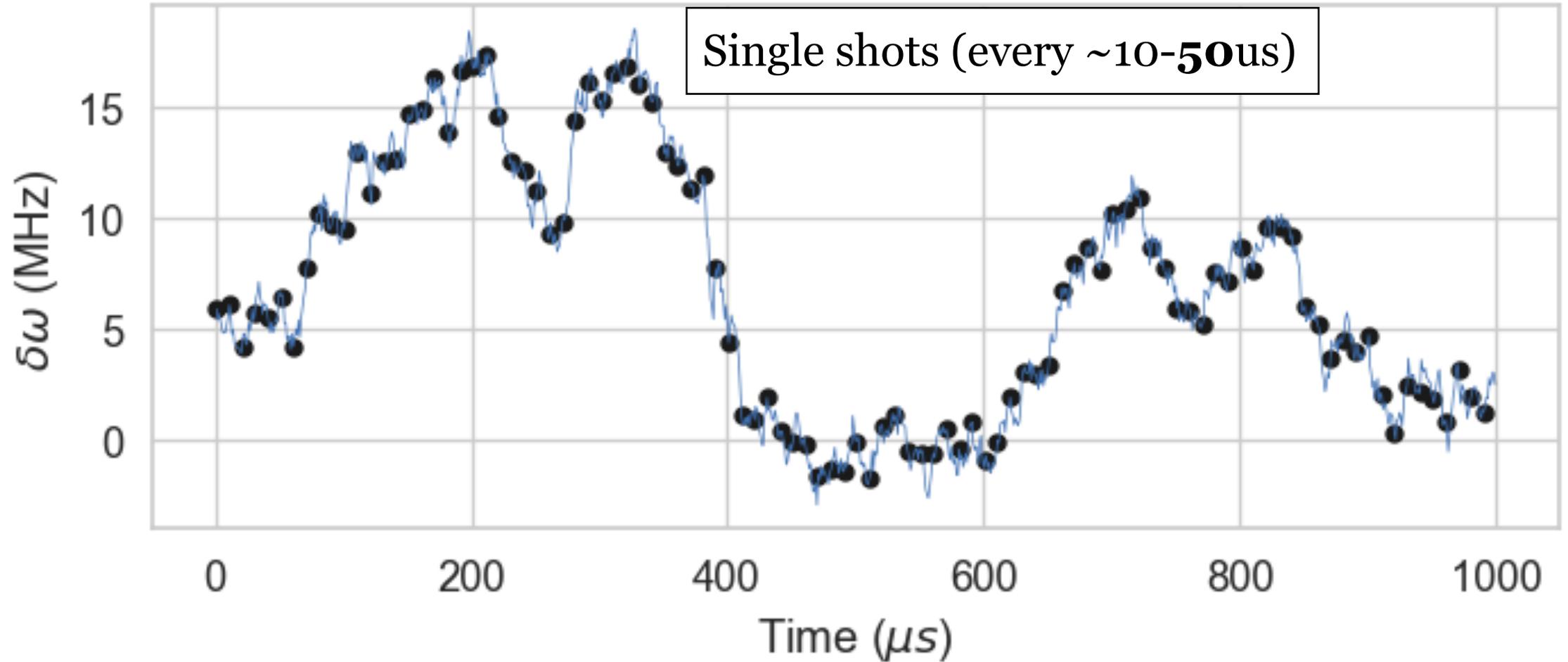
Park, J., et al. "Passive and active suppression of transduced noise in silicon spin qubits." *arXiv:2403.02666* (2024).



# We rely on the trajectory



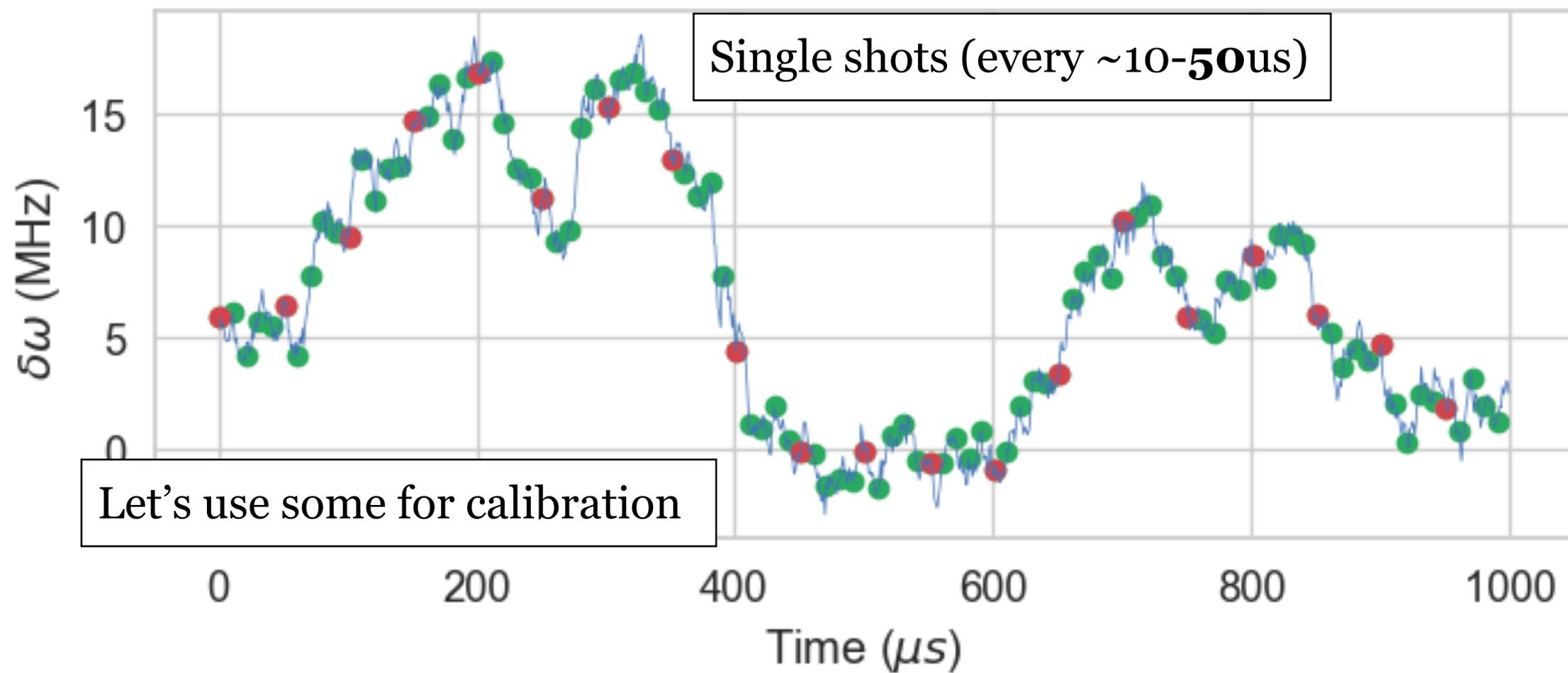
# Research strategy – there is plenty of time



Quasistatic approximation

$$H_n = [\omega + \delta\omega_n]S_z$$

... to correct for the noise.

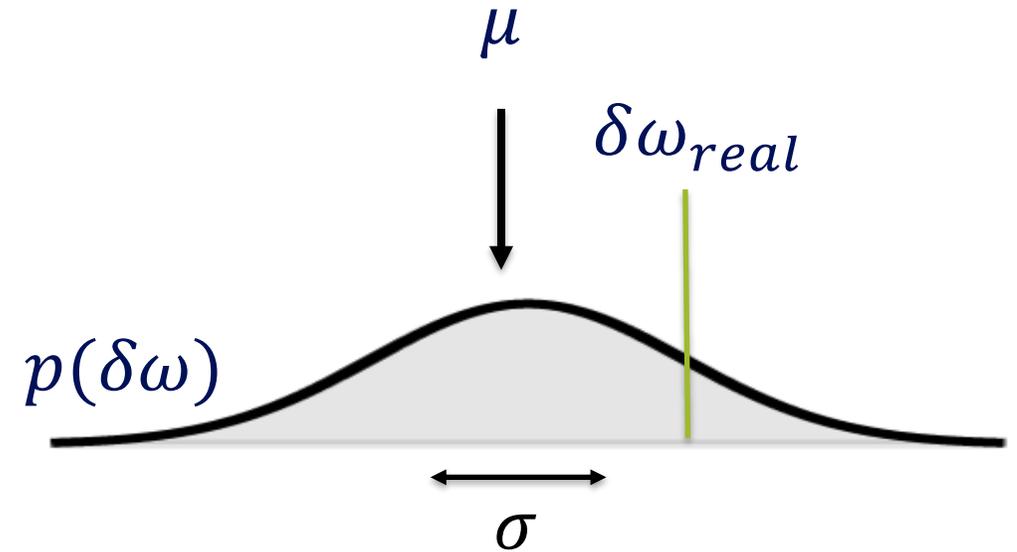
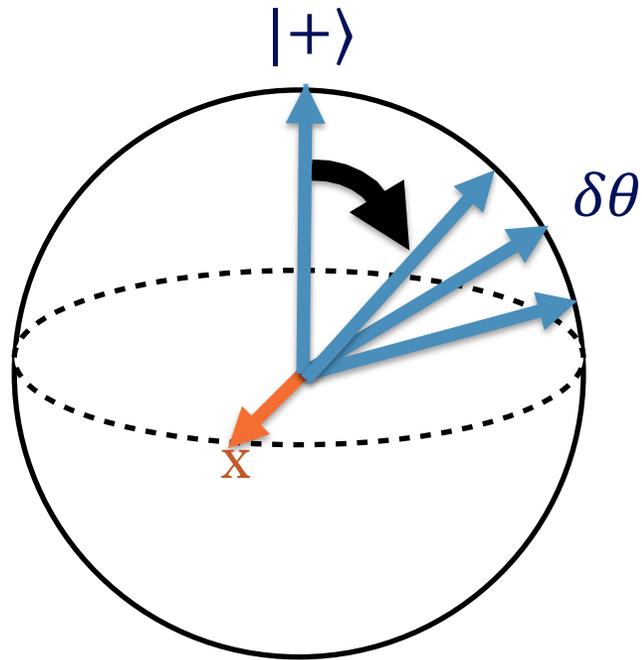


$$H_n = [\omega + \delta\omega_n]S_z$$



**Bayesian estimation (2 min)**

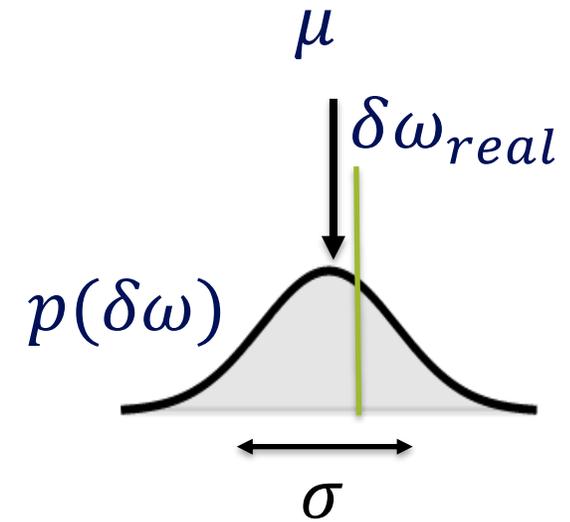
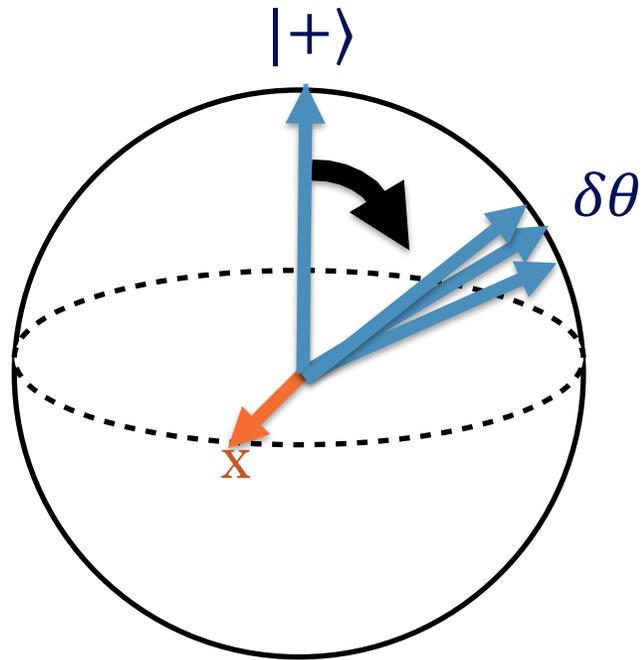
# Phase gate



Gate infidelity

$$1 - F \propto \langle \delta\theta^2 \rangle \propto \sigma^2 \theta^2 / \mu^2$$

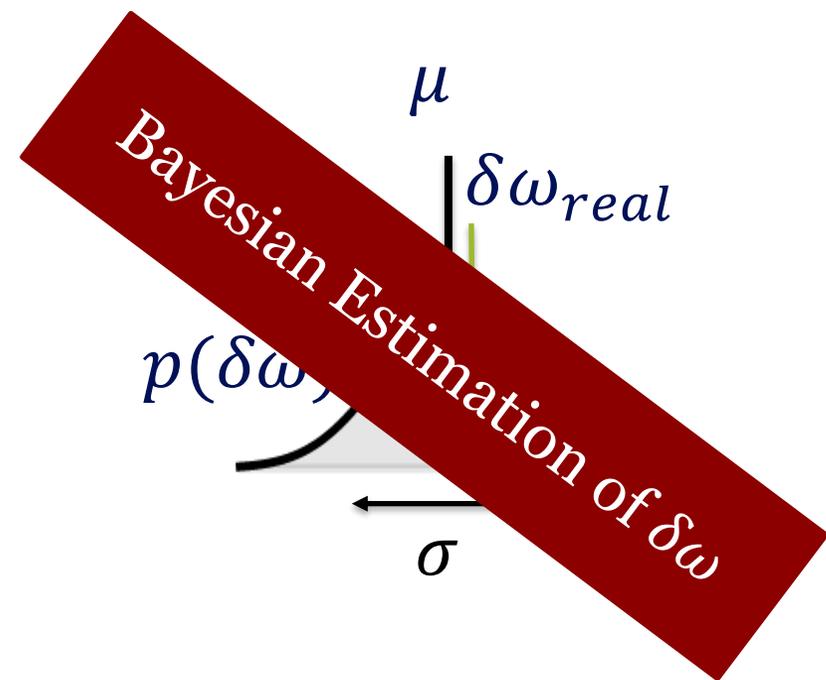
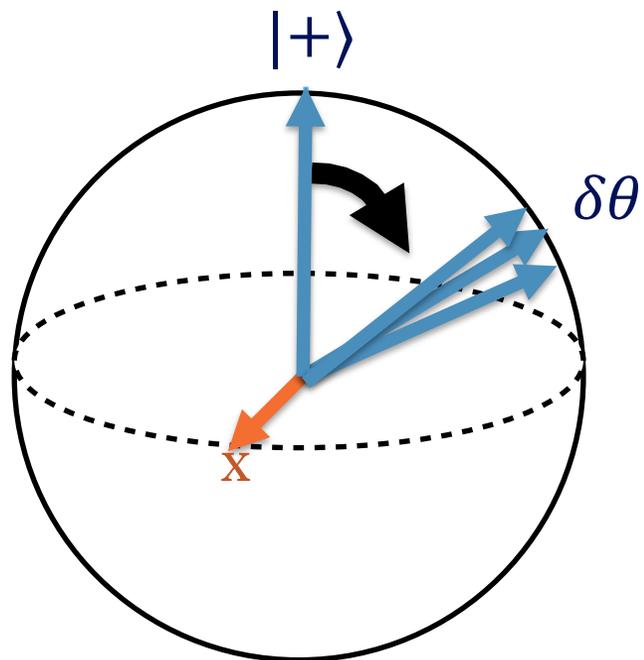
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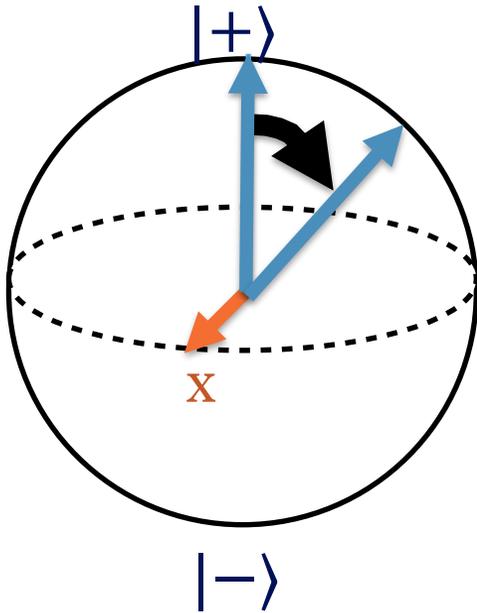
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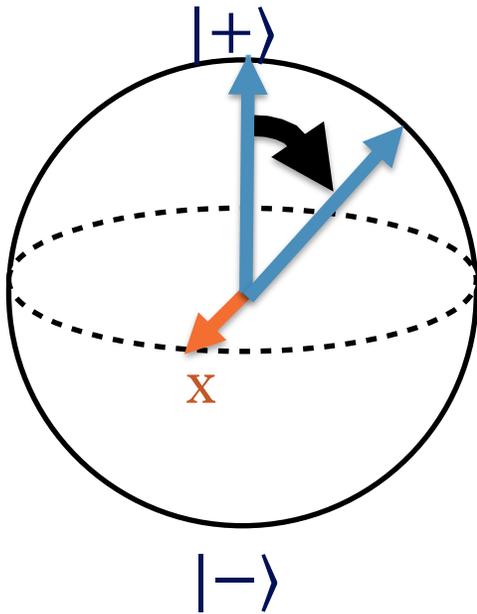
# Bayesian estimation



1. Find likelihood function

$$p(x|\delta\omega, \tau) \propto 1 + x \cos(\delta\omega \tau)$$

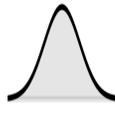
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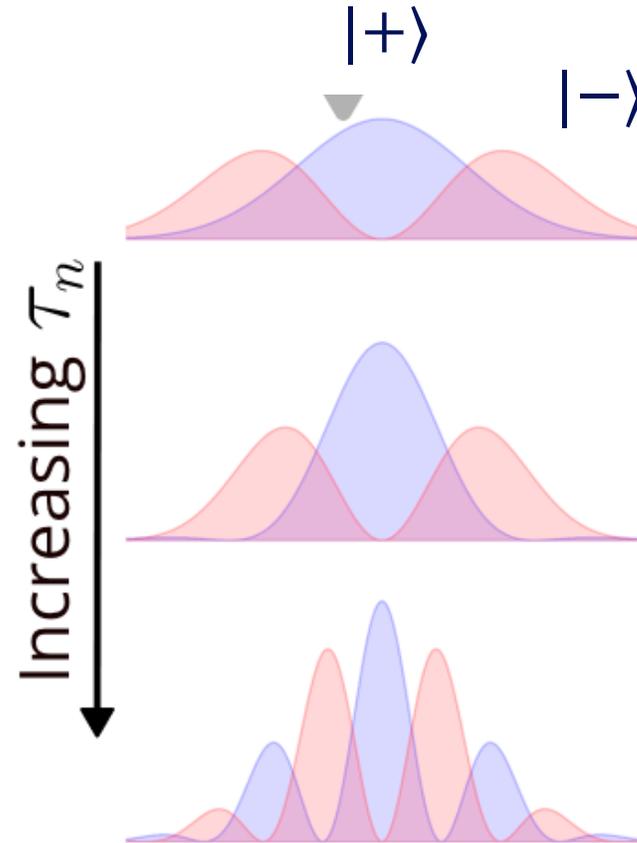
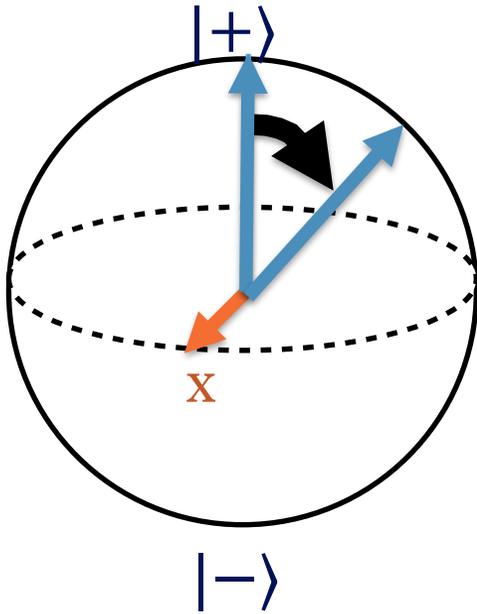
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2. Use Bayesian formula


$$p(\delta\omega|x_1, \tau) \propto p(x_1|\delta\omega, \tau)p_0(\delta\omega)$$


# Bayesian estimation



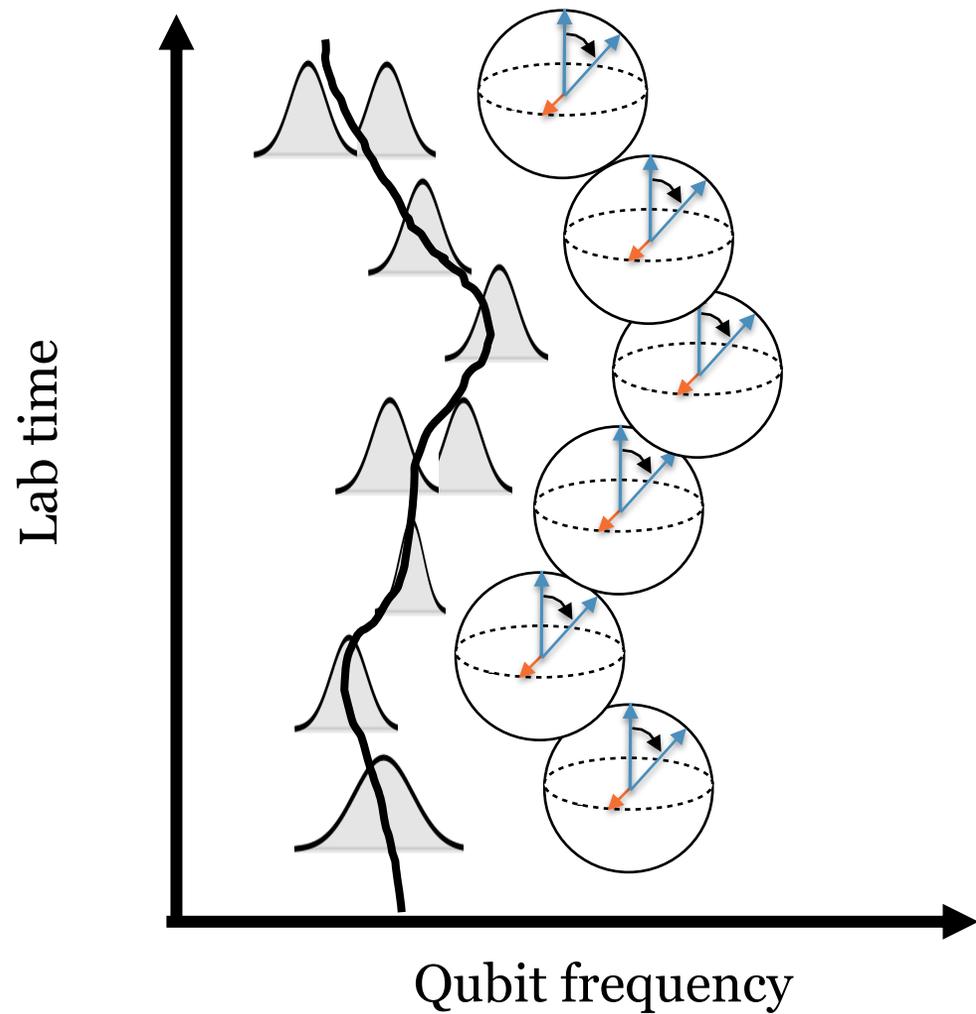
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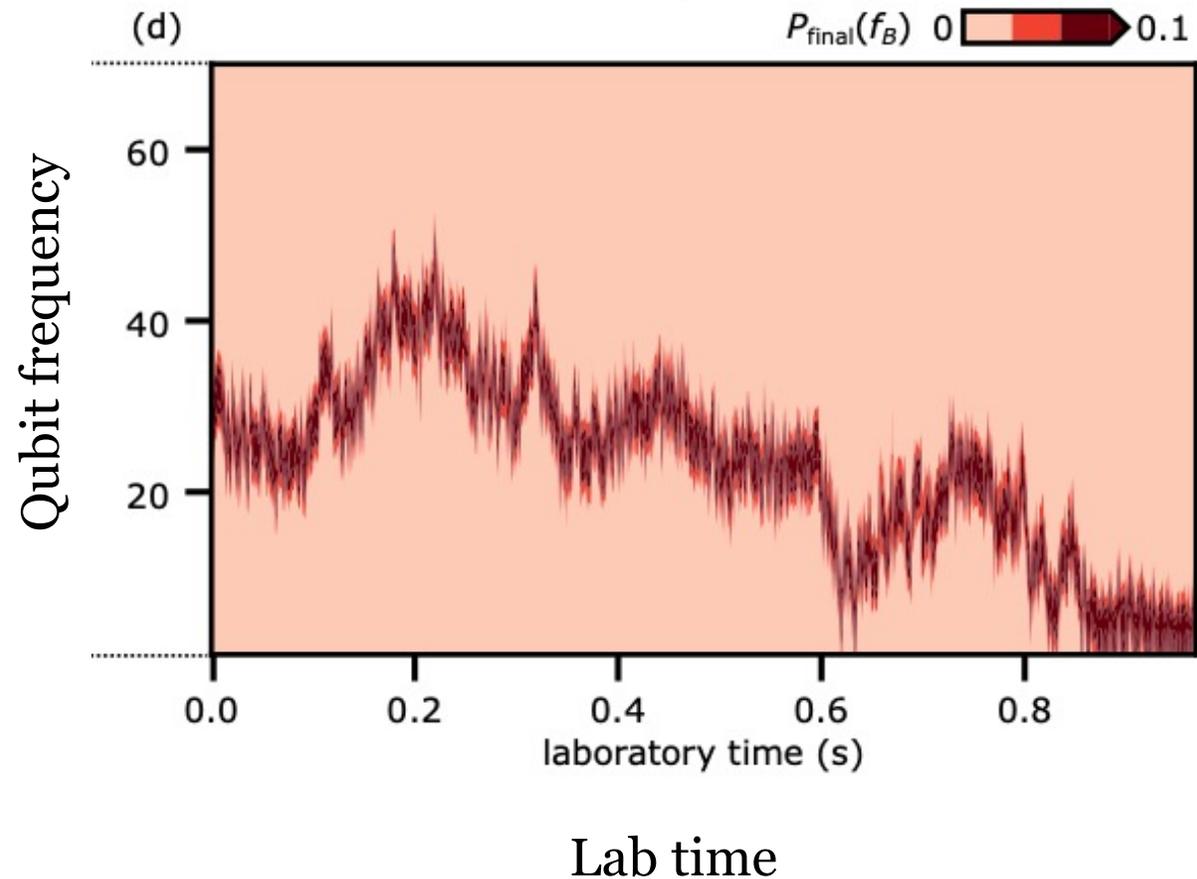
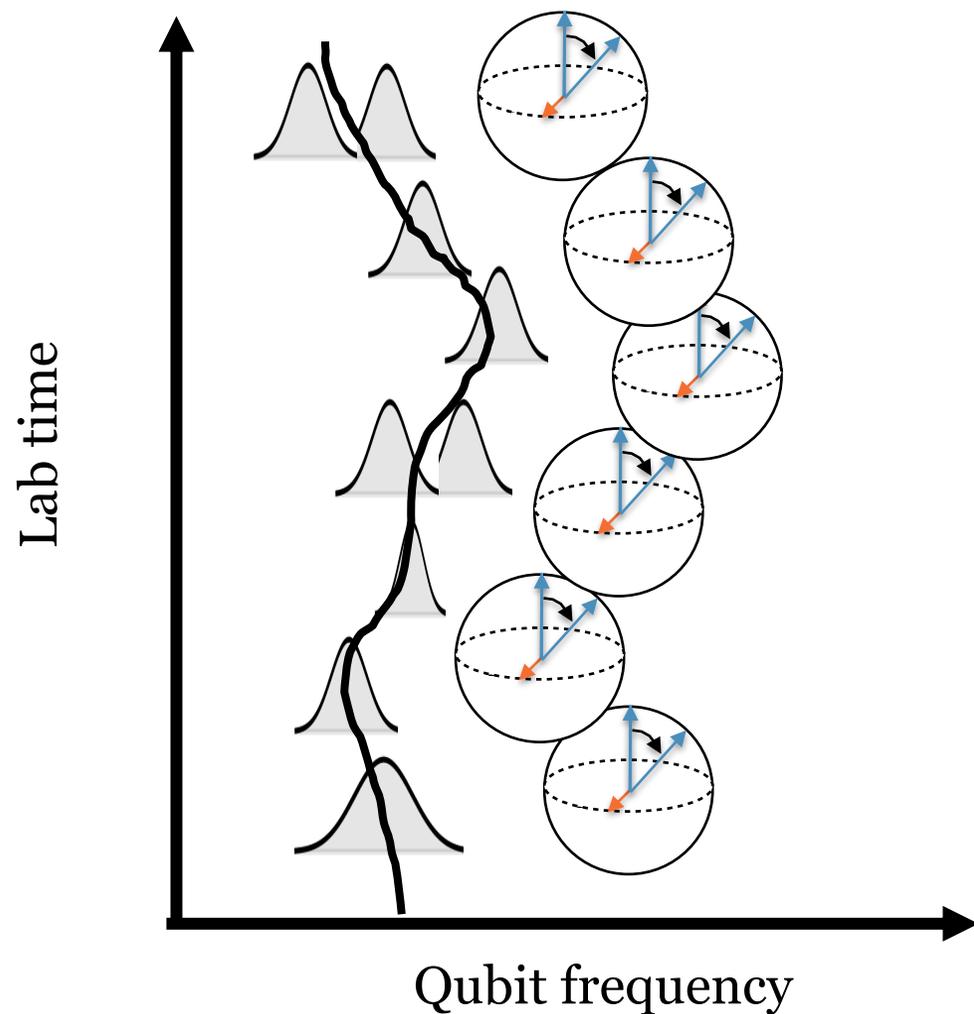
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# Bayesian tracking



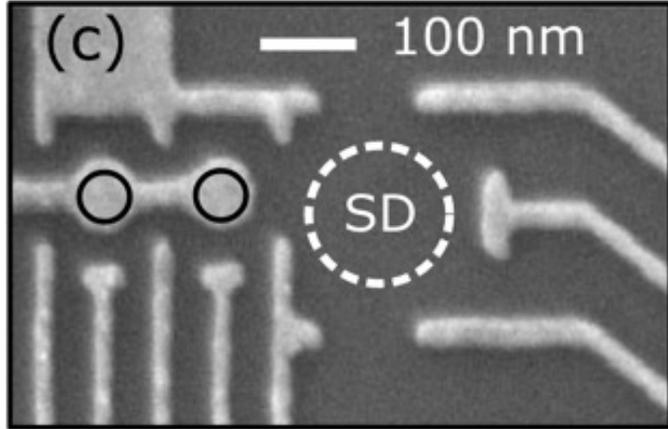
# Bayesian tracking



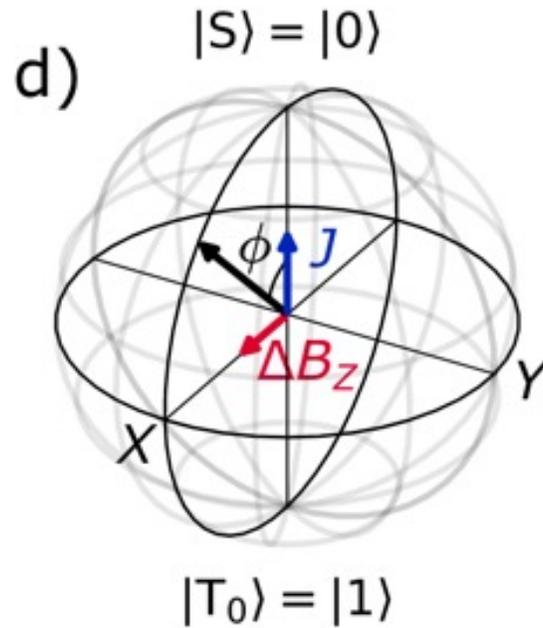


**Coherent rotation around noise - experiment (3 min)**

# Experiment



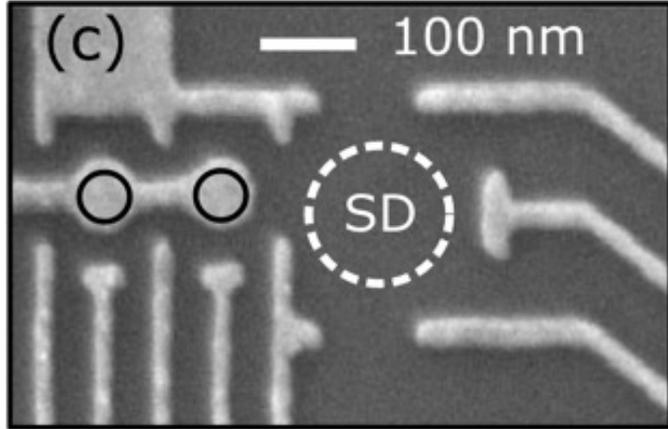
GaAs spin qubit



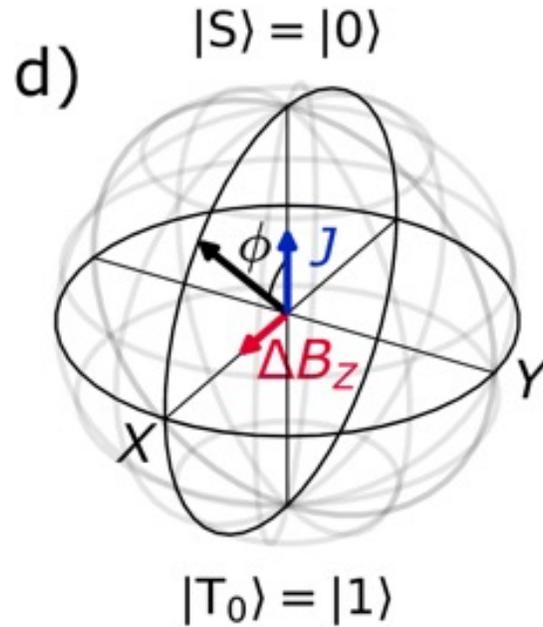
S-T subspace

$$H(\epsilon) = \delta\omega(t)S_x + J(\epsilon)S_z$$

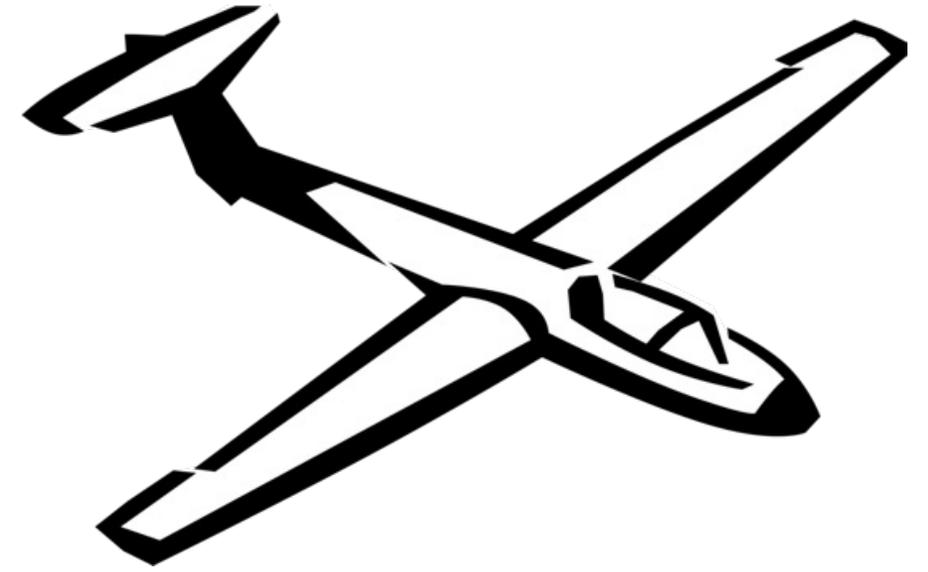
# Experiment



GaAs spin qubit

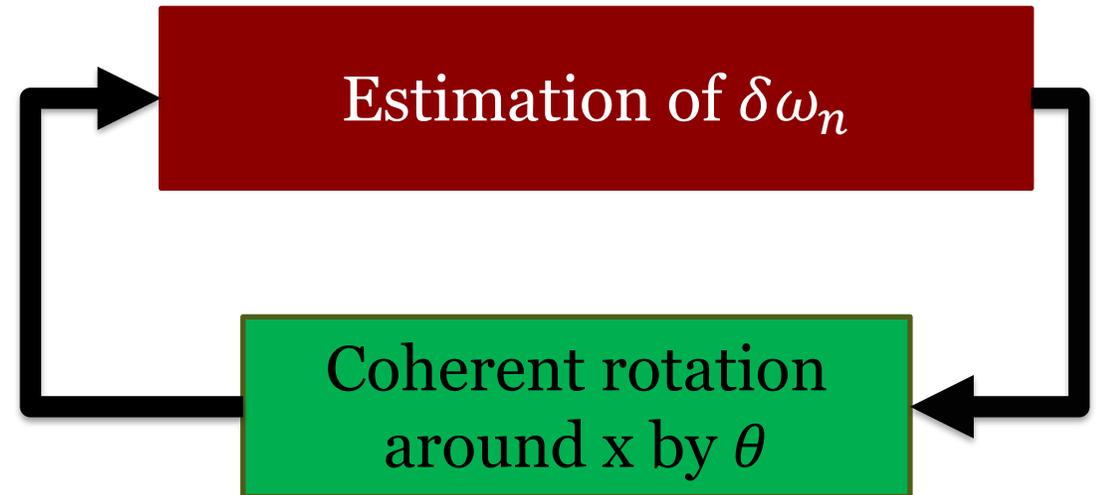


S-T subspace



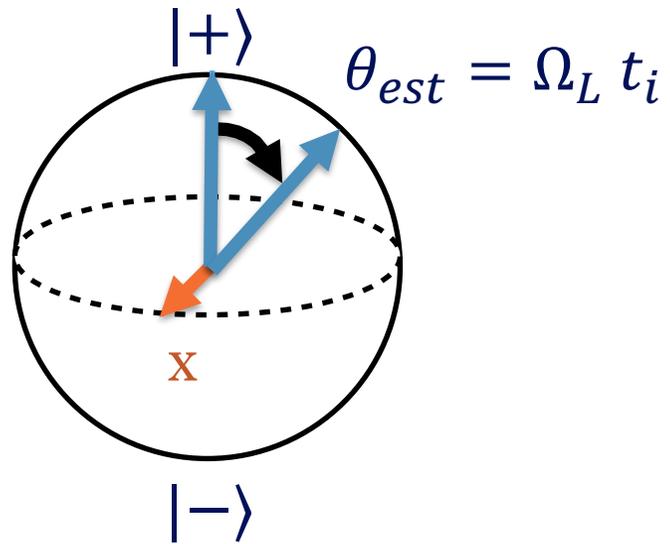
$$H(\epsilon_{11}) = \delta\omega(t)S_x$$

Zero-average



# Experiment

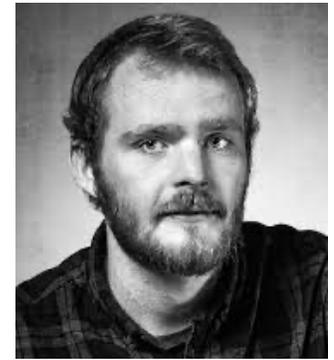
$$H(\epsilon) = \Omega_L S_x$$



Center for Quantum Devices  
Niels Bohr Institute



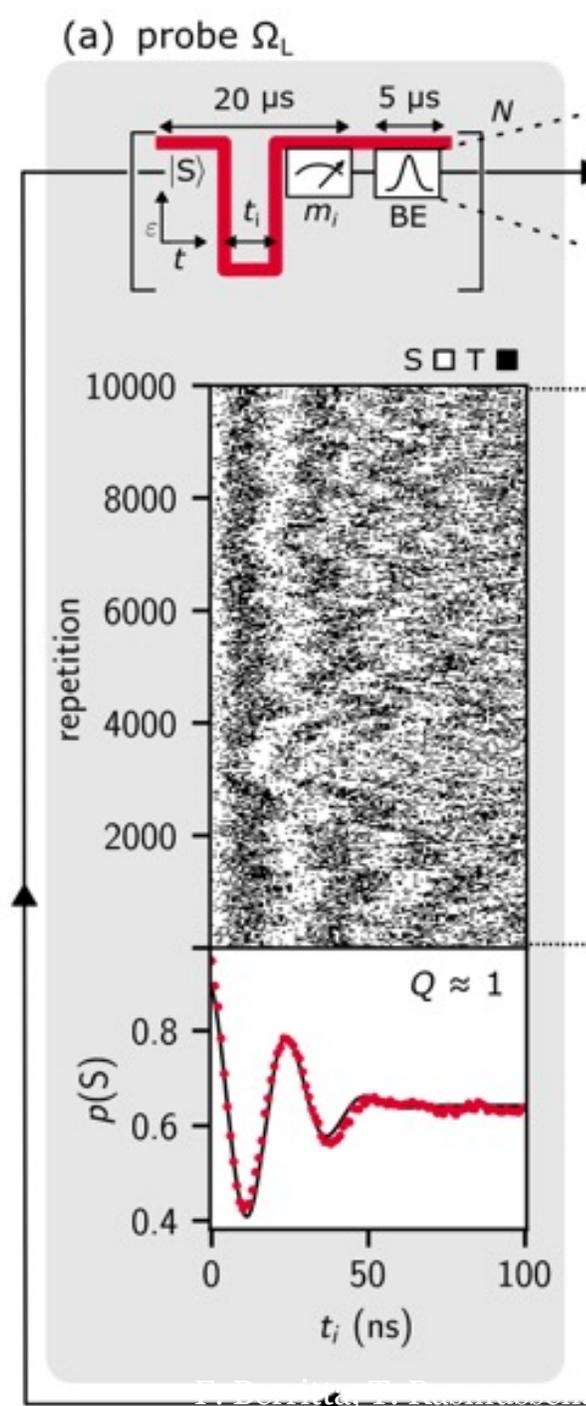
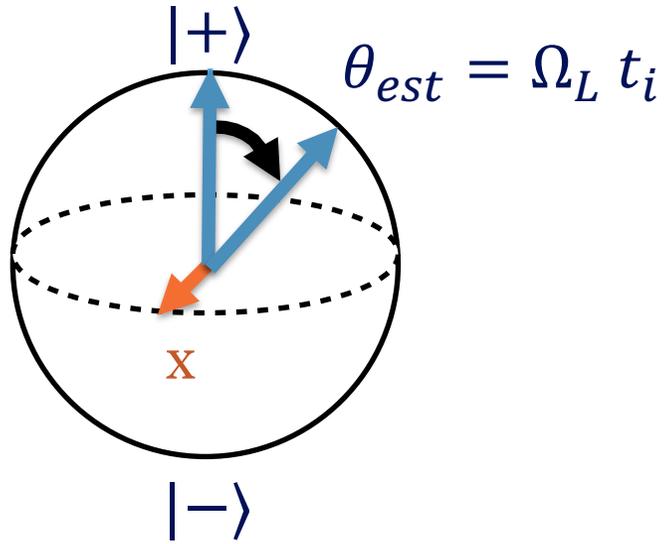
Fabrizio Berritta  
**TALK PAS 2.4**  
(yesterday)



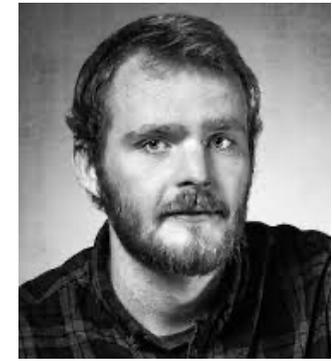
Torbjørn Raasø  
Rasmussen

# Experiment

$$H(\epsilon) = \Omega_L S_x$$



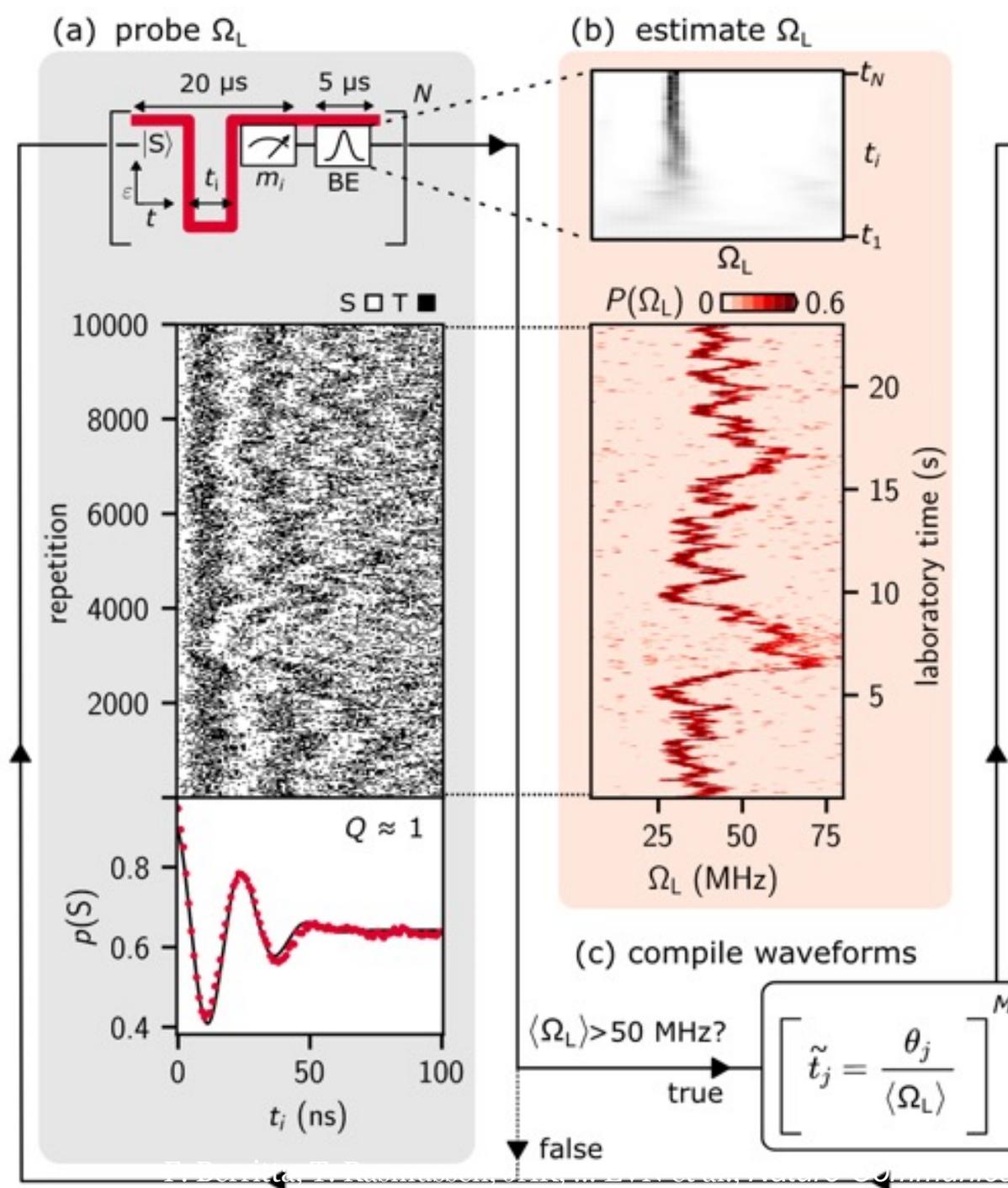
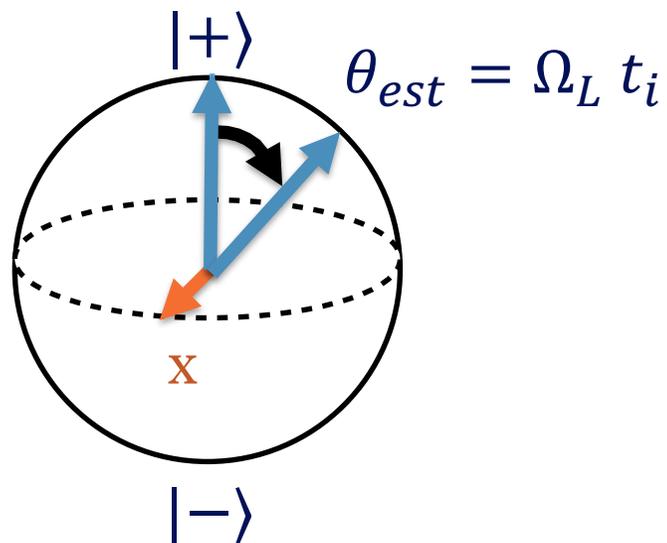
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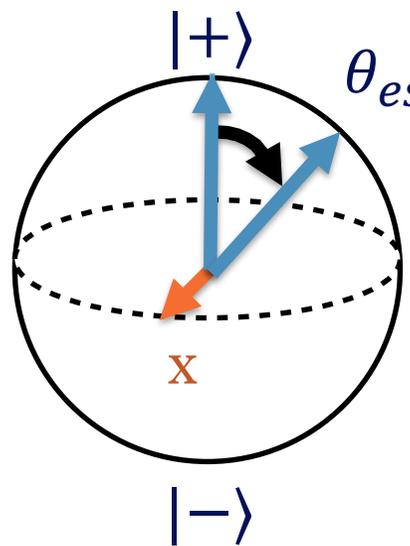
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$$H(\epsilon) = \Omega_L S_x$$

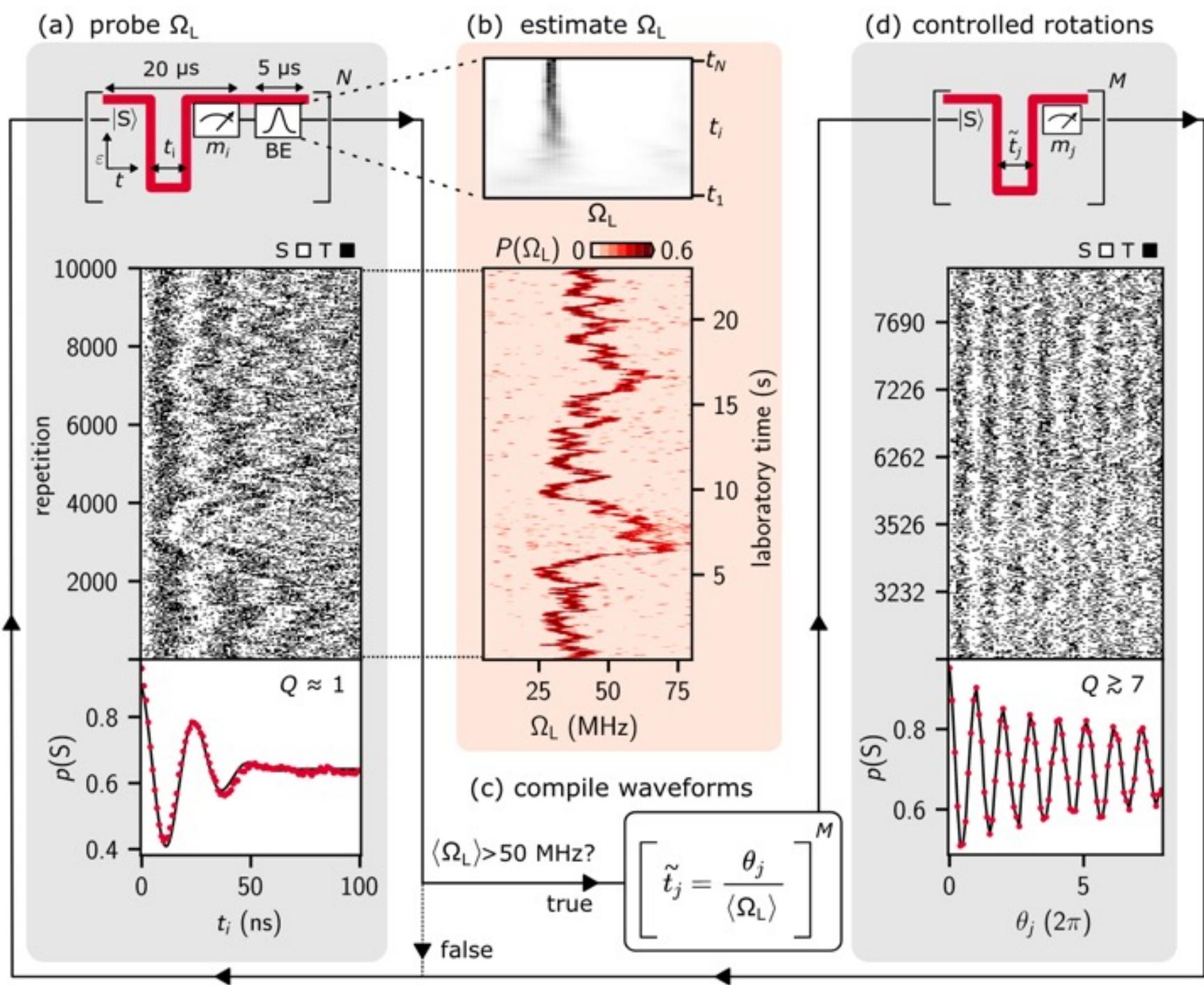


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$$H(\epsilon) = \Omega_L S_x$$

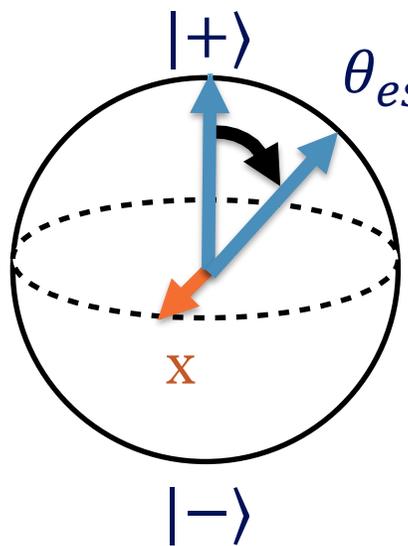


$$\theta_{est} = \Omega_L t_i$$



# Experiment

$$H(\epsilon) = \Omega_L S_x$$

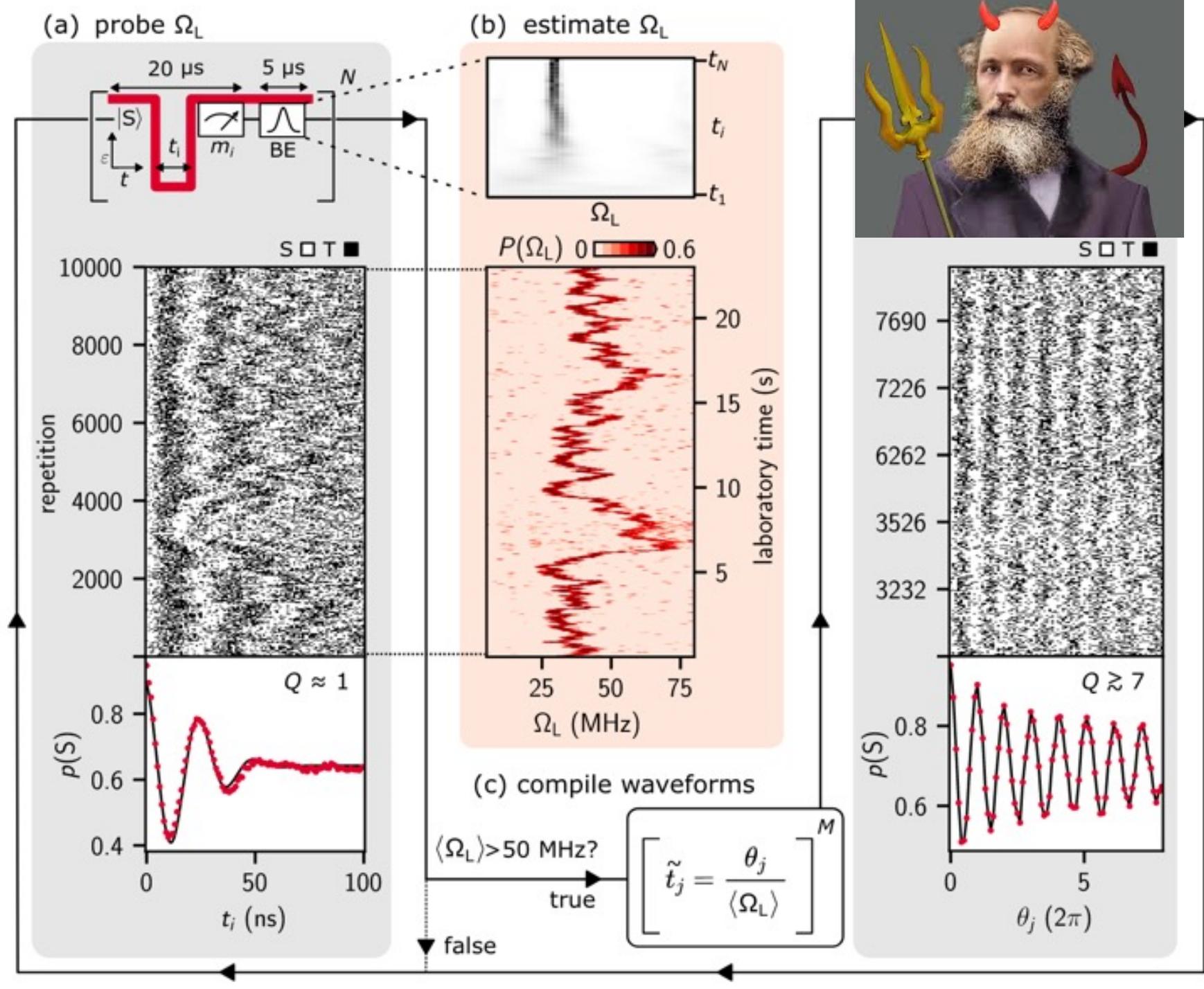


If  $\Omega_L > 50$  MHz

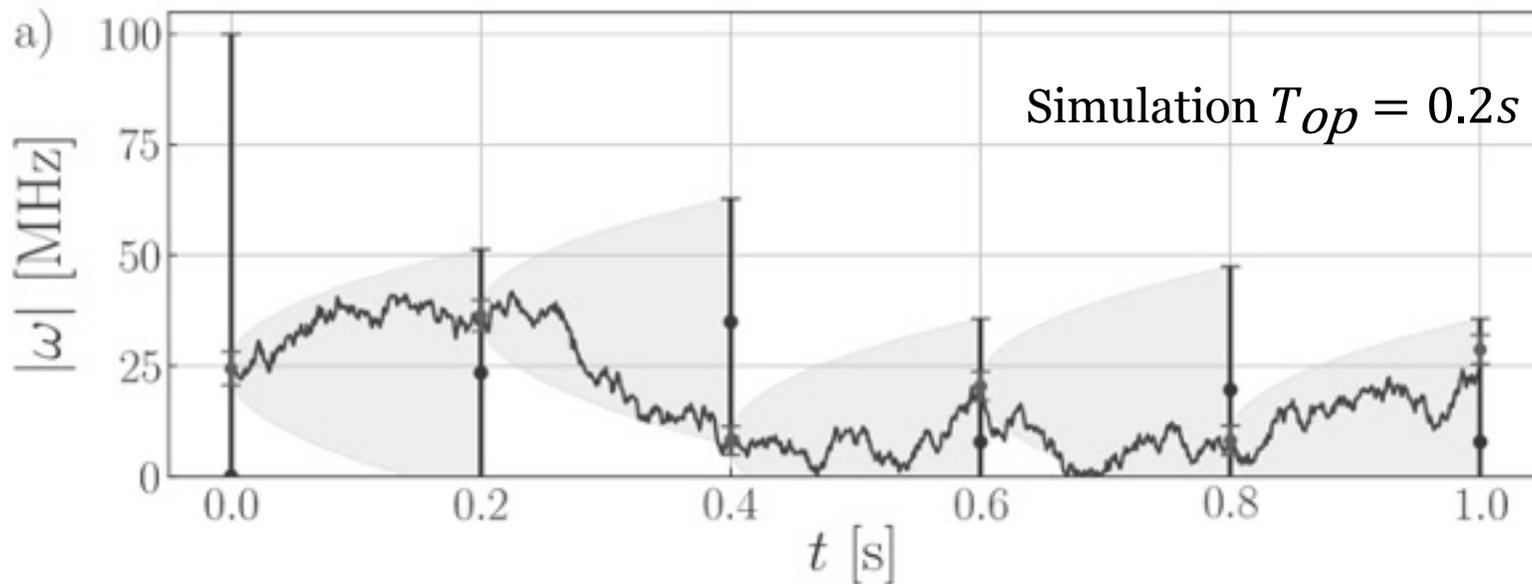
Rotate by  $\theta$ , using time

$$\tau = \frac{\theta}{\widehat{\Omega}_L}$$

$\langle aQa^\dagger \rangle$



# Our progress



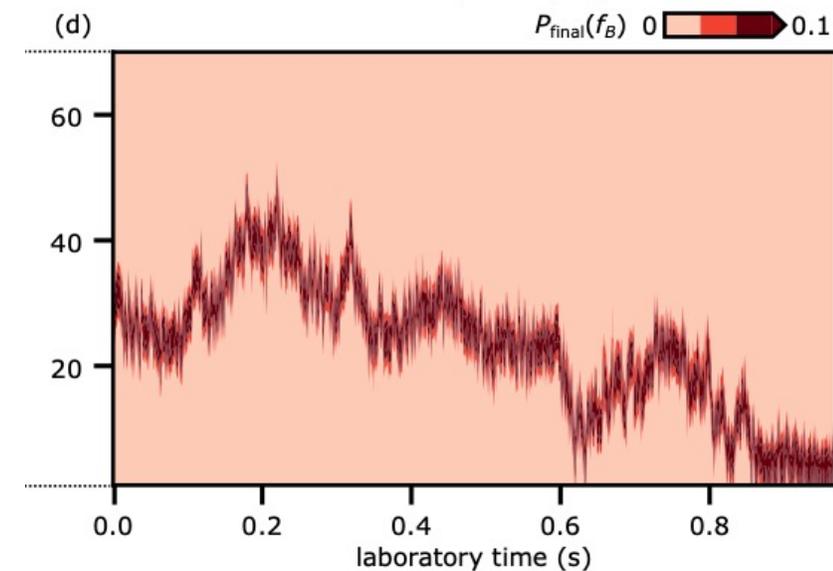
Fabrizio Berritta



Jacob Benestad

1. Physics-informed estimation  
**(No outliers)**

$$P(\delta\omega' t | \delta\omega, 0)$$



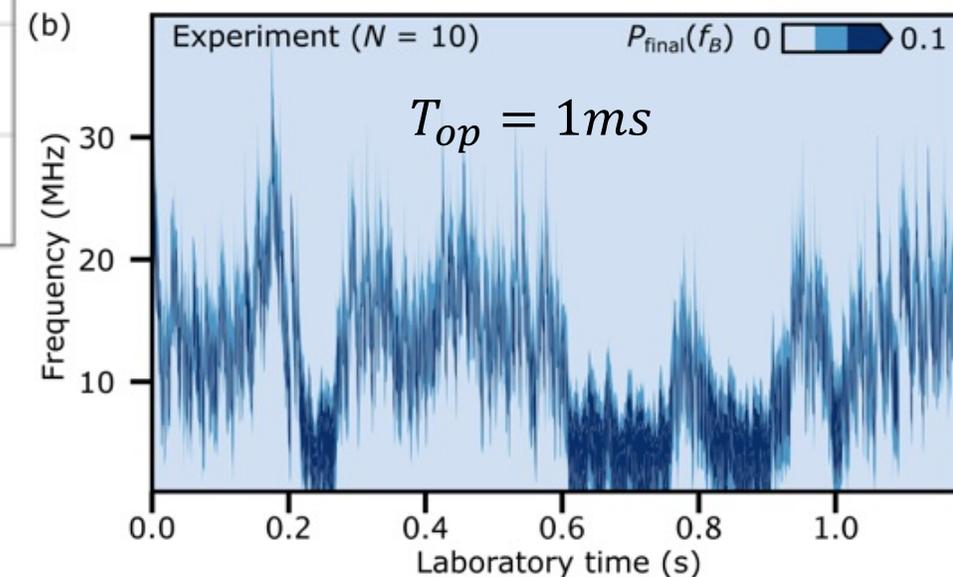
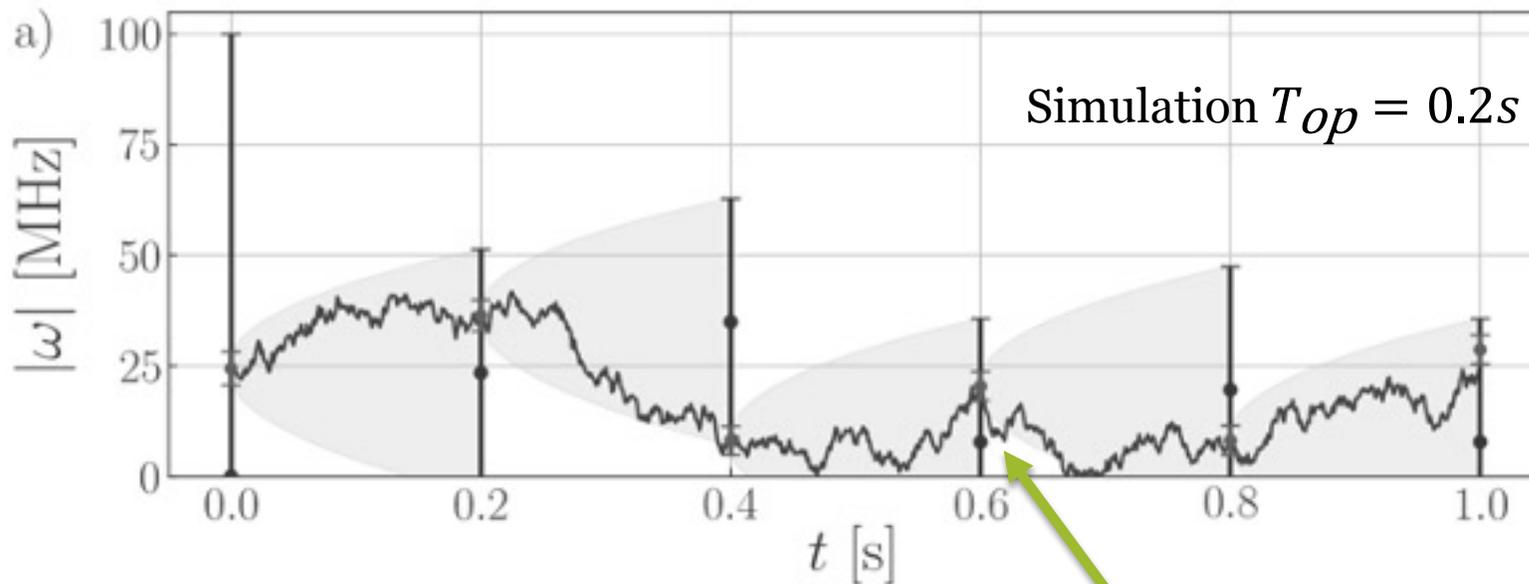
# Our progress



Fabrizio Berritta



Jacob Benestad



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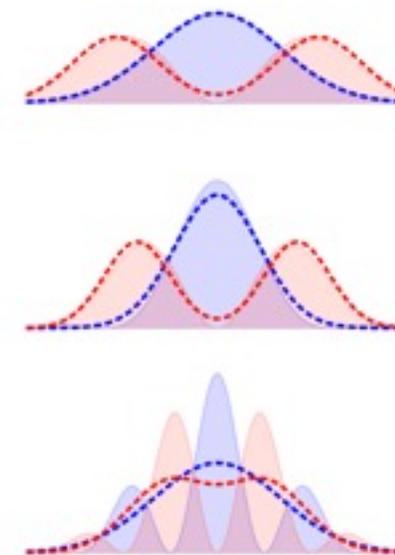
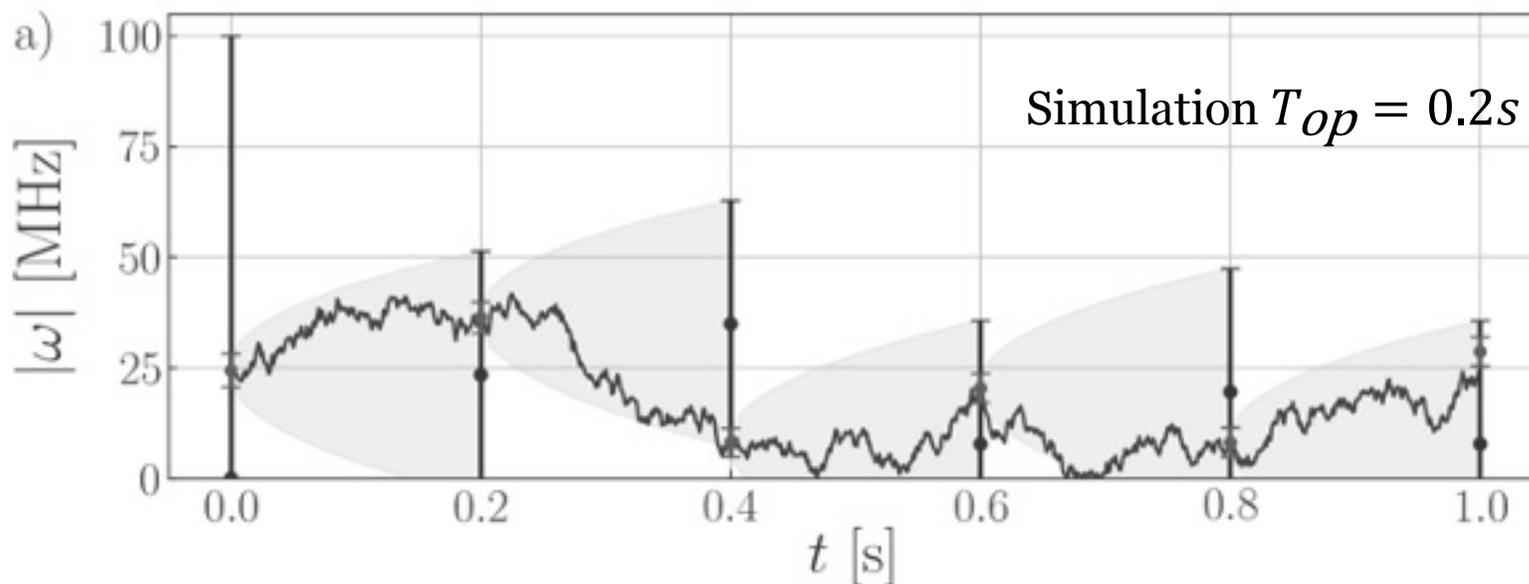
2. Adaptive time  
**(Few shots)**

$$\tau_n = \frac{c}{\sigma_{n-1}}$$

# Our progress



Jacob Benestad



Gaussian fit

1. Physics-informed estimation  
**(No outliers)**

$$P(\delta\omega' t | \delta\omega, 0)$$

2. Adaptive time  
**(Few shots)**

$$t_n = \frac{c}{\sigma_{n-1}}$$

3. Method of moments  
**(Low memory)**

$$\mu_{n+1} = f(\mu_n, \sigma_n)$$

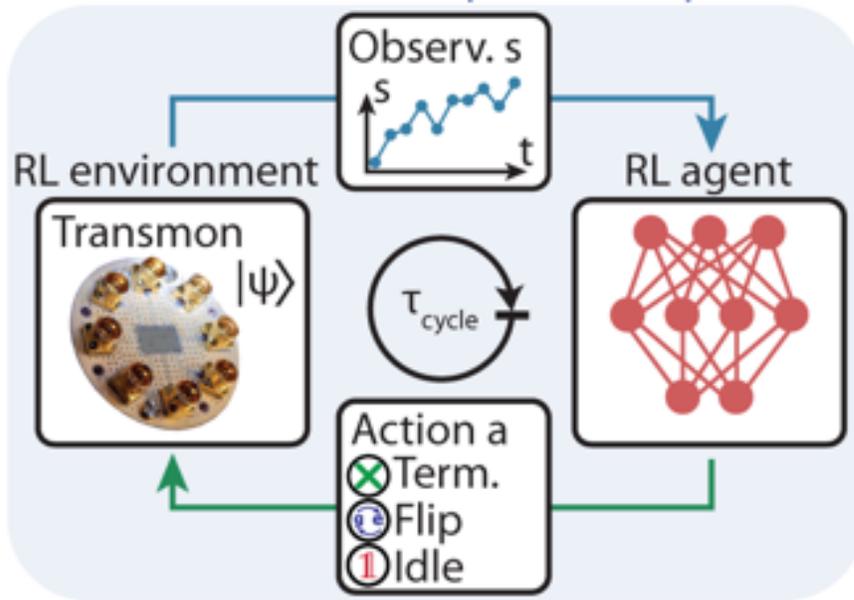
$$\sigma_{n+1} = g(\mu_n, \sigma_n)$$



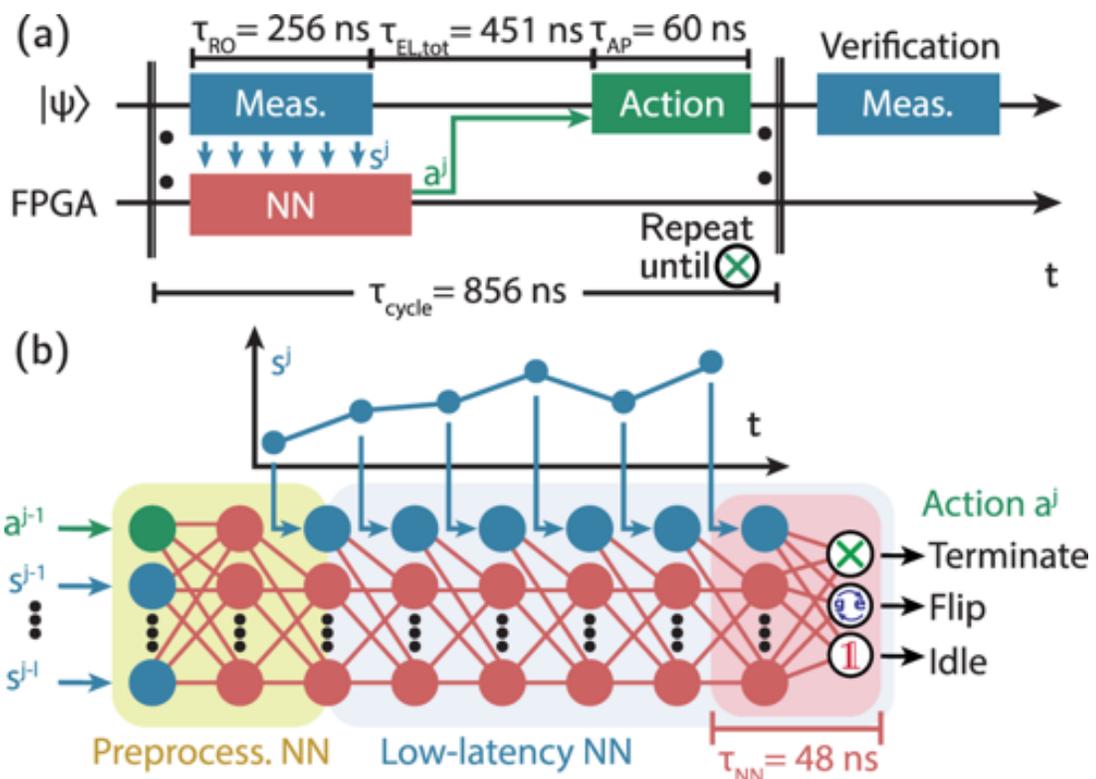
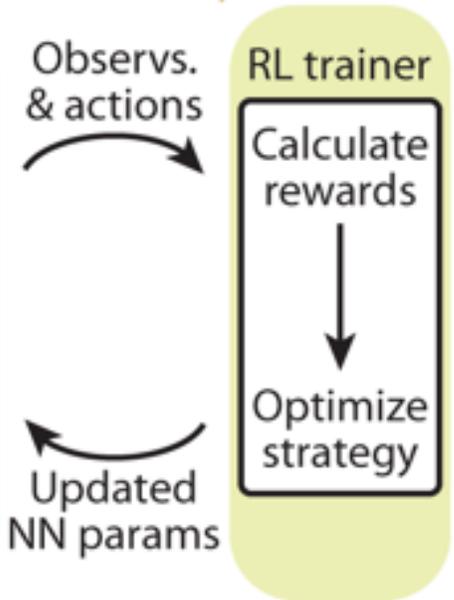
The game and its heuristics (2 min)

# Reinforcement learning on the FPGA

Real-time feedback in quantum experiment



Update on PC



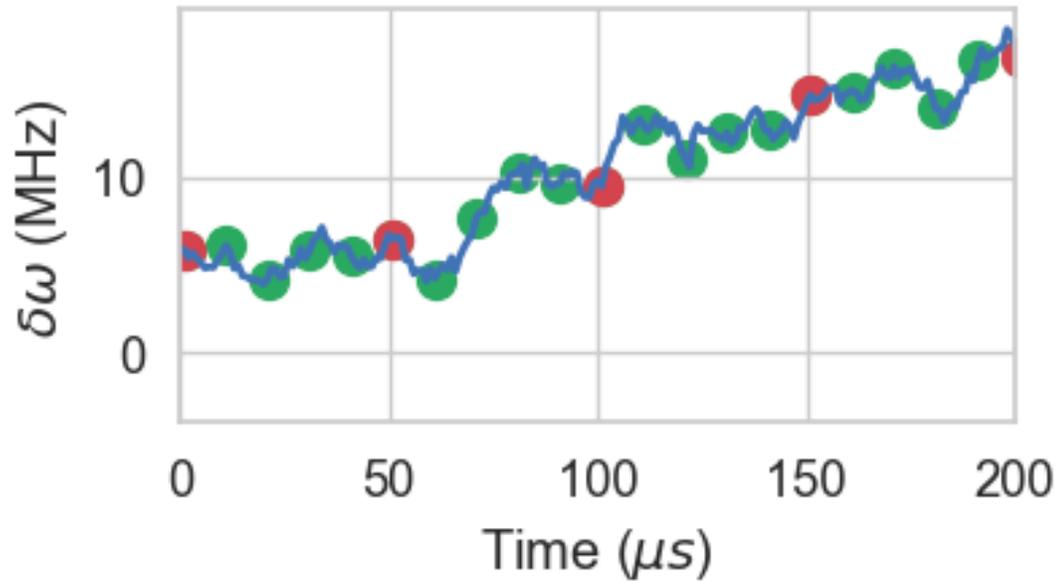
1. Hybrid optimisation method

2. Improved initialisation

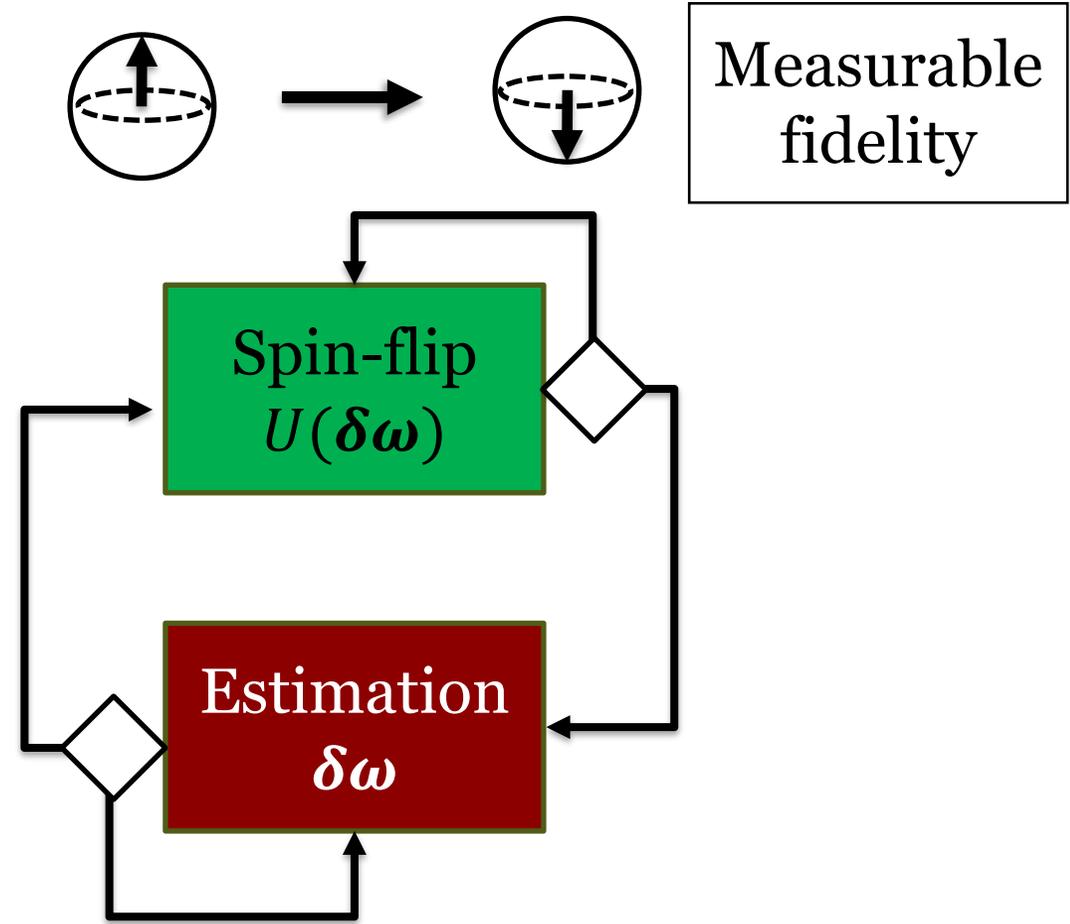
3. Markovian approach

Reuer, Kevin, et al. "Realizing a deep reinforcement learning agent for real-time quantum feedback." *Nature Communications* 14.1 (2023): 7138.

# The game



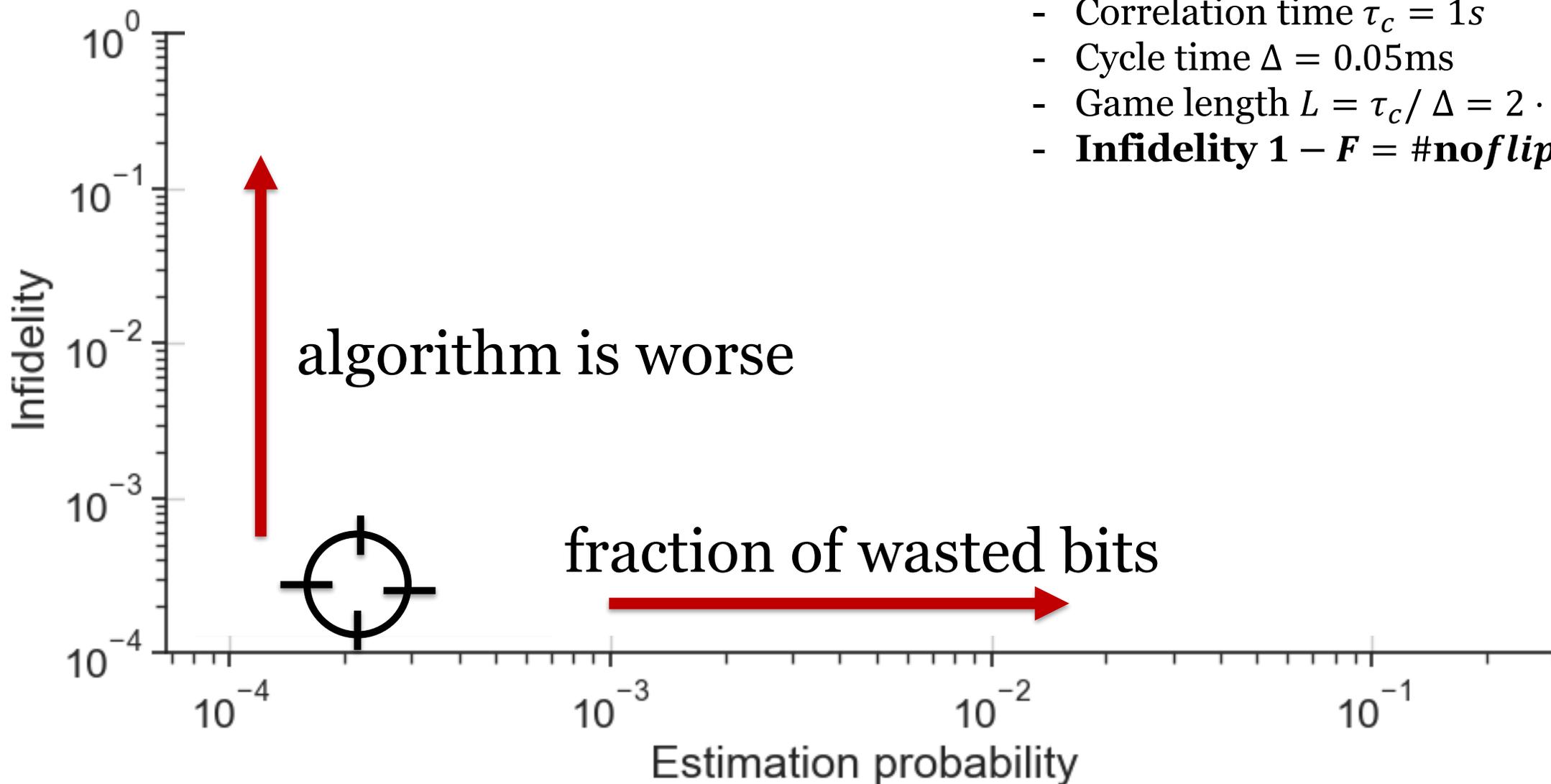
1. Resource allocation



2. Actions

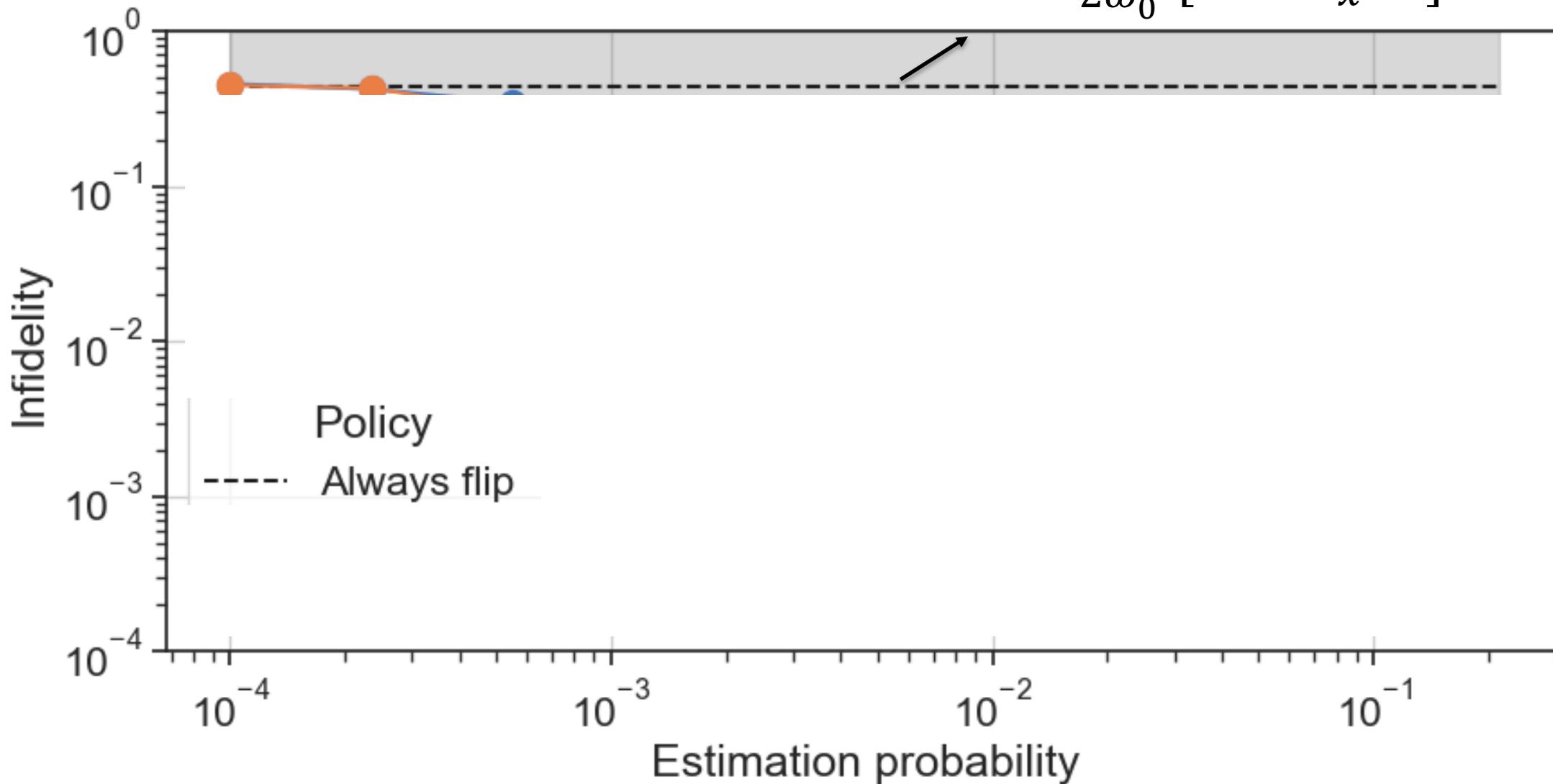
# Heuristics to beat

- Noise amplitude 2MHz
- Target frequency 10MHz
- Initial error 0.5MHz
- Correlation time  $\tau_c = 1s$
- Cycle time  $\Delta = 0.05ms$
- Game length  $L = \tau_c / \Delta = 2 \cdot 10^4$
- **Infidelity  $1 - F = \#noflip / \#x$**

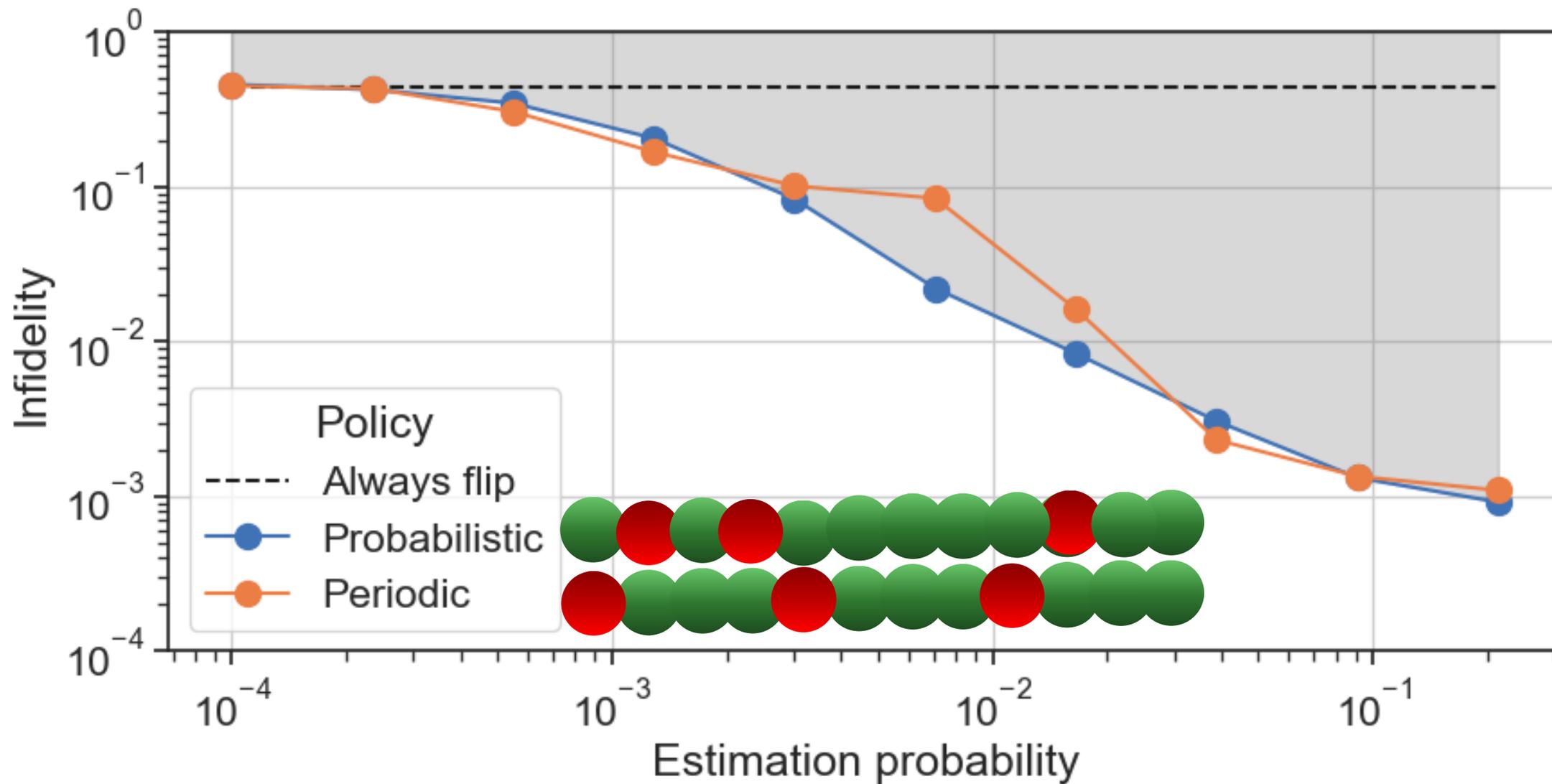


# Heuristics to beat

$$\langle P(0) \rangle_{\delta\omega} \approx \frac{A^2 \pi^2}{2\omega_0^2} \left[ 1 - \frac{1 - e^{-x}}{x} \right] \quad x = \frac{N\Delta t}{\tau_c} = 1$$



# Heuristics to beat

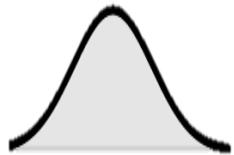




**Bringing the agent – Reinforcement learning (PPO) (5min)**

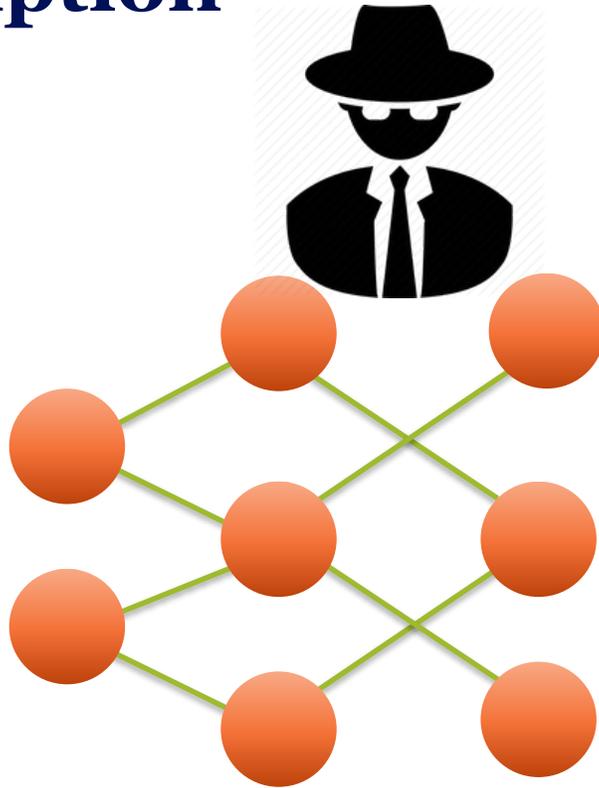
# The agent description

$$H(t) = \delta\omega S_x$$



$\mu_n$

$\sigma_n$

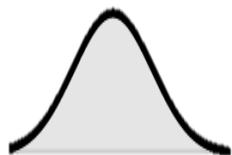


## 1. Observations

$\mu_n, \sigma_n$

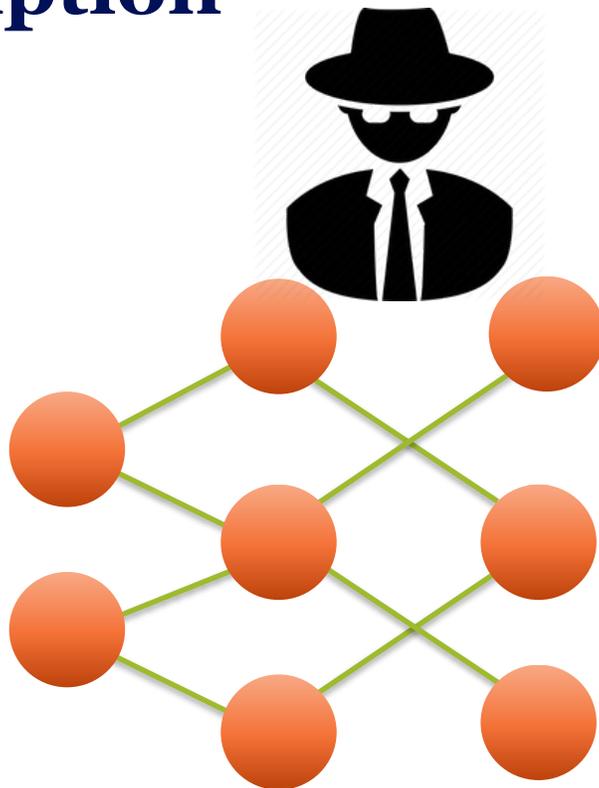
# The agent description

$$H(t) = \delta\omega S_x$$



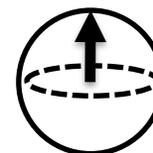
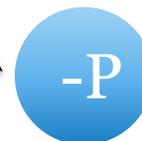
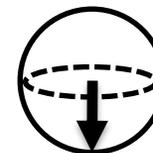
$\mu_n$

$\sigma_n$



$$\tau = \pi / \mu_n$$

Reward



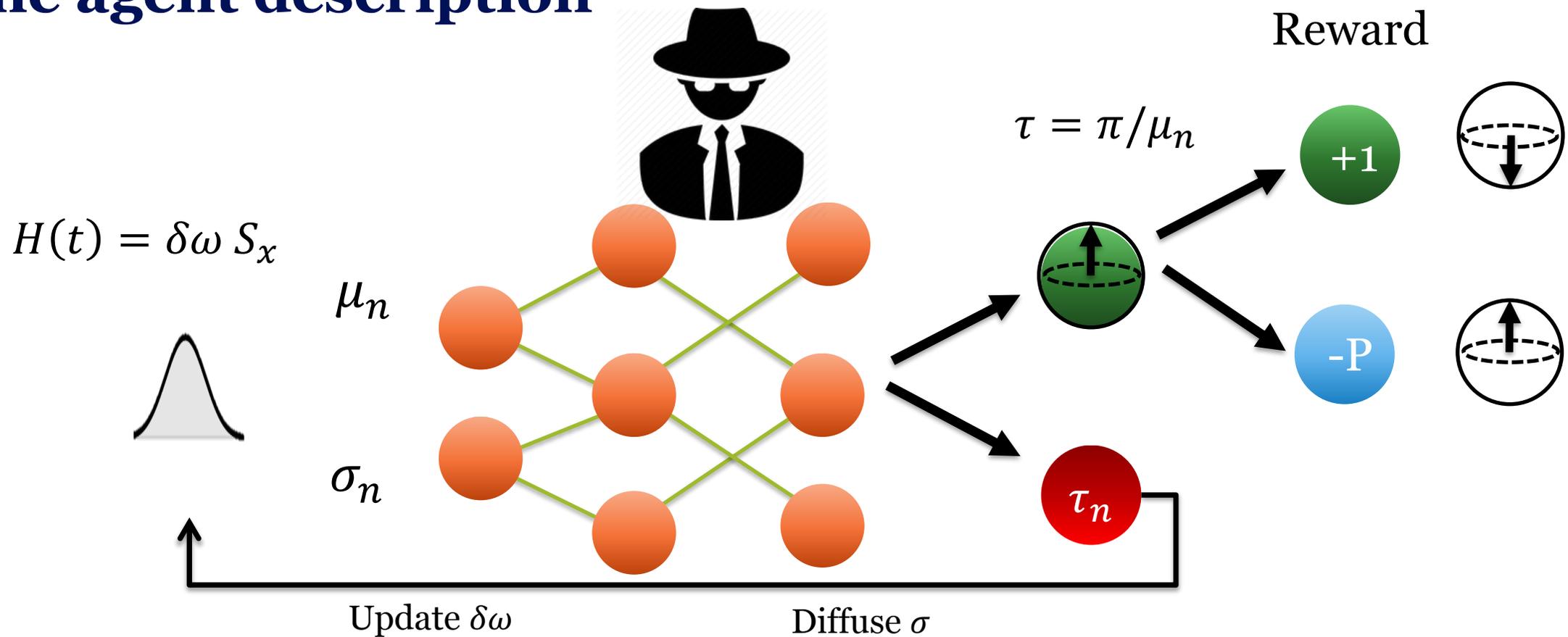
1. Observations

2. Actions

$\mu_n, \sigma_n$

 Run algorithm  Estimate

# The agent description



1. Observations

2. Actions

3. Bayesian update

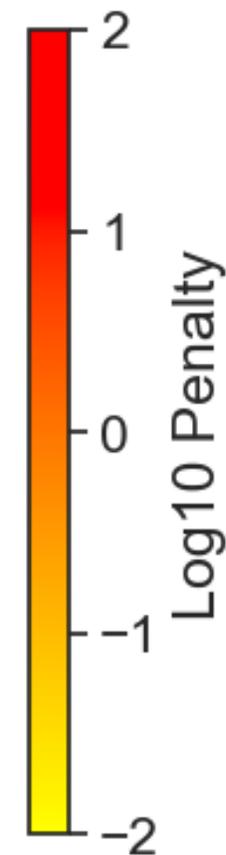
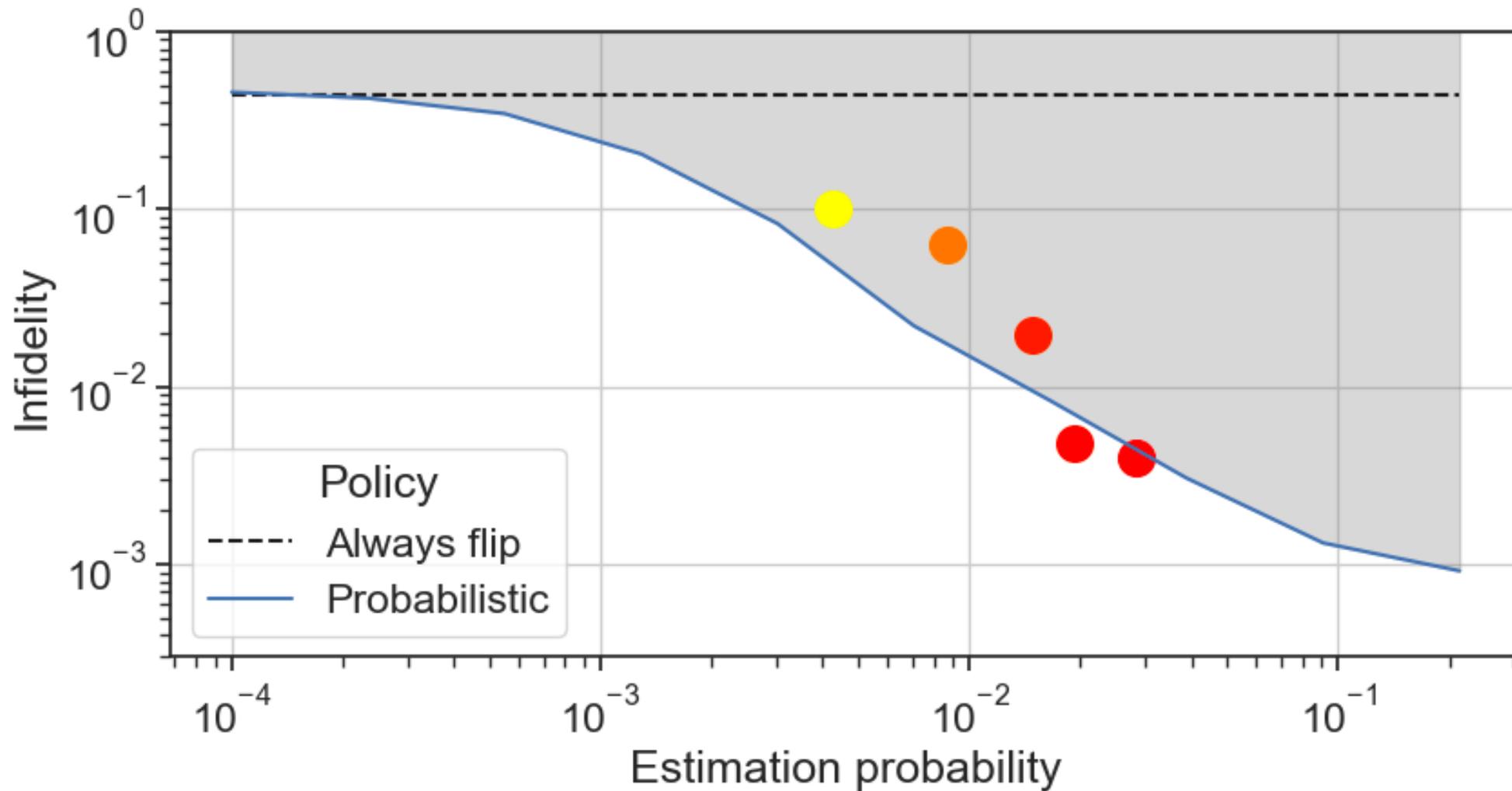
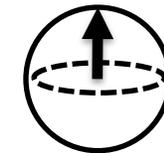
$\mu_n, \sigma_n$

● Run algorithm ● Estimate

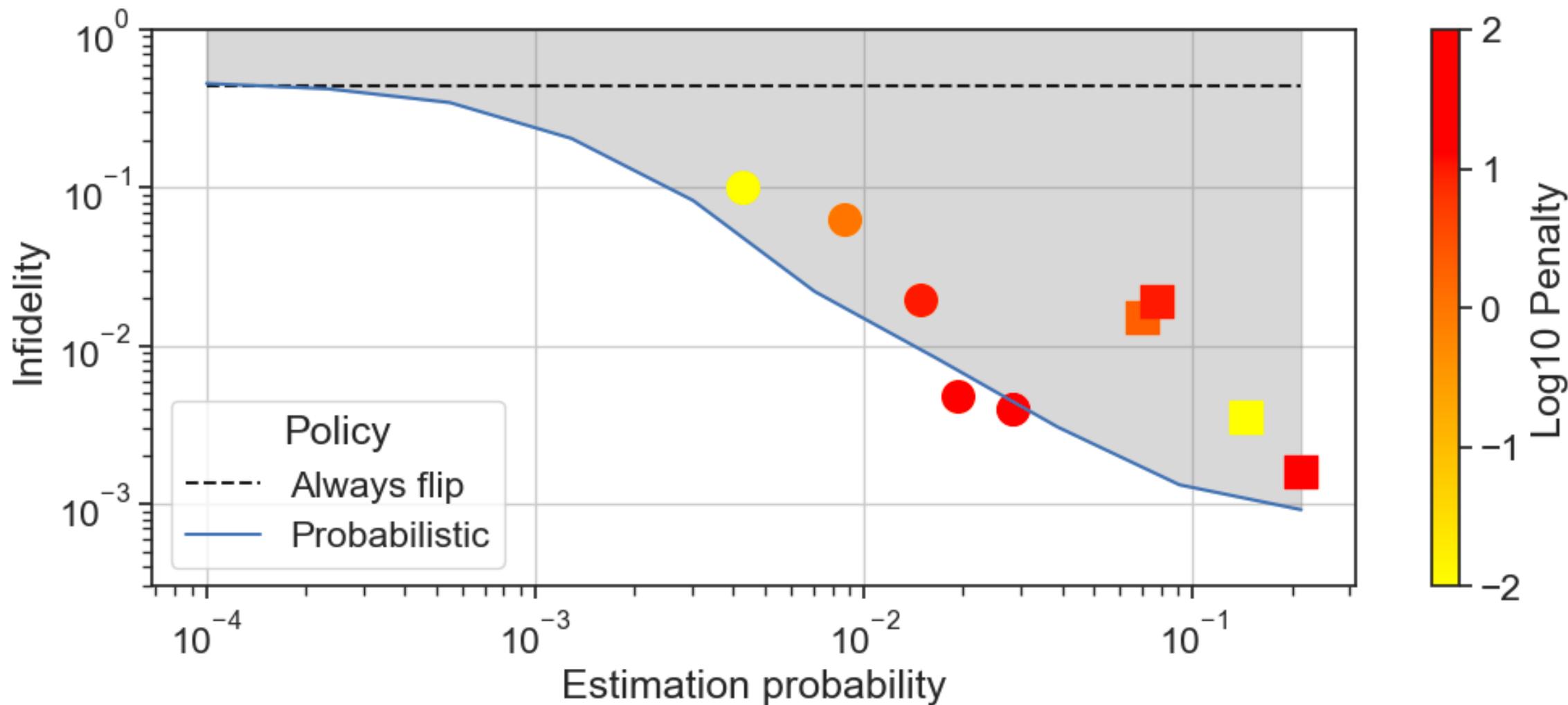
$$P(\delta\omega' t | \delta\omega, 0)$$

$$\mu_{n+1}, \sigma_{n+1} = g(\mu_n, \sigma_n, x_n, \tau_n)$$

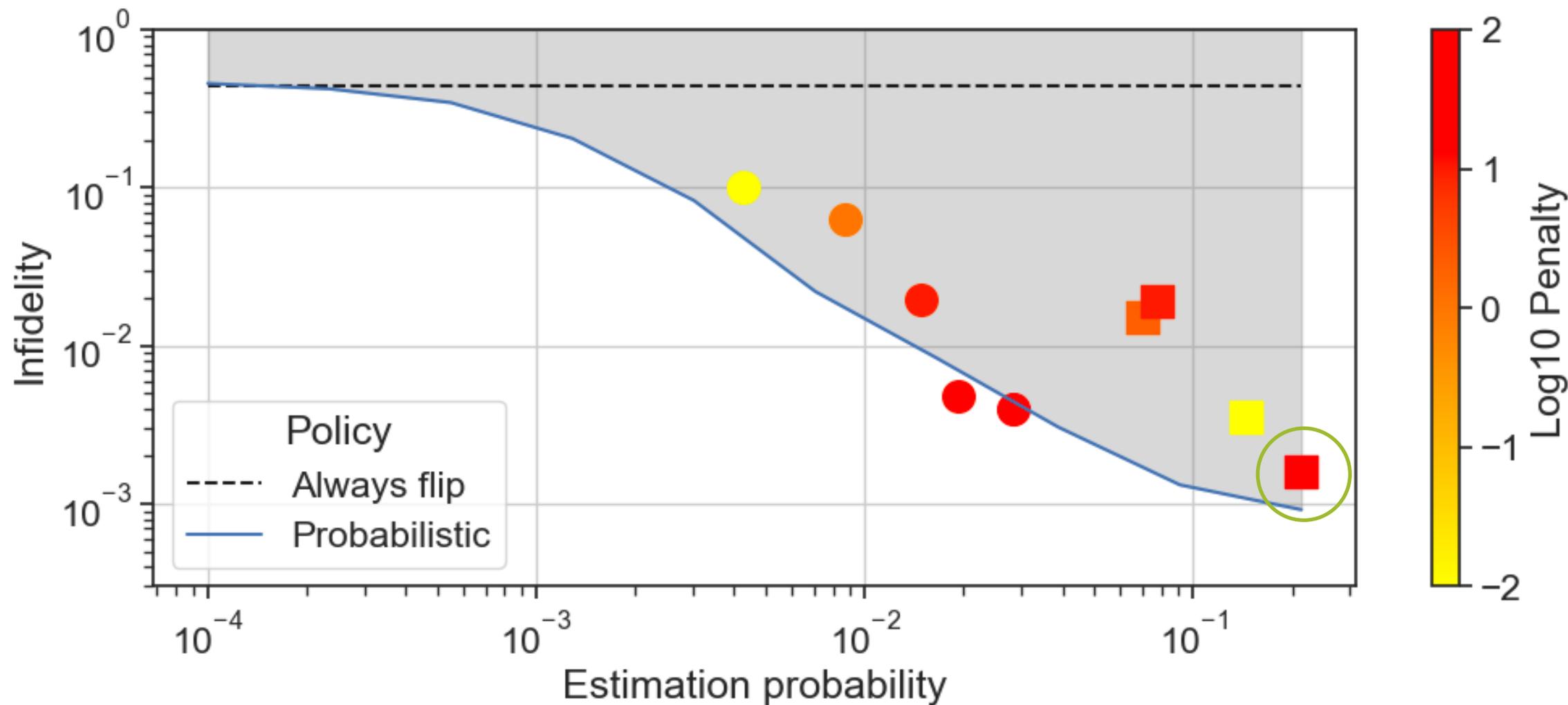
# Agent cannot control time, $\tau_n = 1/c\sigma_{n-1}$



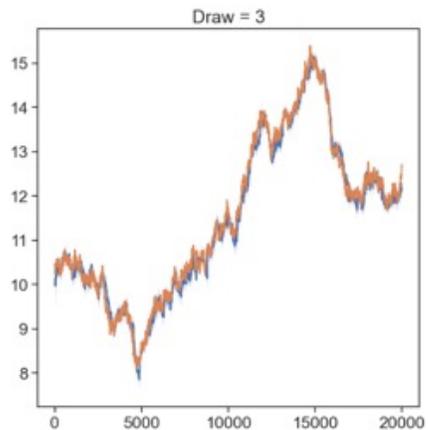
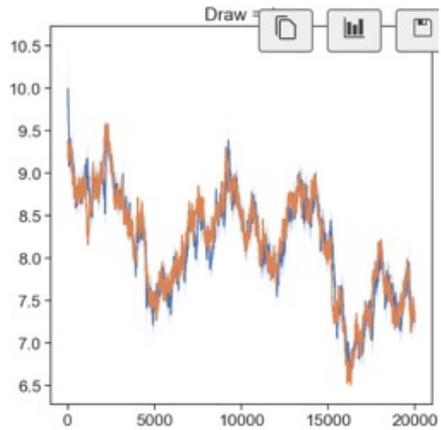
# Agent can control time



# Agent can control time

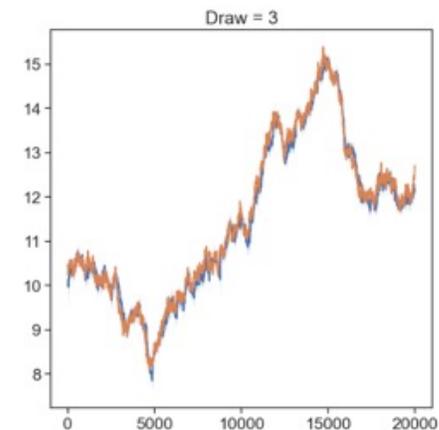
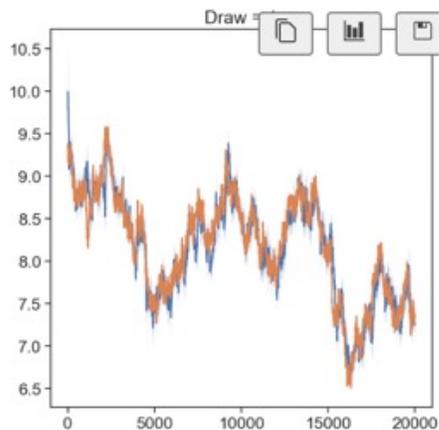


# Understanding the best agent

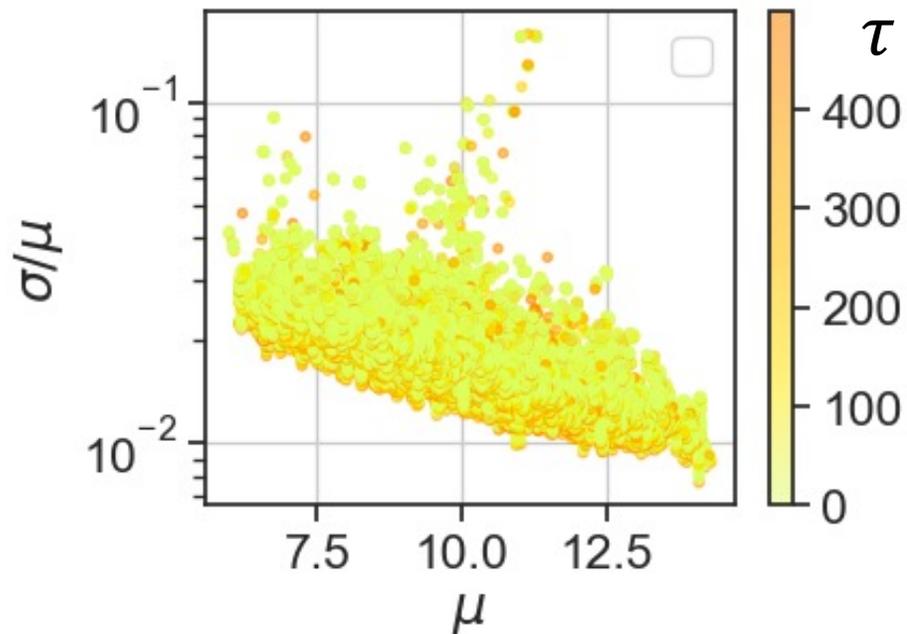


1. Tracks  
trajectories

# Understanding the best agent

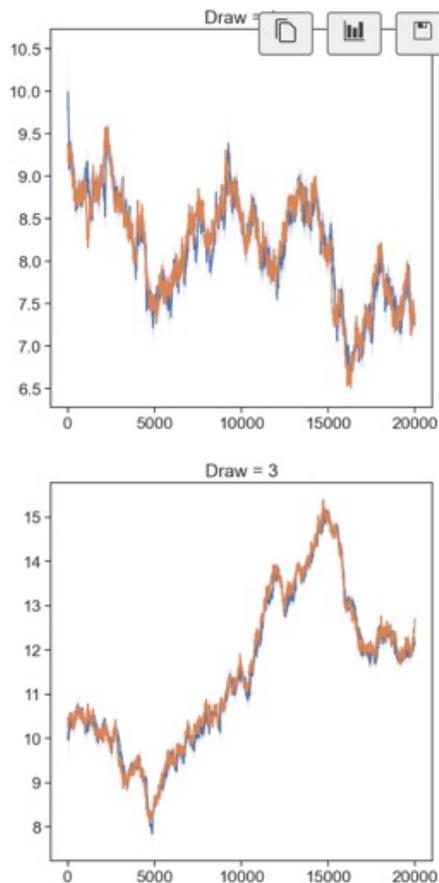


1. Tracks trajectories

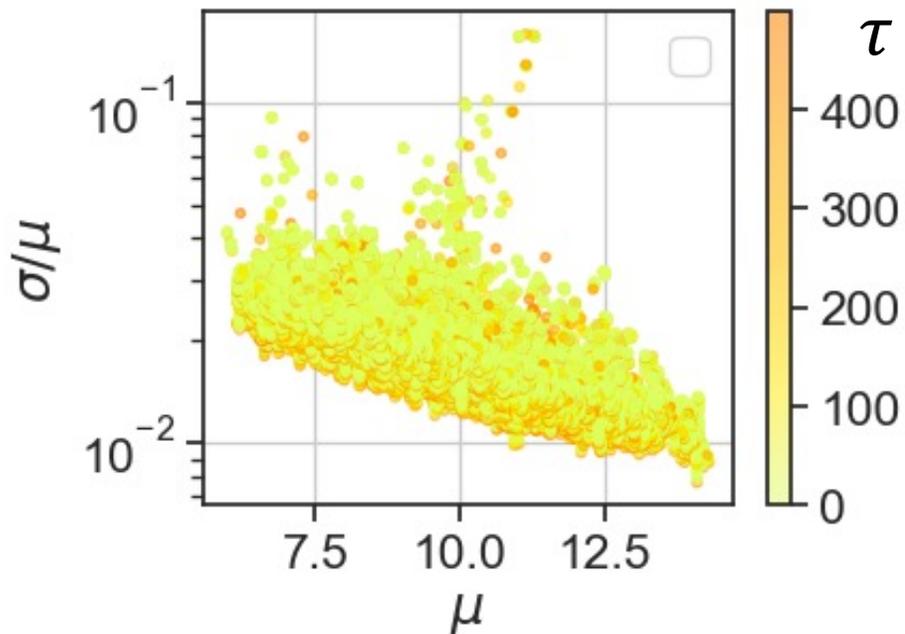


2. Applies  $\frac{1}{\sigma}$  strategy

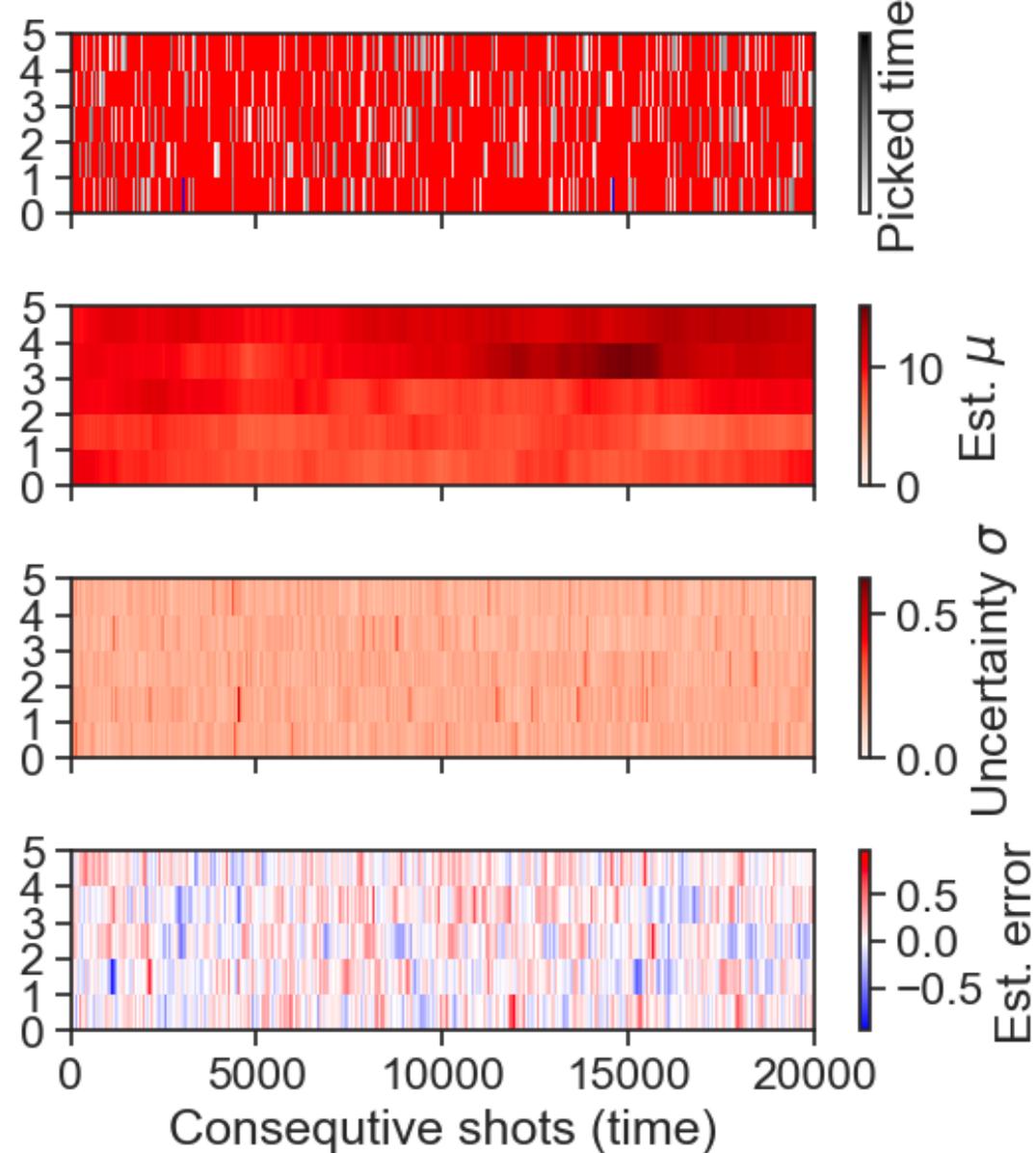
# Understanding the best agent



1. Tracks trajectories

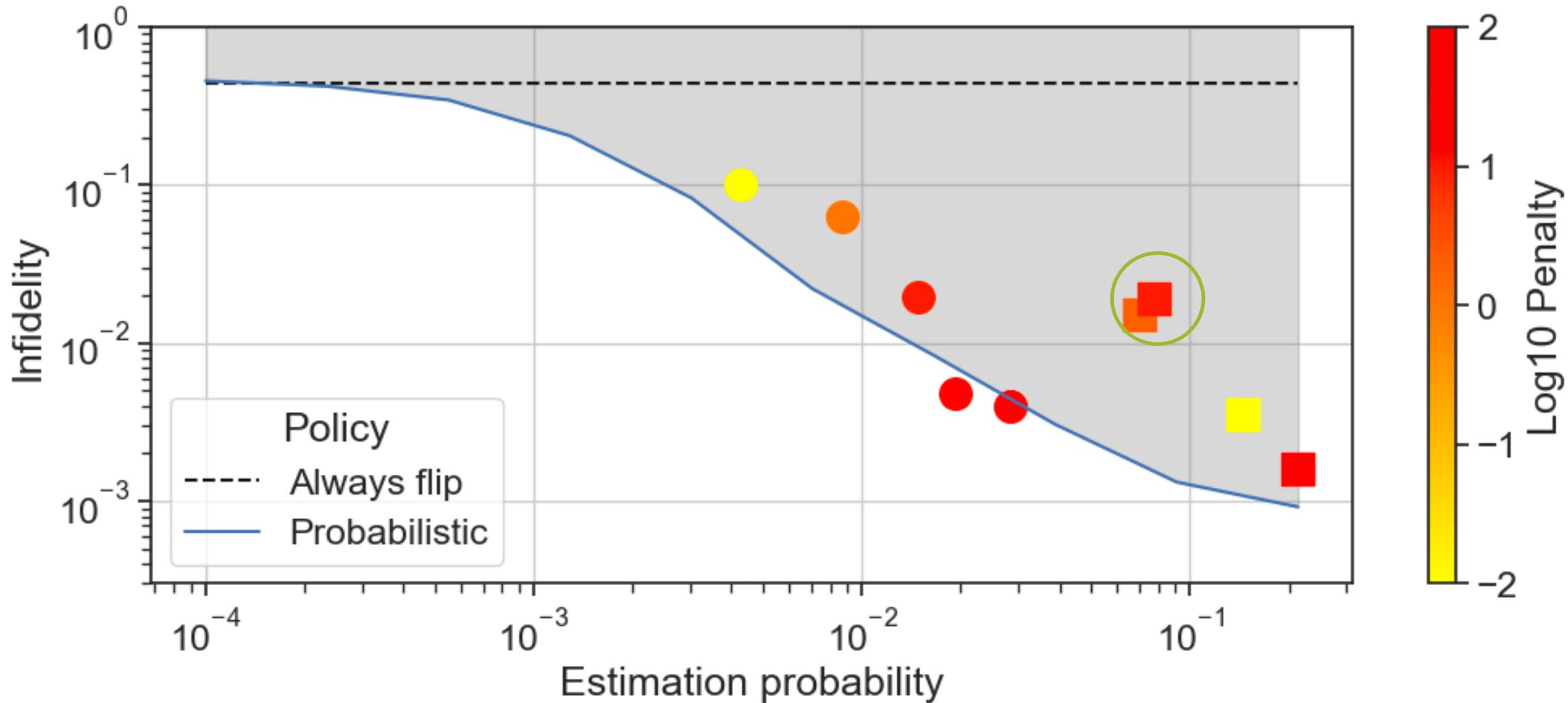


2. Applies  $\frac{1}{\sigma}$  strategy

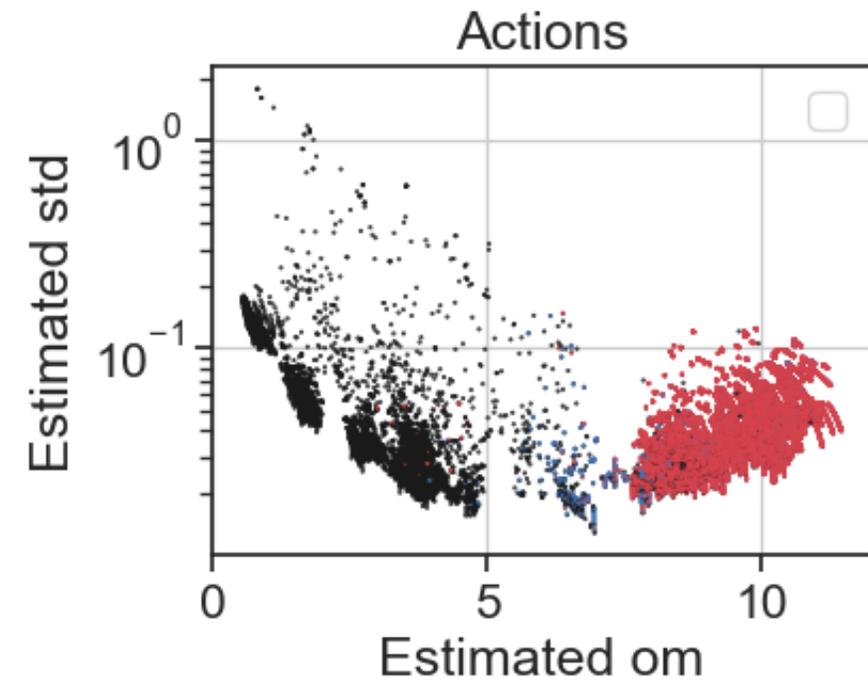


3. Behaves

# But there is a more clever one

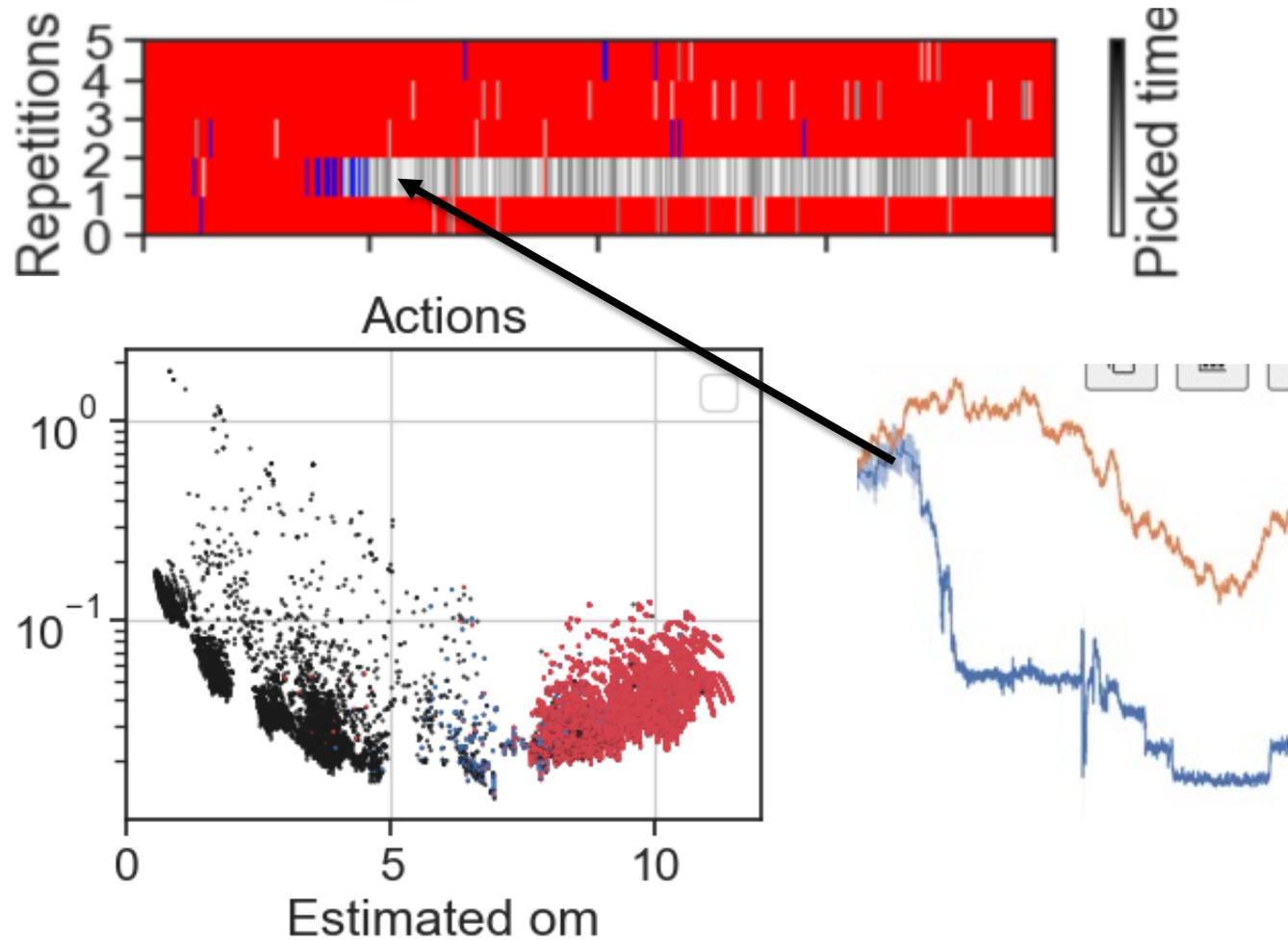


# Smart agent (but not efficient)



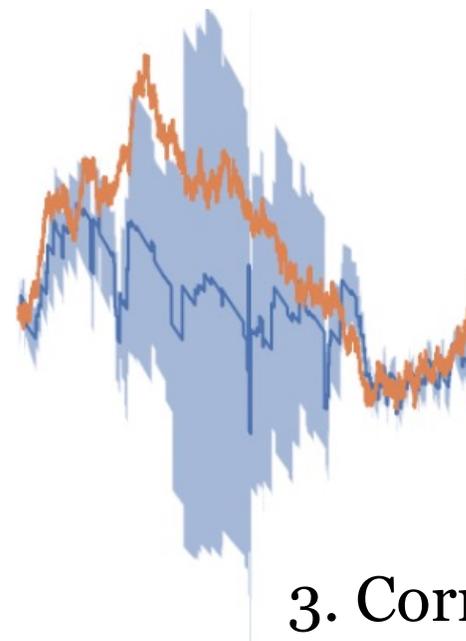
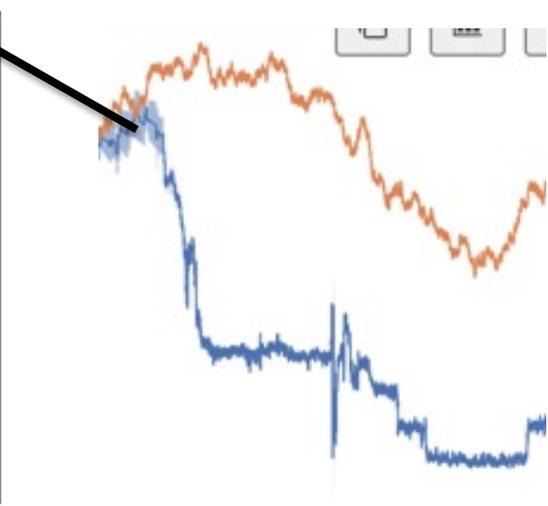
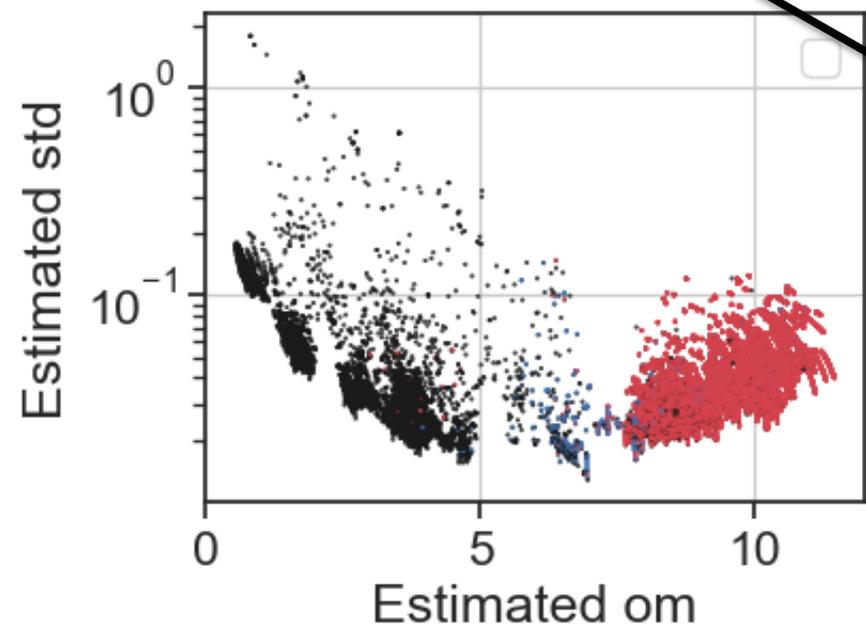
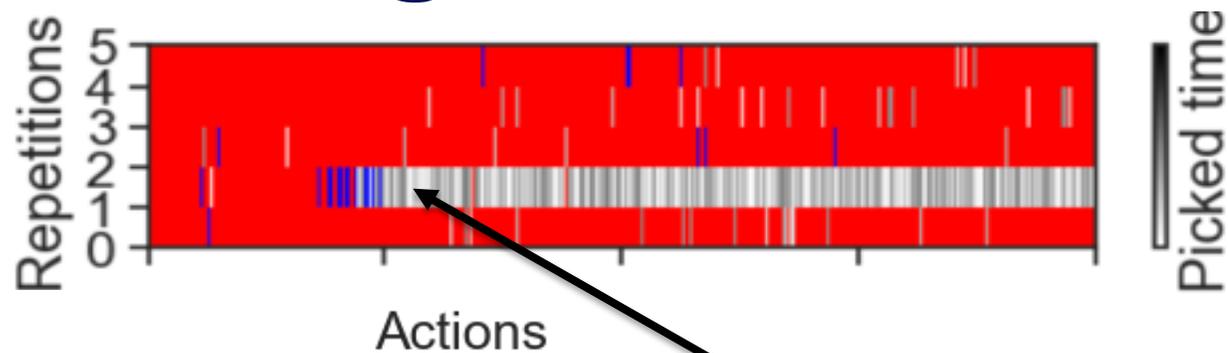
1. Waits for large field

# Smart agent (but not efficient)



1. Waits for large field
2. Knows when its lost

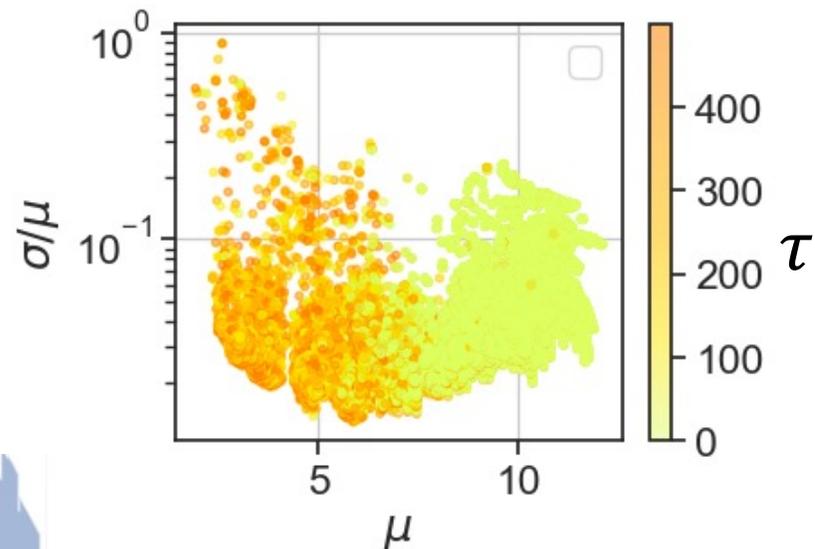
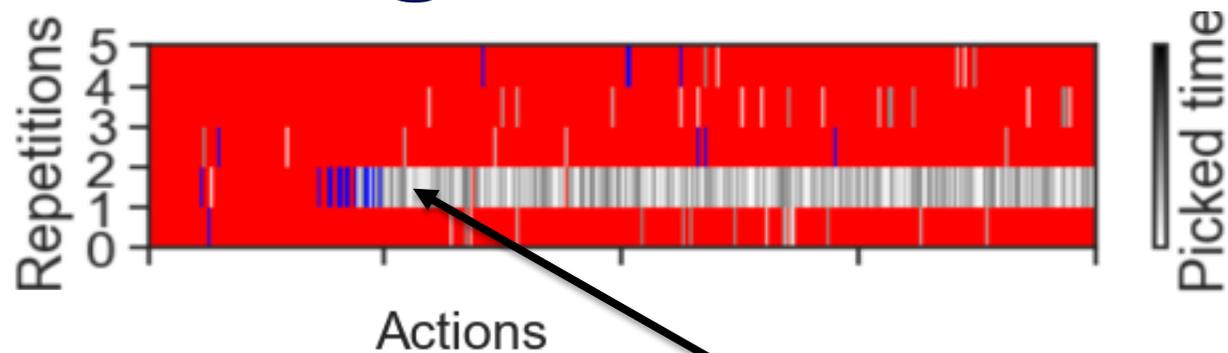
# Smart agent (but not efficient)



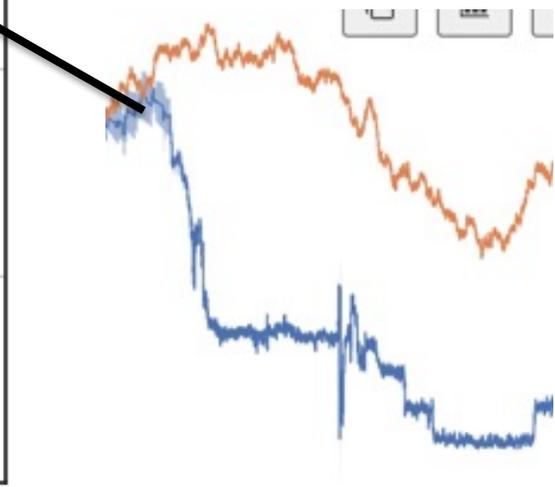
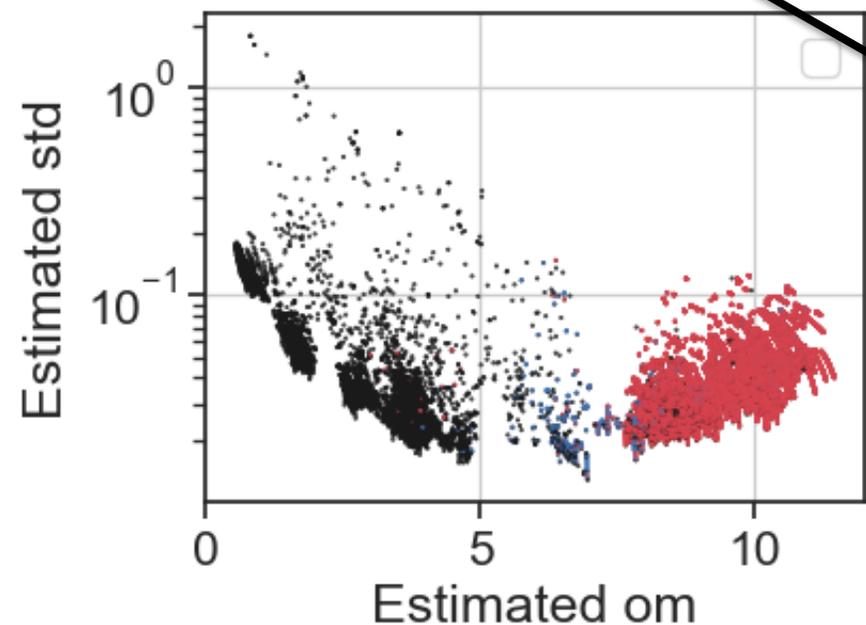
3. Correlates  $\sigma$  with error

1. Waits for large field
2. Knows when its lost

# Smart agent (but not efficient)



4. Uses large  $\tau$   
For small fields



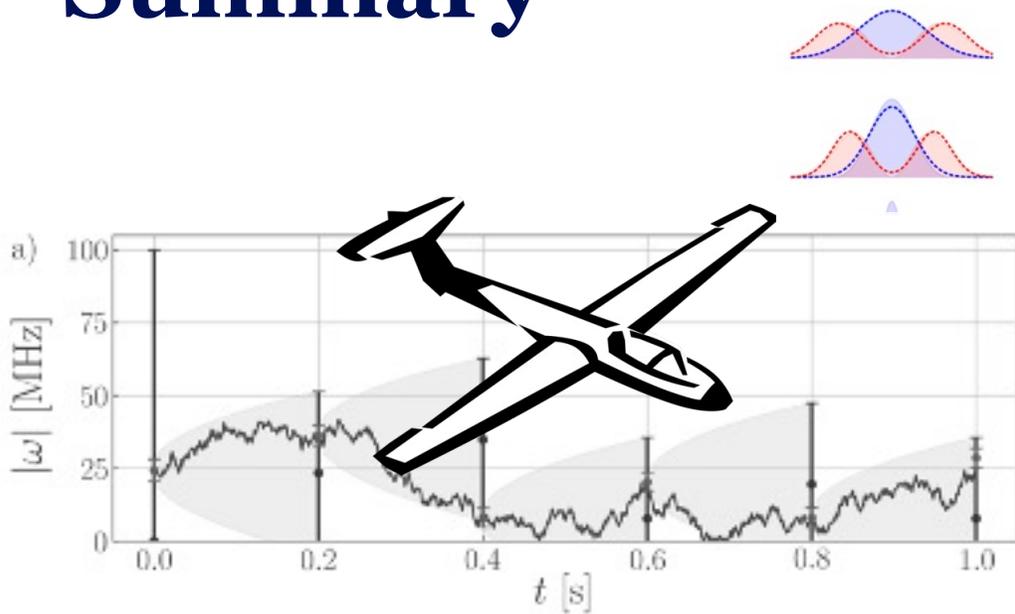
3. Correlates  
 $\sigma$  with error

1. Waits for large field    2. Knows when its lost

# Summary



# Summary



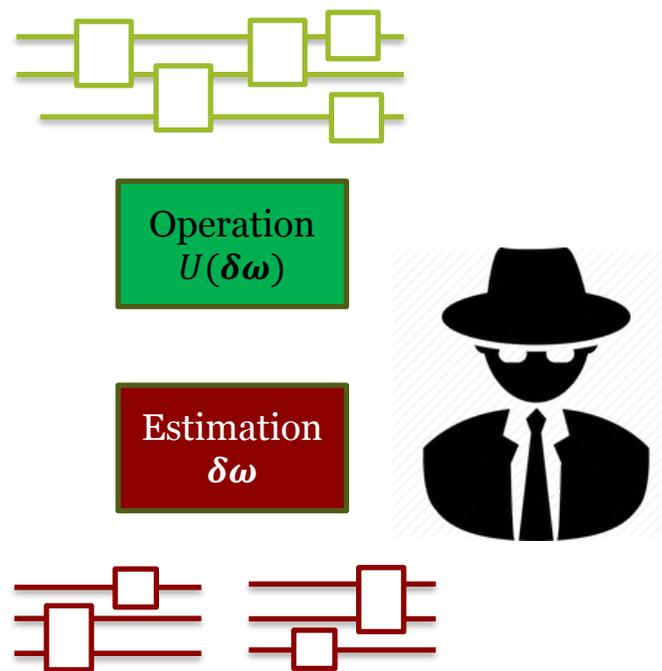
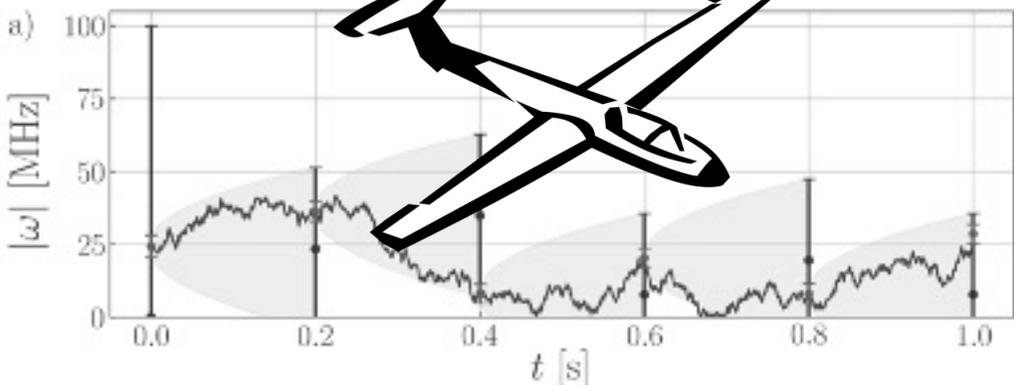
Summary

We developed methods  
of fast, resource-efficient  
field estimation

Outlook

Can we generalize to  
arbitrary noise source?

# Summary



Summary

We developed methods of fast, resource-efficient field estimation

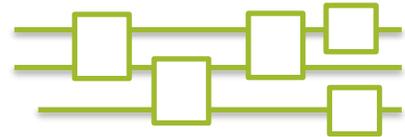
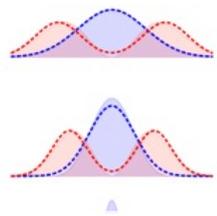
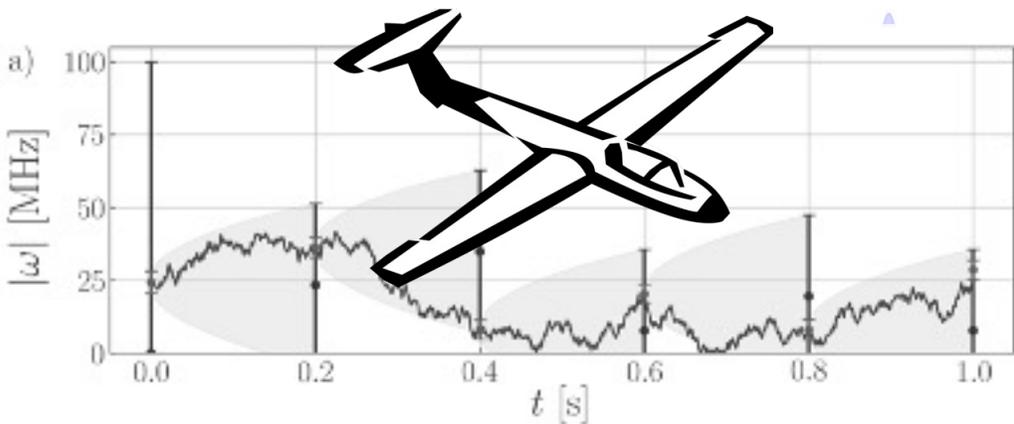
We employed a RL agent to dynamically change between estimation and operation modes

Outlook

Can we generalize to arbitrary noise source?

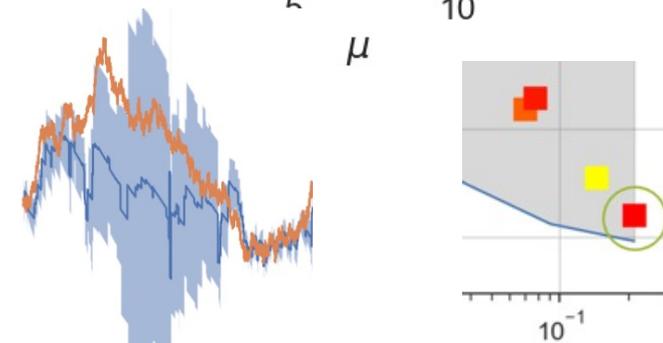
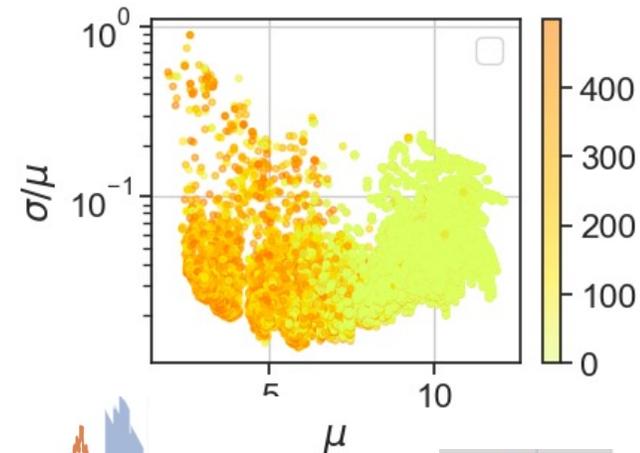
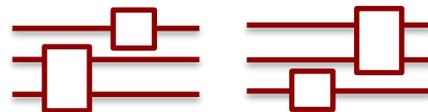
Can we do online learning (FPGA?)  
Can we use it for two-qubit gates?

# Summary



Operation  
 $U(\delta\omega)$

Estimation  
 $\delta\omega$



Summary

We developed methods of fast, resource-efficient field estimation

We employed a RL agent to dynamically change between estimation and operation modes

The agent developed non-trivial strategies and matched best-known heuristics

Outlook

Can we generalize to arbitrary noise source?

Can we do online learning (FPGA?)  
Can we use it for two-qubit gates?

Can we beat the heuristics?  
Can we use the learned strategy to improve heuristics?

# Hadamard gate

$$J(\epsilon^*) = \Delta B_z$$

- For each shot, we performed two estimations:

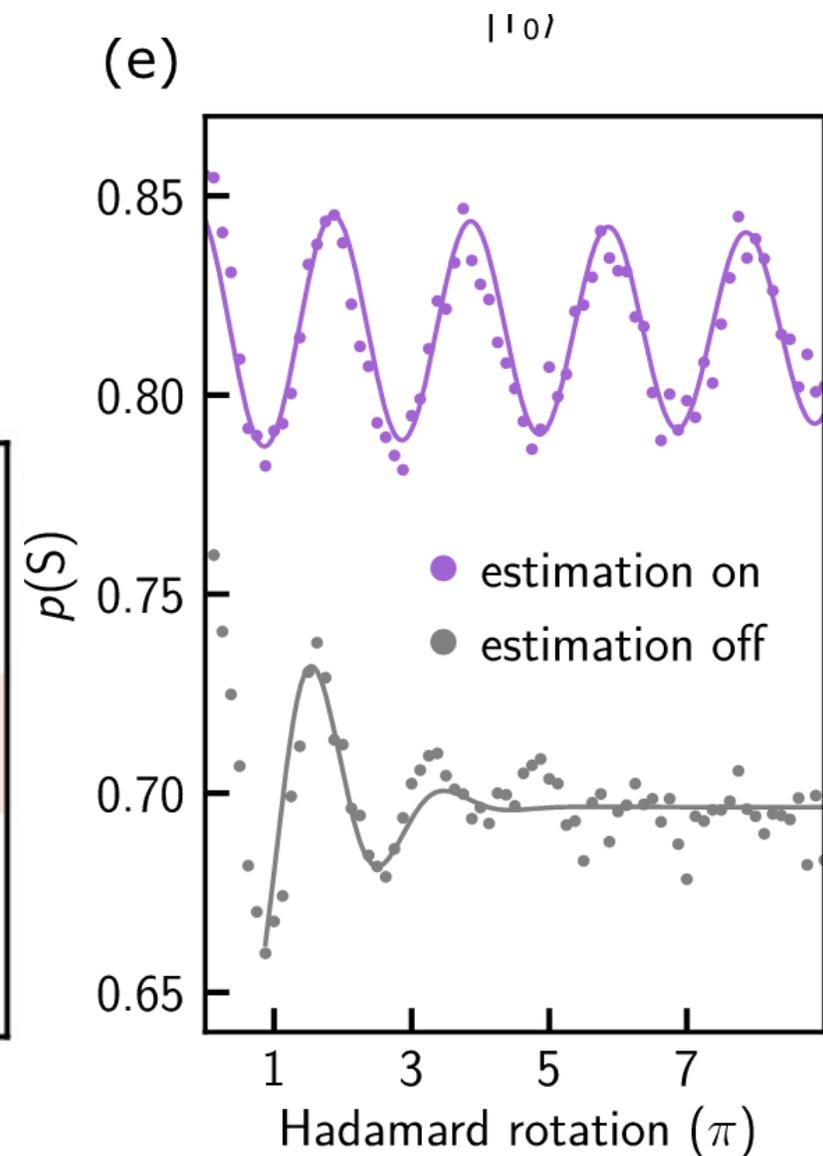
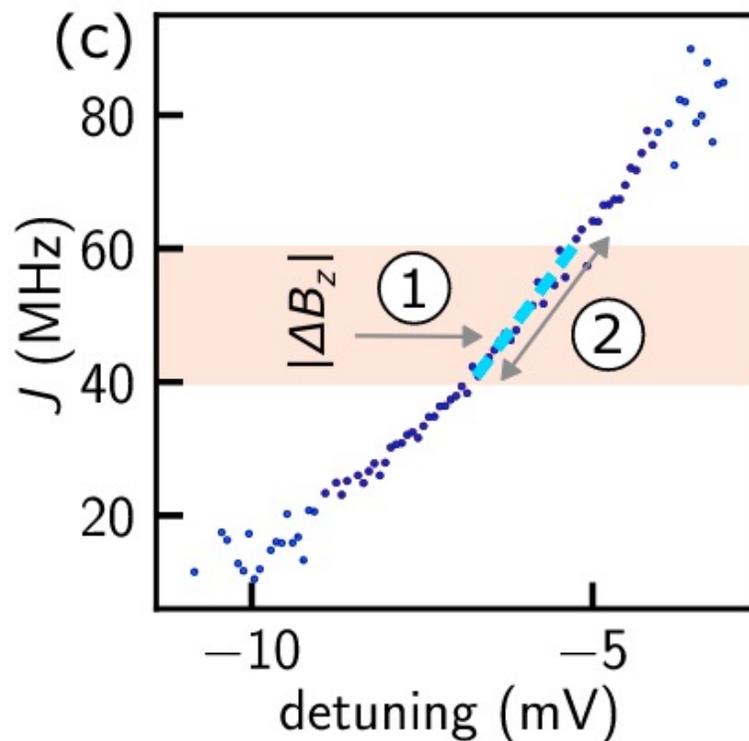
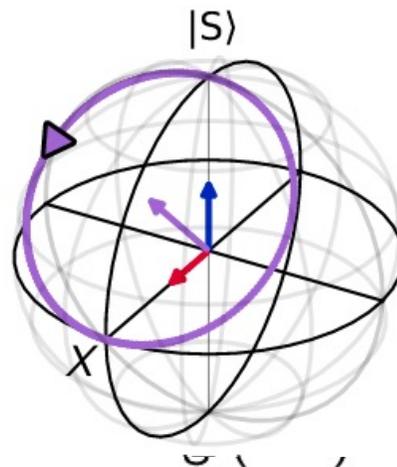
1. Estimation of  $\Delta B_z$

2. Estimation of  $\Omega(\epsilon)$ , at  $\epsilon$

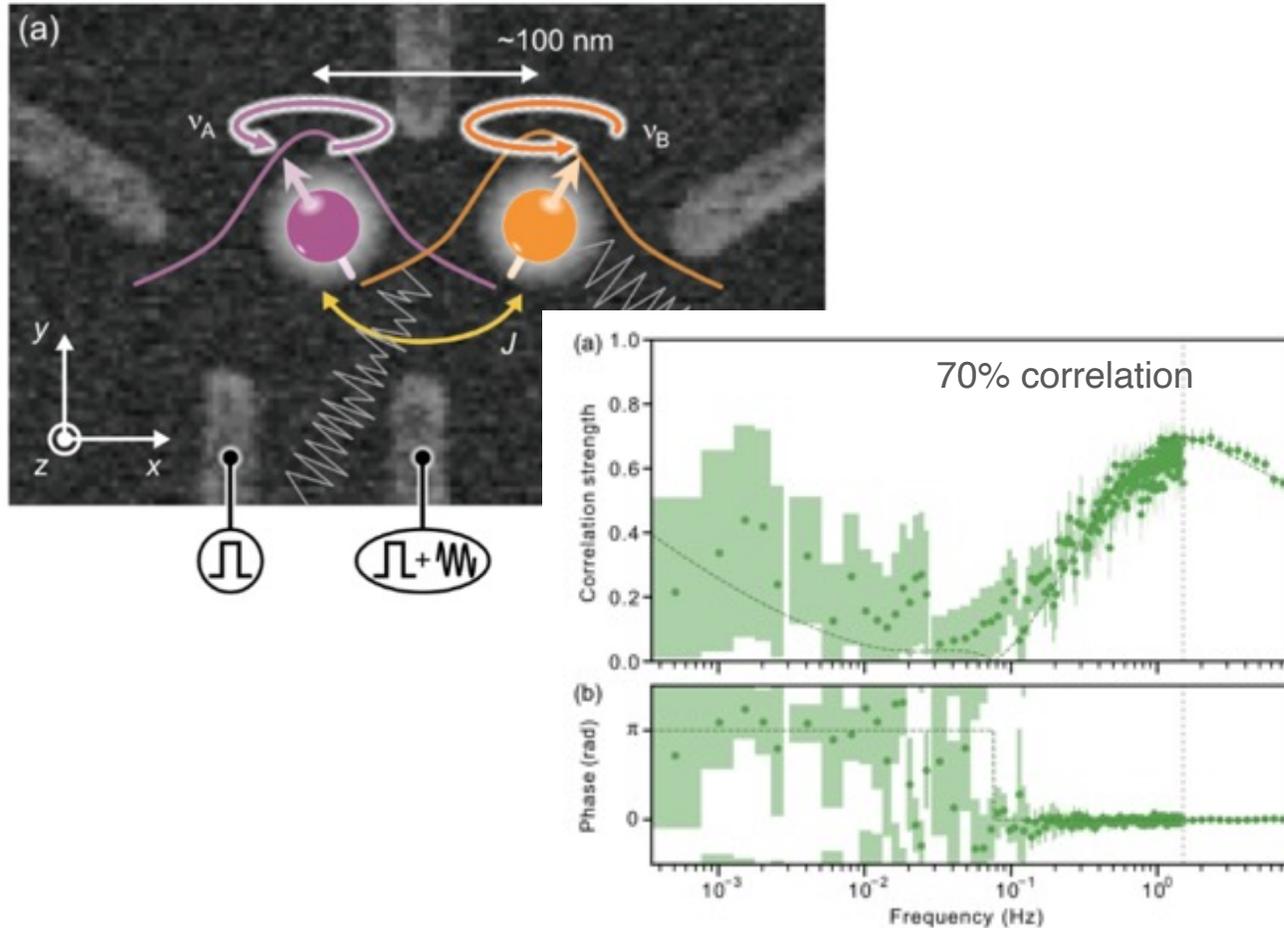
where  $J(\epsilon) = \Delta B_z$

- Based on  $\Delta\Omega$  :

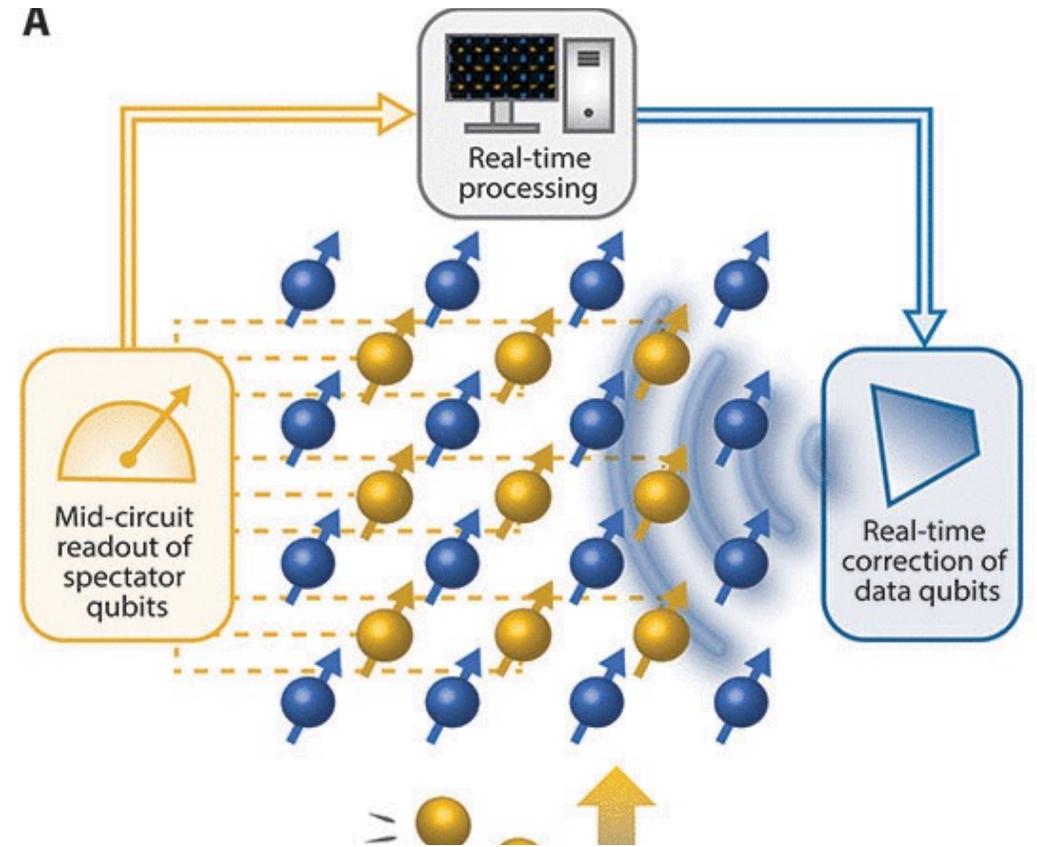
$$\Delta\epsilon = \epsilon - \epsilon^*$$



# Investigate utility of spatial correlations



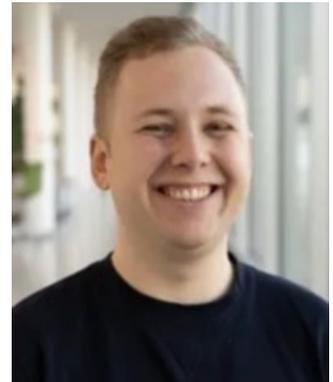
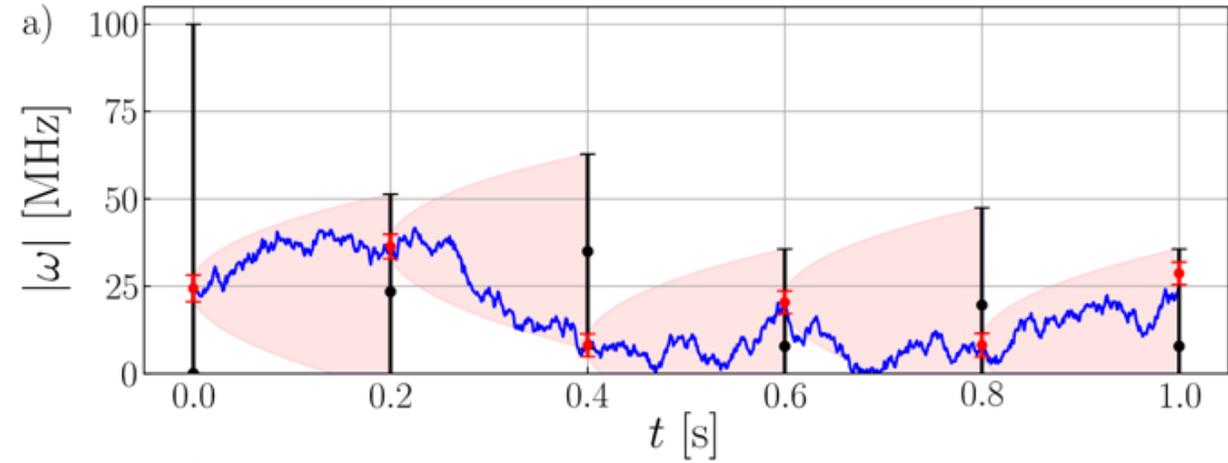
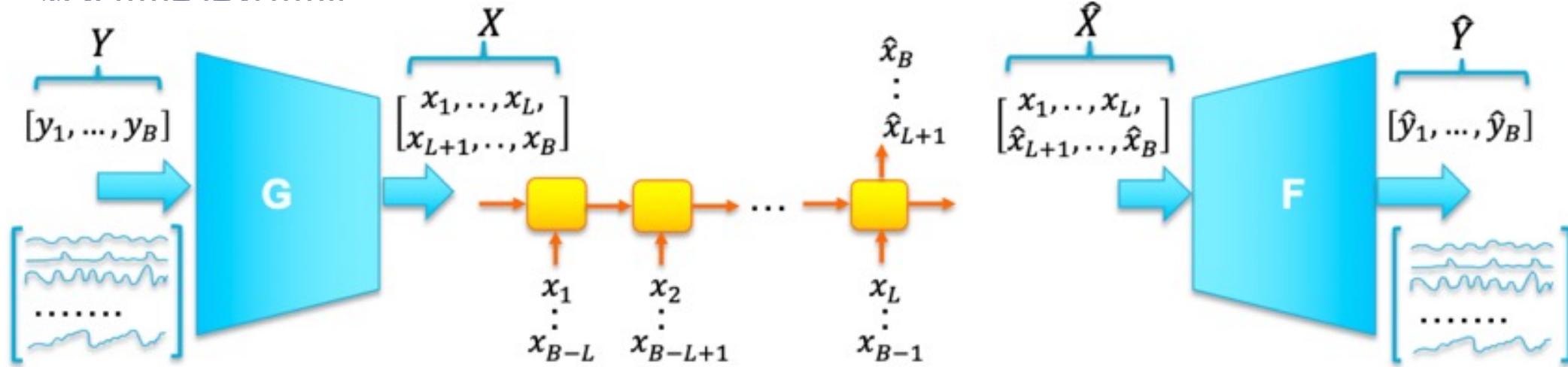
Y. Yoneda et al., arXiv:2208.14150 (2023)



K. Singh *et al.*, Mid-circuit correction of correlated phase errors using an array of spectator qubits *Science* **380**,1265-1269 (2023).

# Trajectory analysis and prediction

- Representing the sequential estimation and field broadening in the language of functional integral
- Process identification and prediction enabled by Machine learning

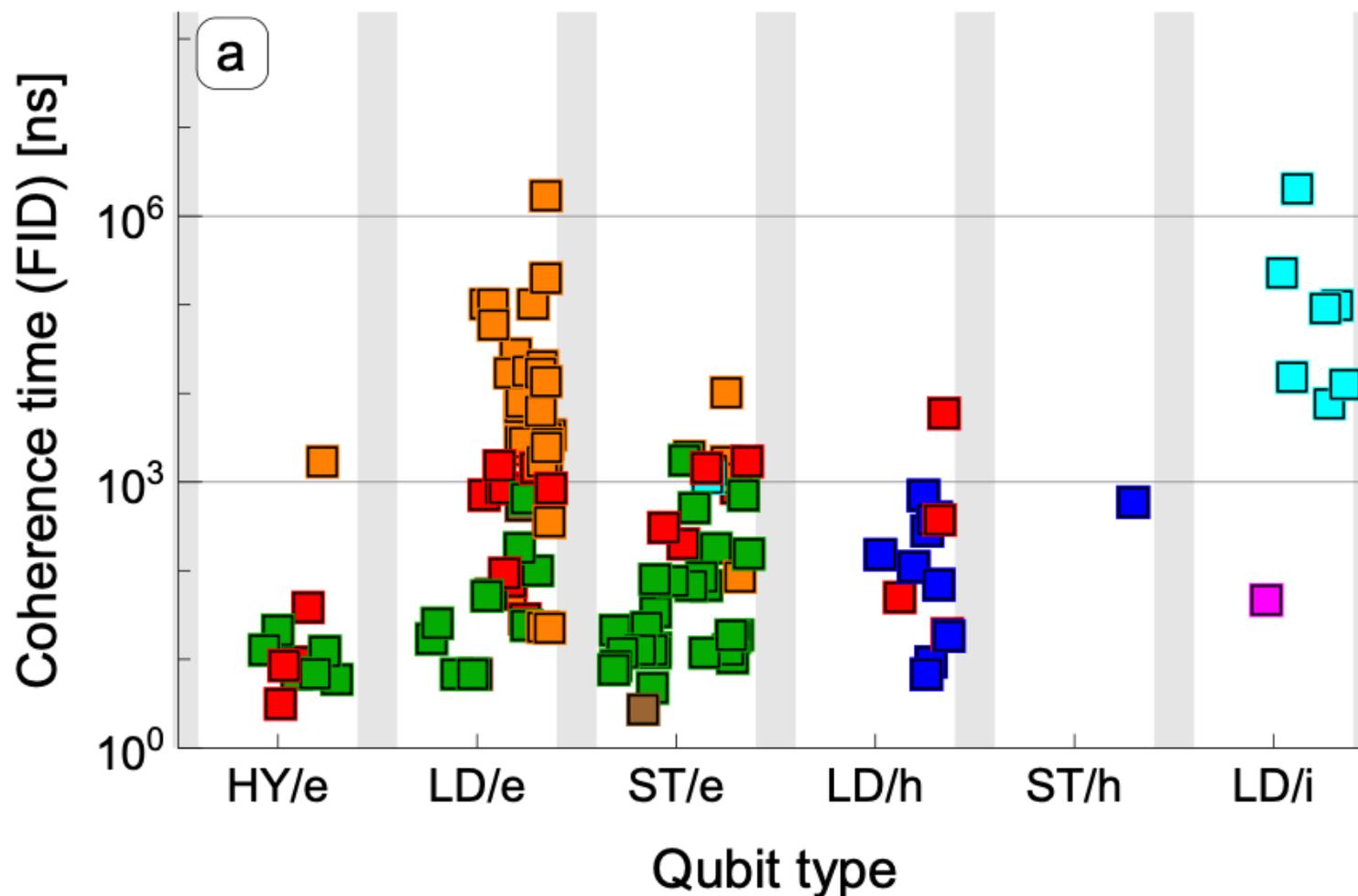


Felix Frohnert

N. Nguyen, B. Quanz, Temporal Latent Auto-Encoder: A Method for Probabilistic Multivariate Time Series Forecasting, arXiv:2101.10460 (2021)

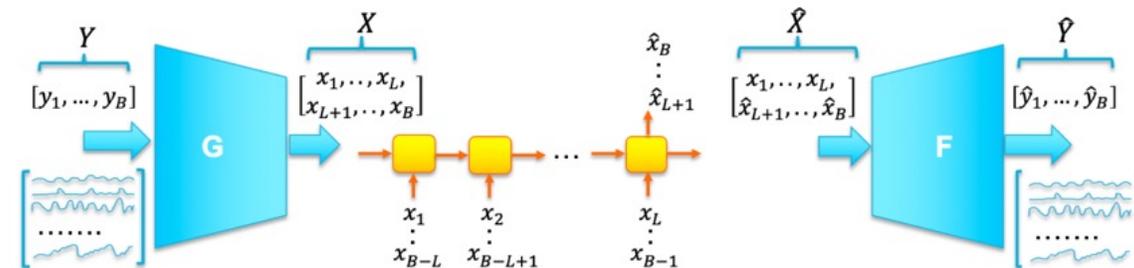
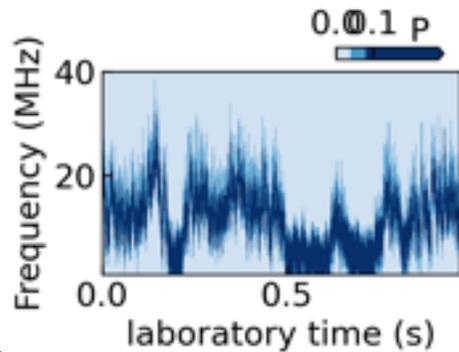
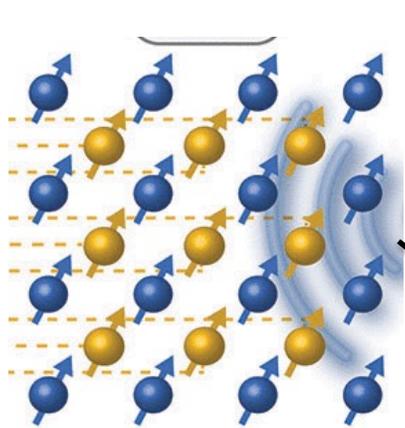
# Spin qubits are limited by inhomogeneous broadening...

● III-V ● Ge ● Si ●  $^{28}\text{Si}$  ● Si:X ●  $^{28}\text{Si:X}$  ● C □  $T_2^*$



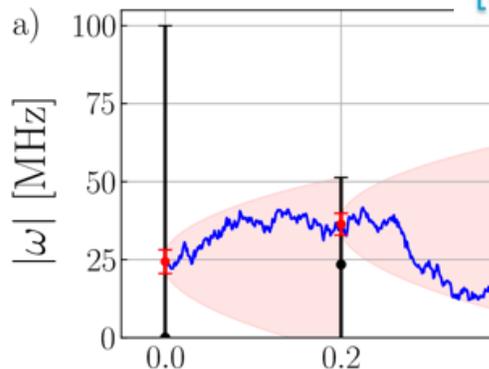
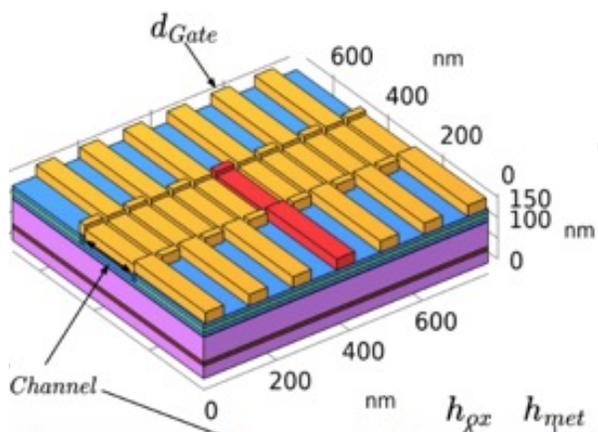


# Anyway the Wind Blows: Bayesian Estimation and Feedback for Correlated

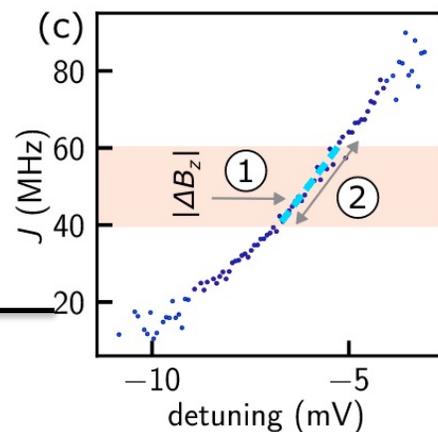


Future quantum computer

PLAN: Use ML, filtering and Bayesian tools

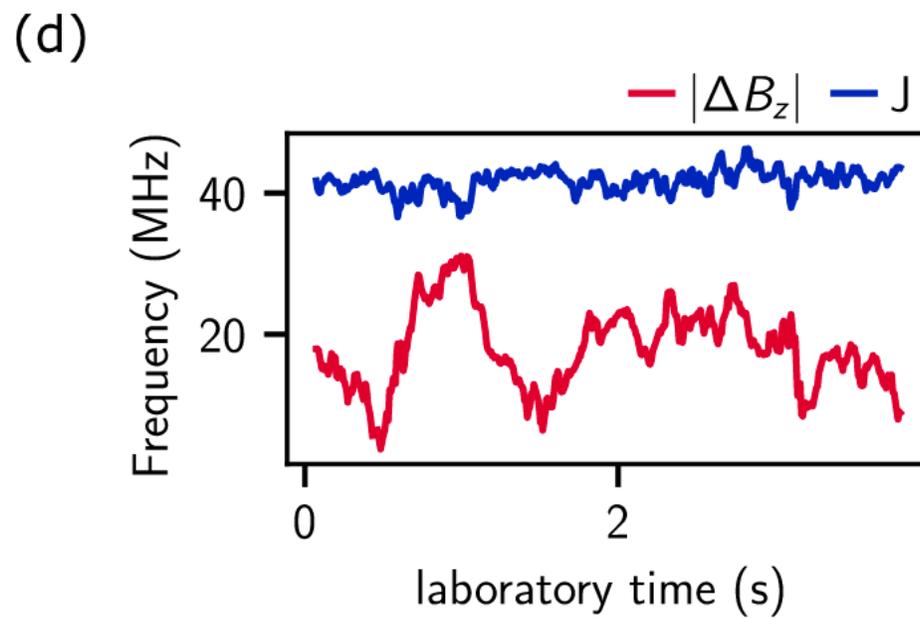
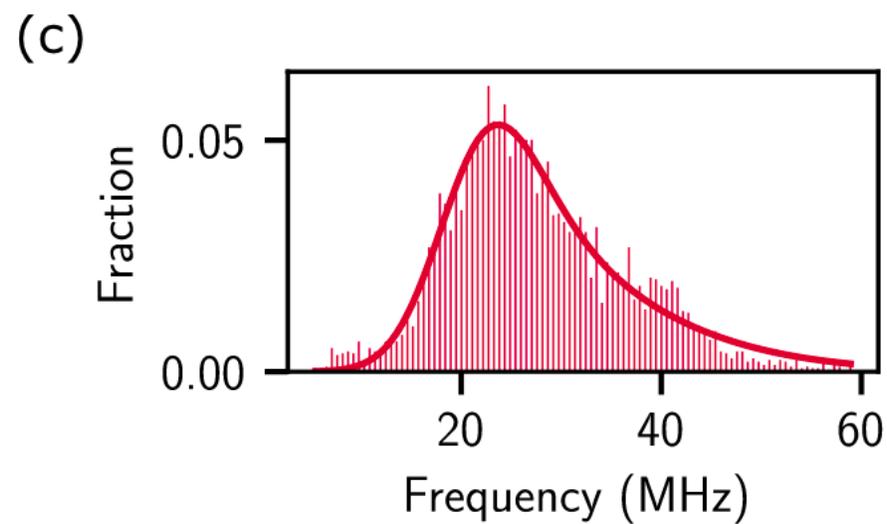
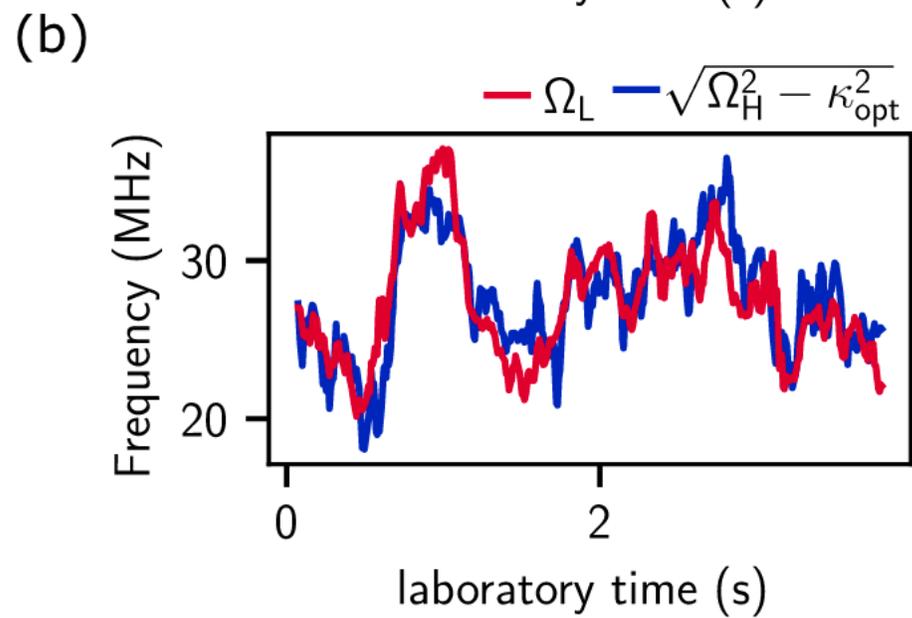
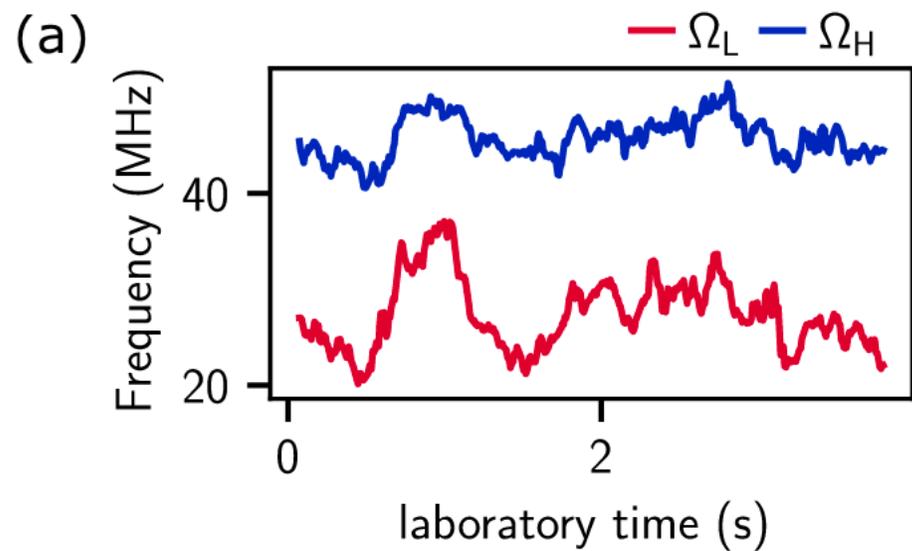


Tracking Hamiltonian Parameters



Feedback for Hadamard gate

Model of charge noise  
And spatial correlations

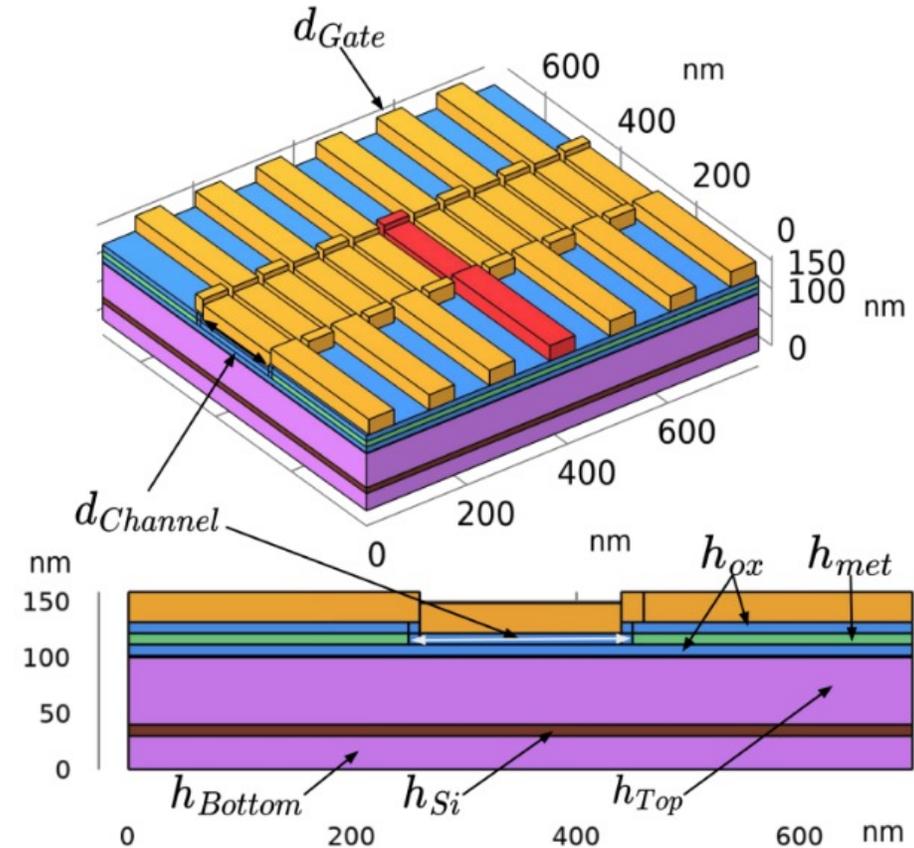
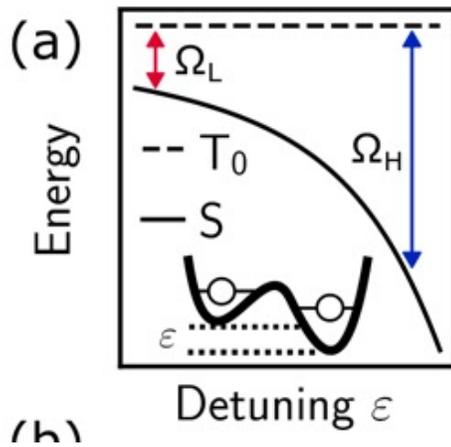


# Charge noise

- Charge noise limits almost all spin qubits. For S-T we have

$$J(\epsilon + \delta\epsilon) = J(\epsilon) + \partial_{\epsilon}J(\epsilon)\delta\epsilon$$

- It is believed to originate at the isolated chargers at the oxide-semiconductor interface

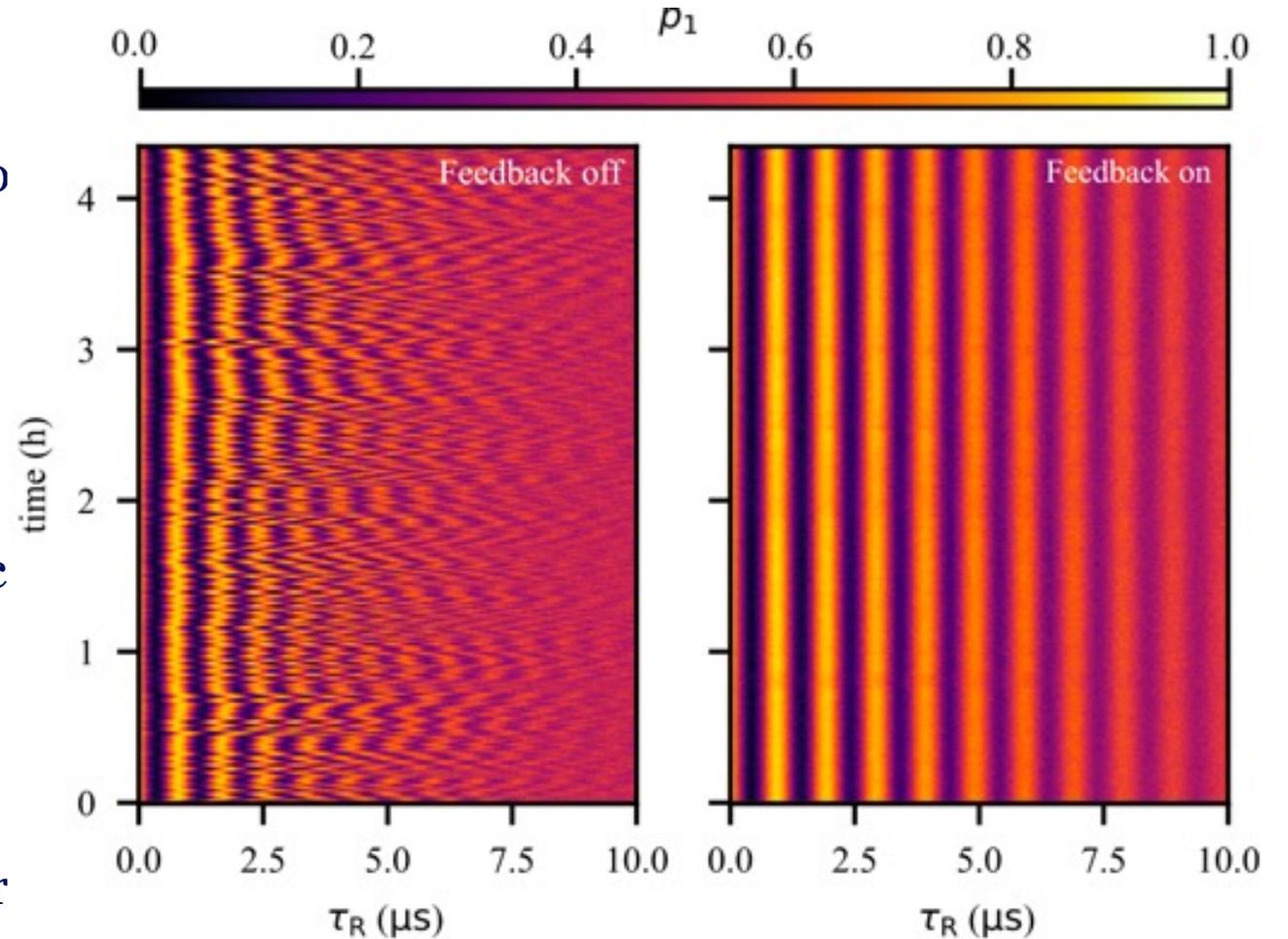


# Charge noise

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$$J(\epsilon + \delta\epsilon) = J(\epsilon) + \partial_{\epsilon}J(\epsilon)\delta\epsilon$$

- It is believed to originate at the isolated chargers at the oxide-semiconductor interface
- Each defect is a source of telegraph noise, which result in  $1/f$  spectral density
- In comparison to  $\Delta B_z$  charge noise have more weight at finite frequency.



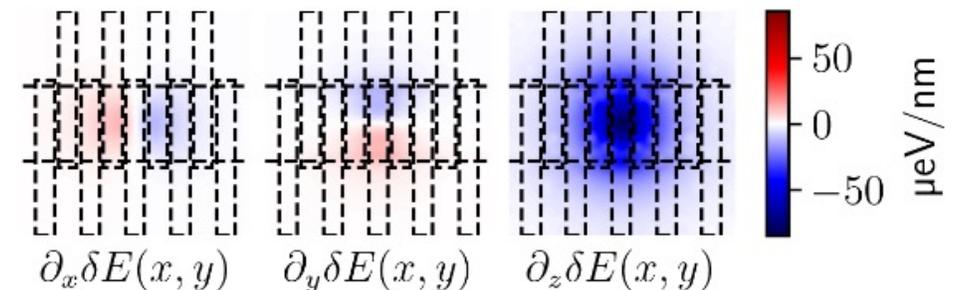
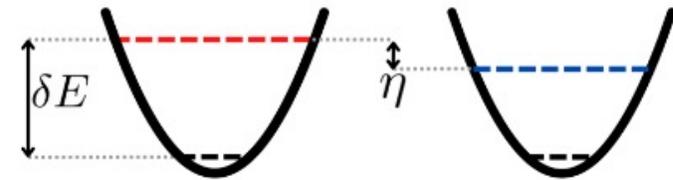
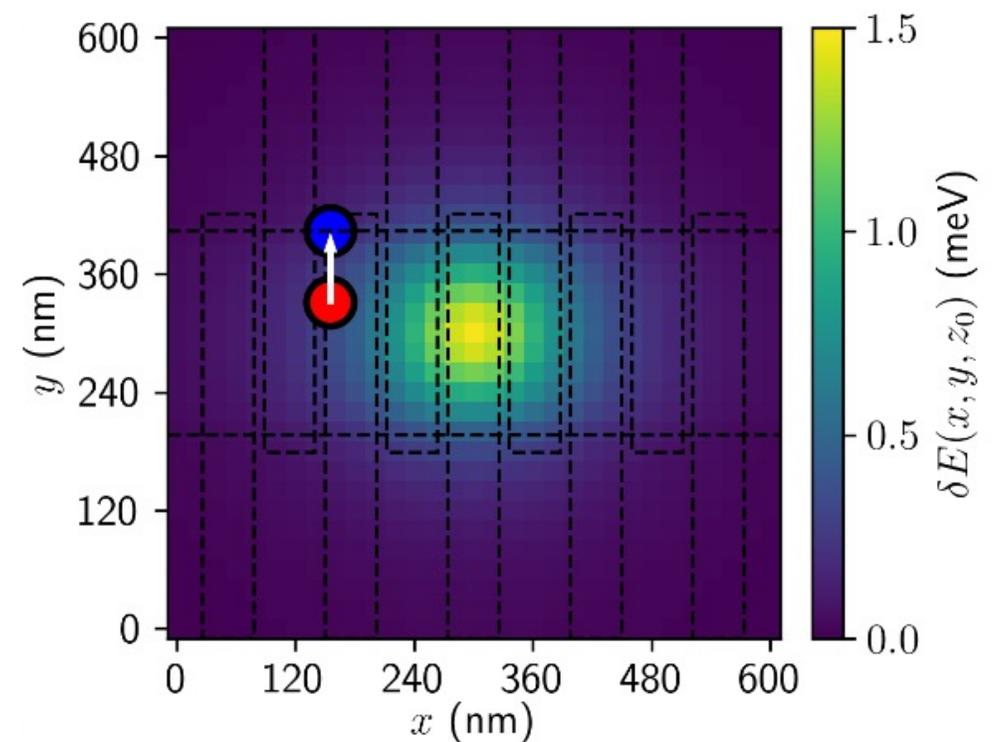
# Model of charge noise

- Noise come from the sum of TLF

$$\sigma^2 = \sum_n \eta_n^2$$

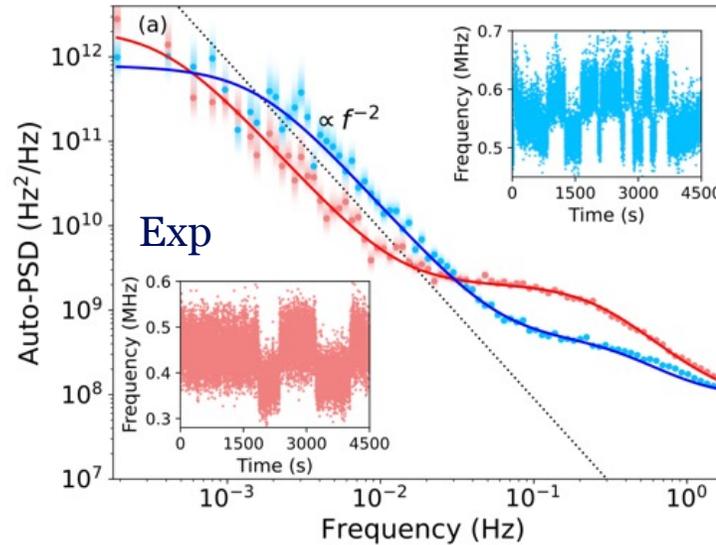
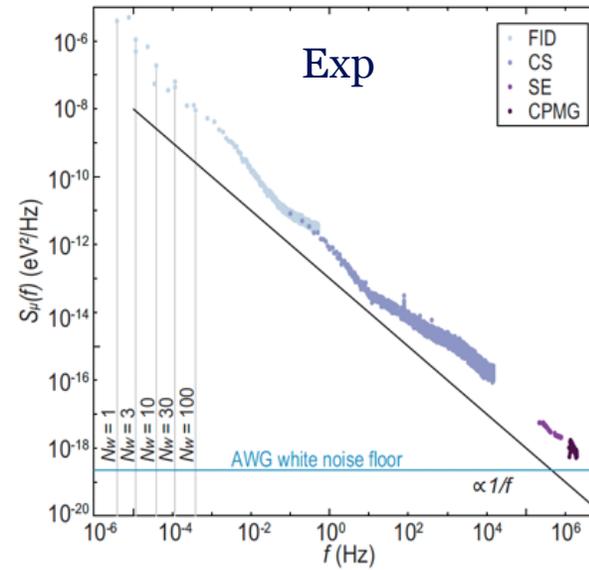
- Each defect charge can physically move by random vector  $\delta \mathbf{r}_n$
- Use finite-element method (COMSOL) to compute shift of dots energy  $\delta E(x, y, z_0)$  due to defect at  $(x, y, z_0)$
- We compute the contribution from charge movement using spatial derivatives:

$$\eta_n = \nabla \delta E \cdot \delta \mathbf{r}_n$$

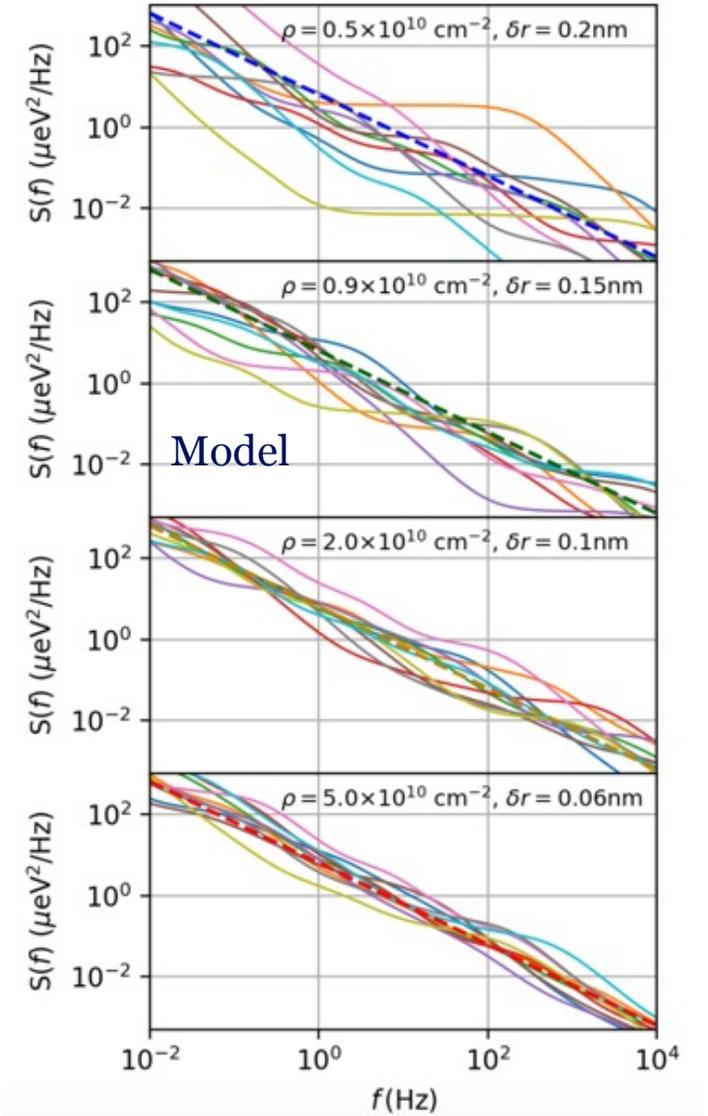


# Spectral density

- Compared against experimentally measured spectra
- Adjusted two free parameters
  - Defect density  $\rho$
  - Typical size of the displacement  $\delta r$



arXiv 2302.11717 (2023)



# Planar motion of the charges?

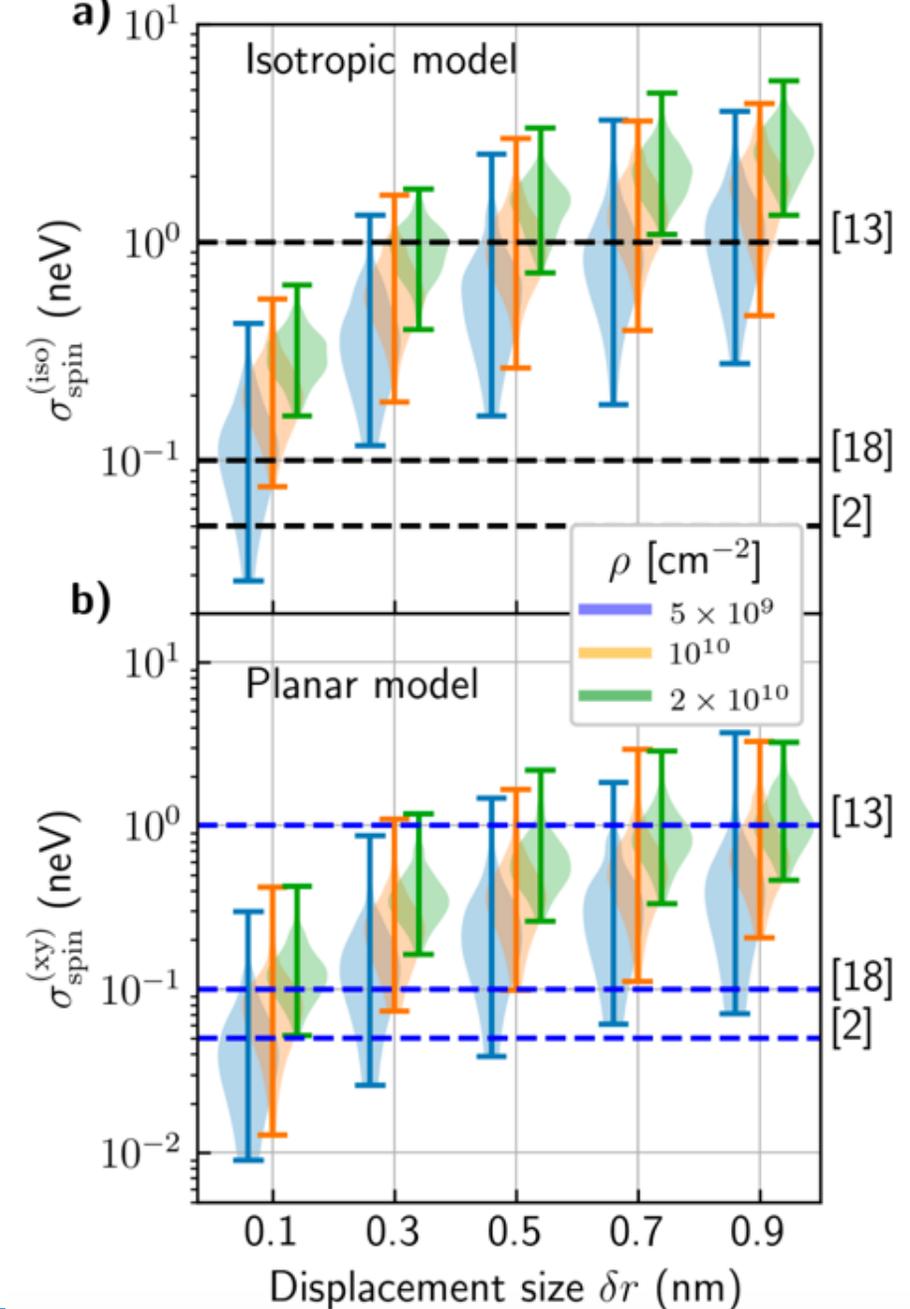
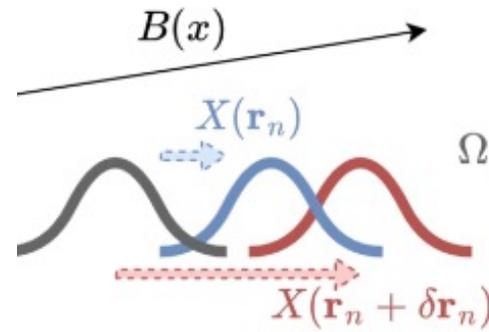
- Charge noise induces spin splitting noise(SOI)

$$H = \mathbf{B}_{\parallel} \cdot \boldsymbol{\sigma} = \Omega \hat{\sigma}'_z$$

- It is caused by shaking of wavefunction in presence of mag. field gradient

$$\delta\Omega(\mathbf{r}_n) = g\mu_B\Delta B_{\parallel} \cdot \delta R(\mathbf{r}_n)$$

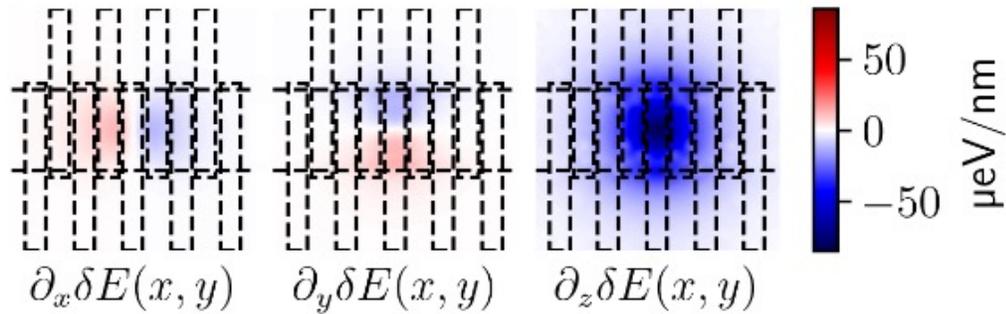
- From this analysis we made a hypothesis that charges move in the planar direction
- We predict  $\rho \approx 10^{10} \text{ cm}^{-2}$ ,  $\delta r = 0.5 \text{ nm}$



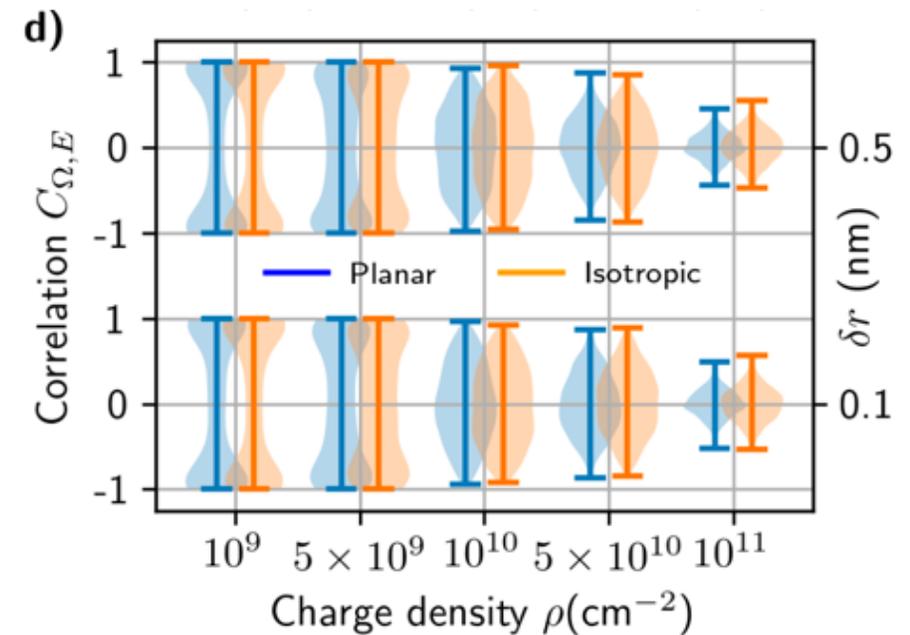
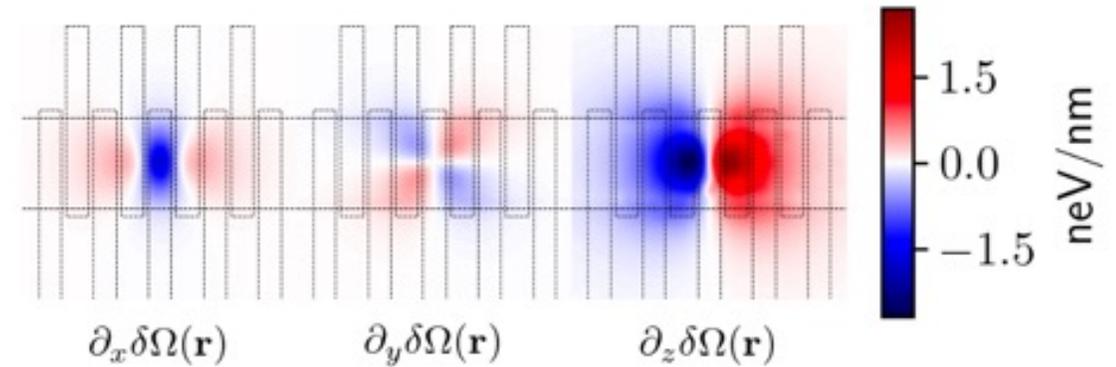
# Orbital noise and spin splitting noise are (spatially) correlated

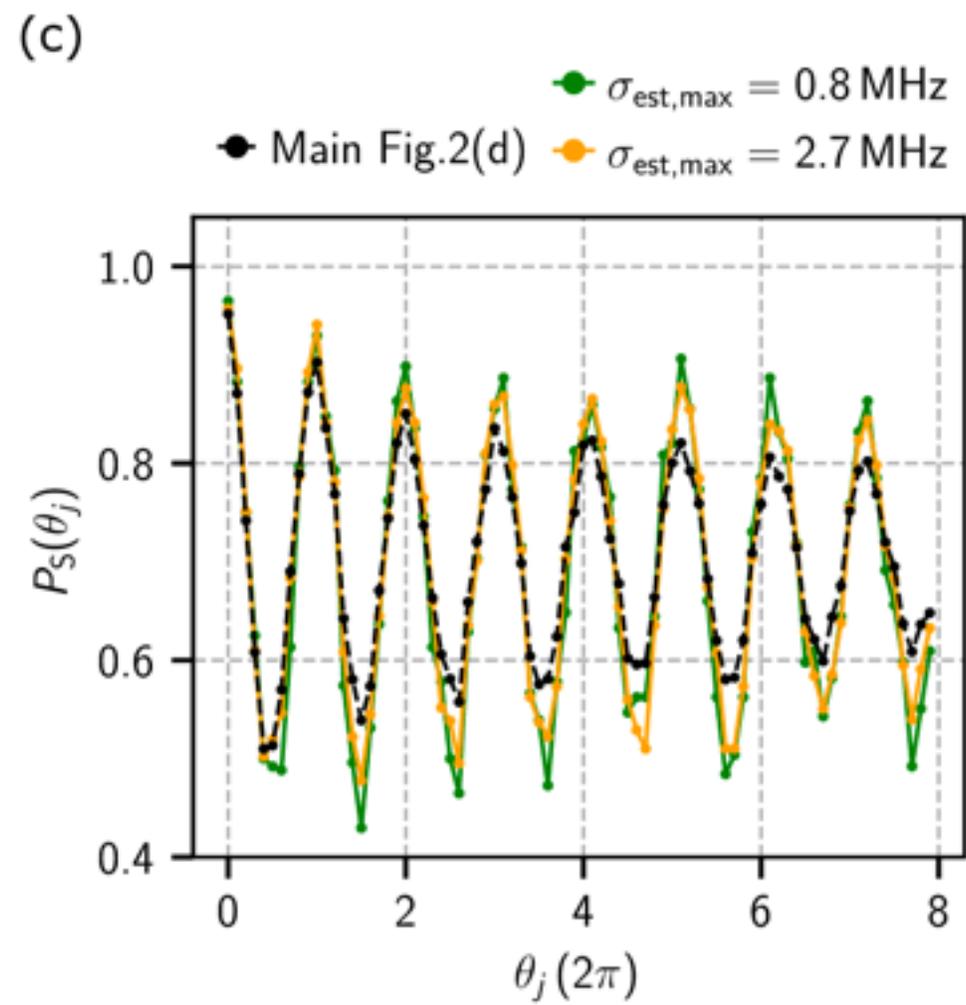
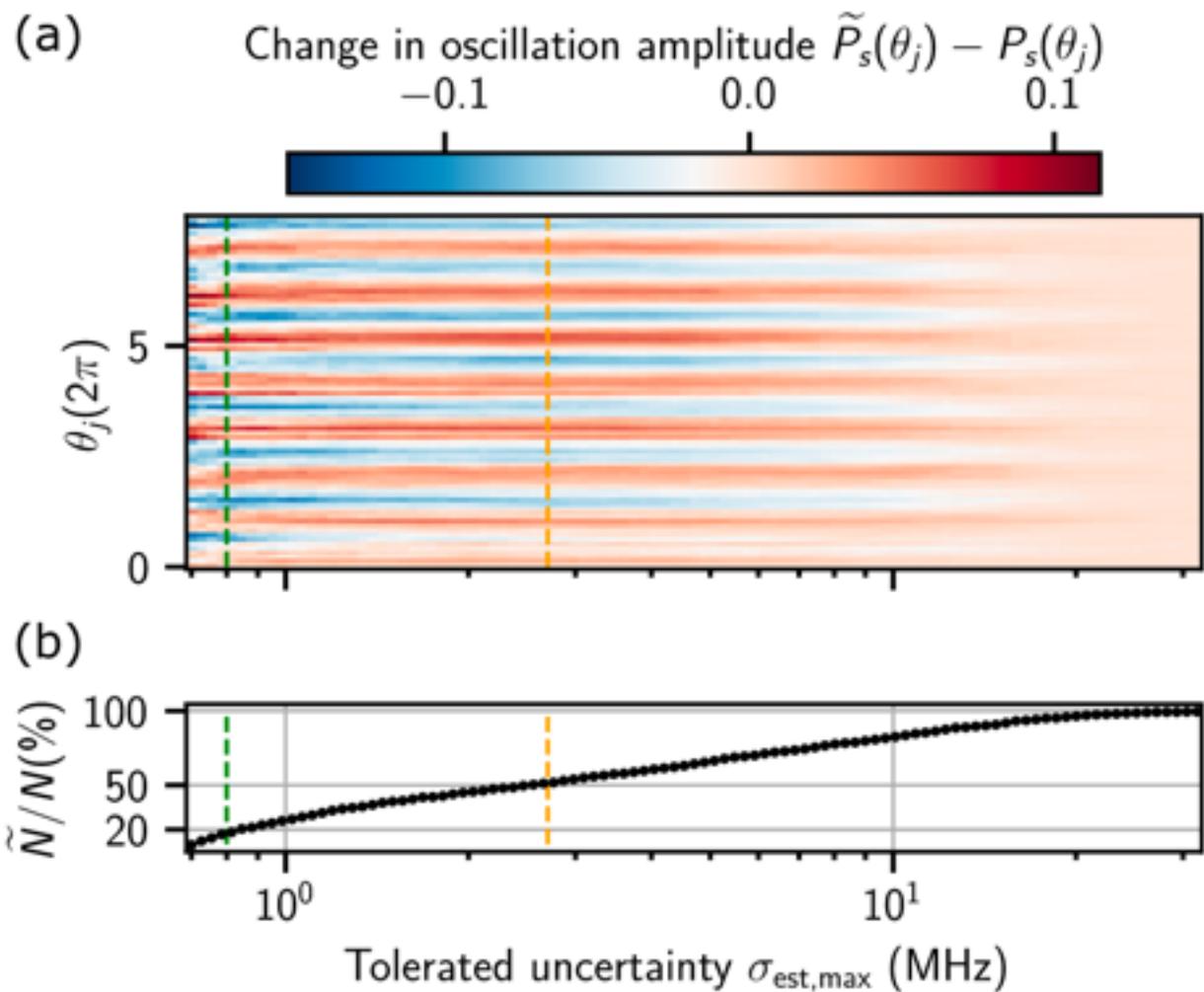
- We found that both orbital noise and spin-splitting noise can lead to spatial correlations

$$\langle \epsilon_L \epsilon_R \rangle \neq 0, \langle \Omega_L \Omega_R \rangle \neq 0$$



- Apart from that non-zero correlations between them is also expected.
- This means that  $\langle \delta \epsilon \delta \Delta B_z \rangle \neq 0$





# Time scales

- Correlation time  $T_c = 1s$
- Relaxation time  $T_1 \approx 1ms$
- Estimation time  $T_{est} = 100\mu s$
- Qubit cycle  $T_{cycle} = 10\mu s$
- Effective dephasing time  $T_2' = 1/MHz = 1\mu s$
- Dephasing time  $T_2^* = 20ns$

$$T_1 = 10^{-3}T_c$$

$$T_{est} = 10^{-4}T_c$$

$$T_{cycle} = 10^{-5}T_c$$

$$T_2' = 10^{-6}T_c$$

$$T_2^* = 10^{-8}T_c$$

Time

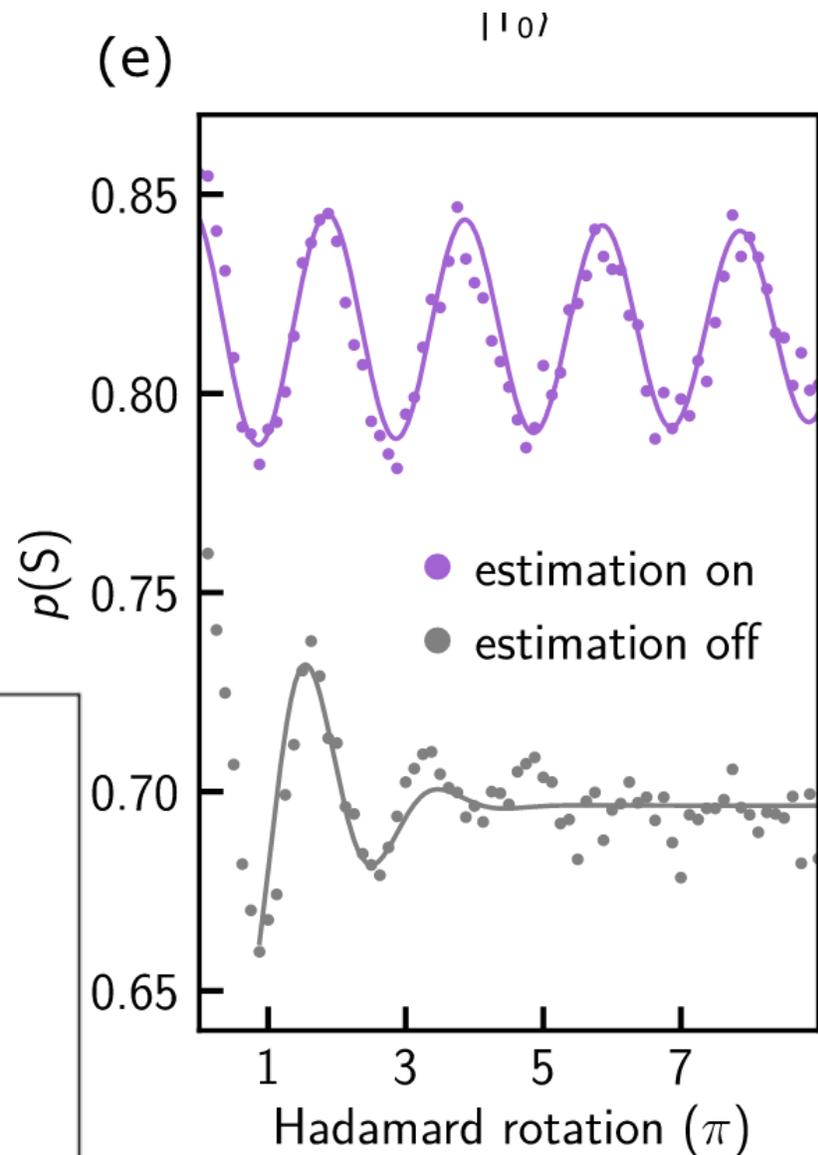
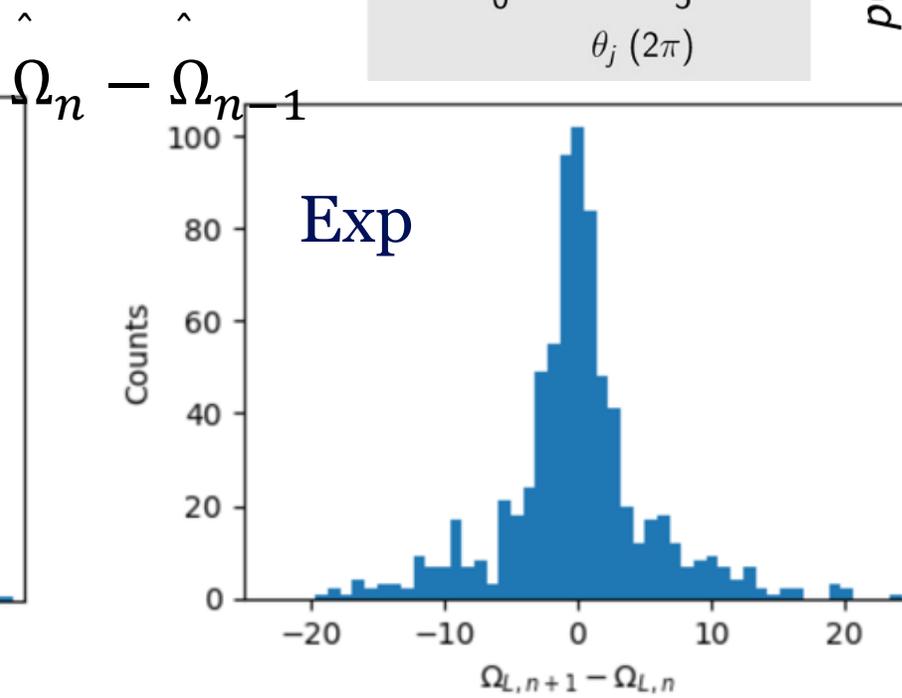
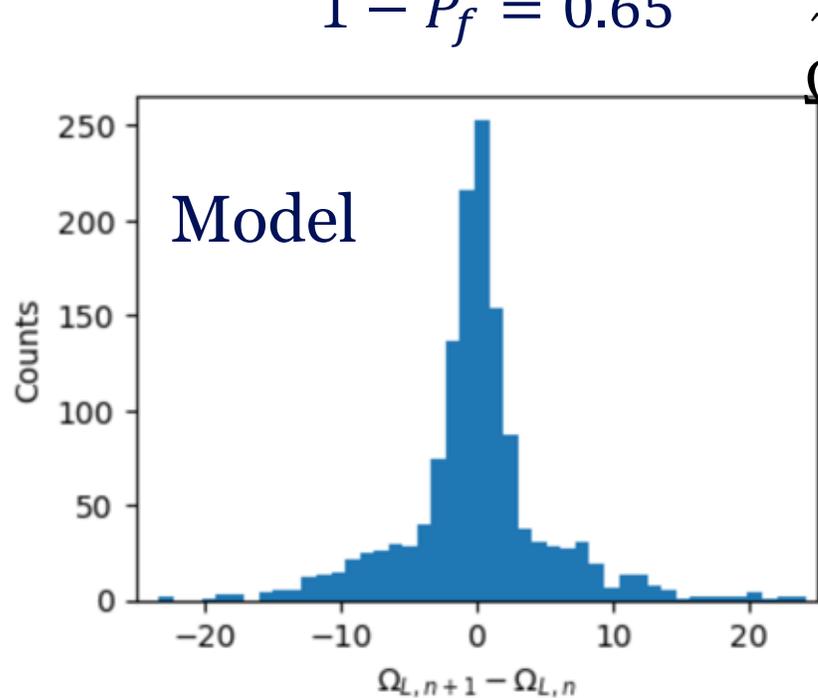
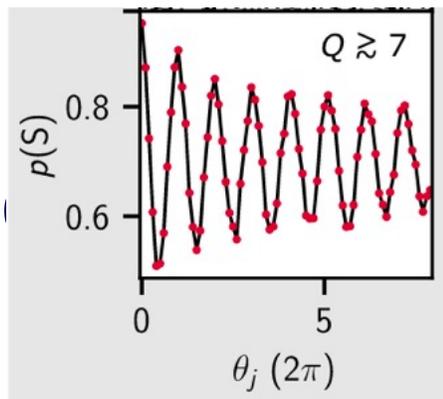
- $10^4$  single shots in  $0.1T_c = 0.1s$ . During this time:
  - 0.1% estimation
  - 10% coherent evolution
  - 90% readout

# Hadamard gate synthetisation

- Stable oscillations are achieved with feedback,
- Lack of contrast due to outliers:

$$\delta\Omega \sim P_f \mathcal{N}(0, \sigma_{out}^2) + (1 - P_f) \mathcal{N}(0, \sigma_{in}^2)$$

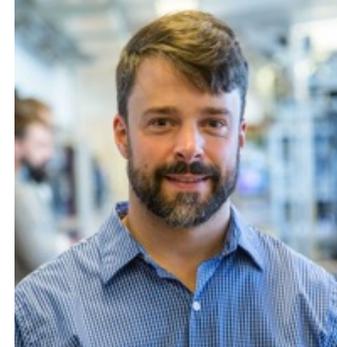
$$1 - P_f = 0.65$$



# Outline (Different outline)



Anasua Chattejee



Ferdinand Kuemmeth



Jeroen Danon



Evert van Nieuwenburg

Experiment (NBI Copenhagen)

Theory (NTNU)

Machine learning (Leiden)

1. Spin qubit Quantum  
Computer

2. Correlated noise

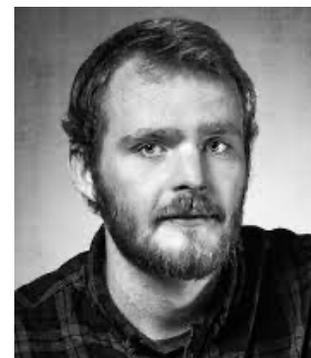
3. Gates driven by noise

4. Perspective and outlook

ConSpiQuOS



Fabrizio Berritta



Torbjørn Raasø  
Rasmussen



Jacob Benestad

Etiuda  
Preludium

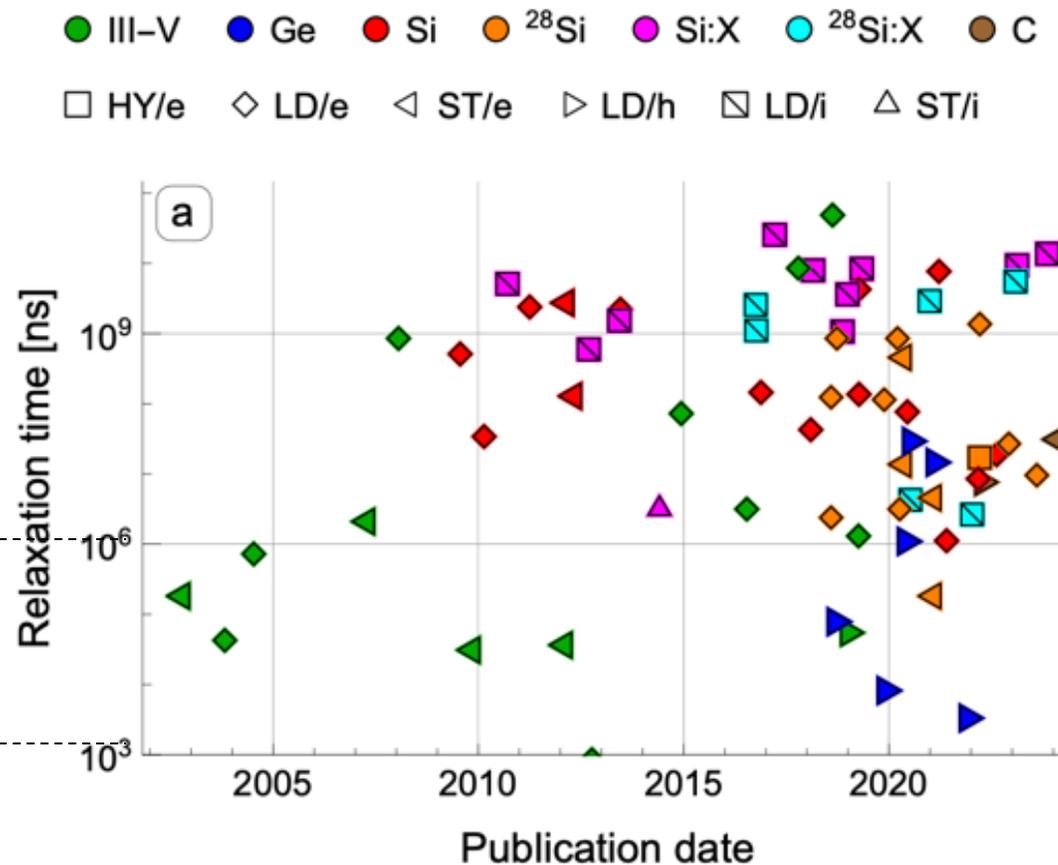
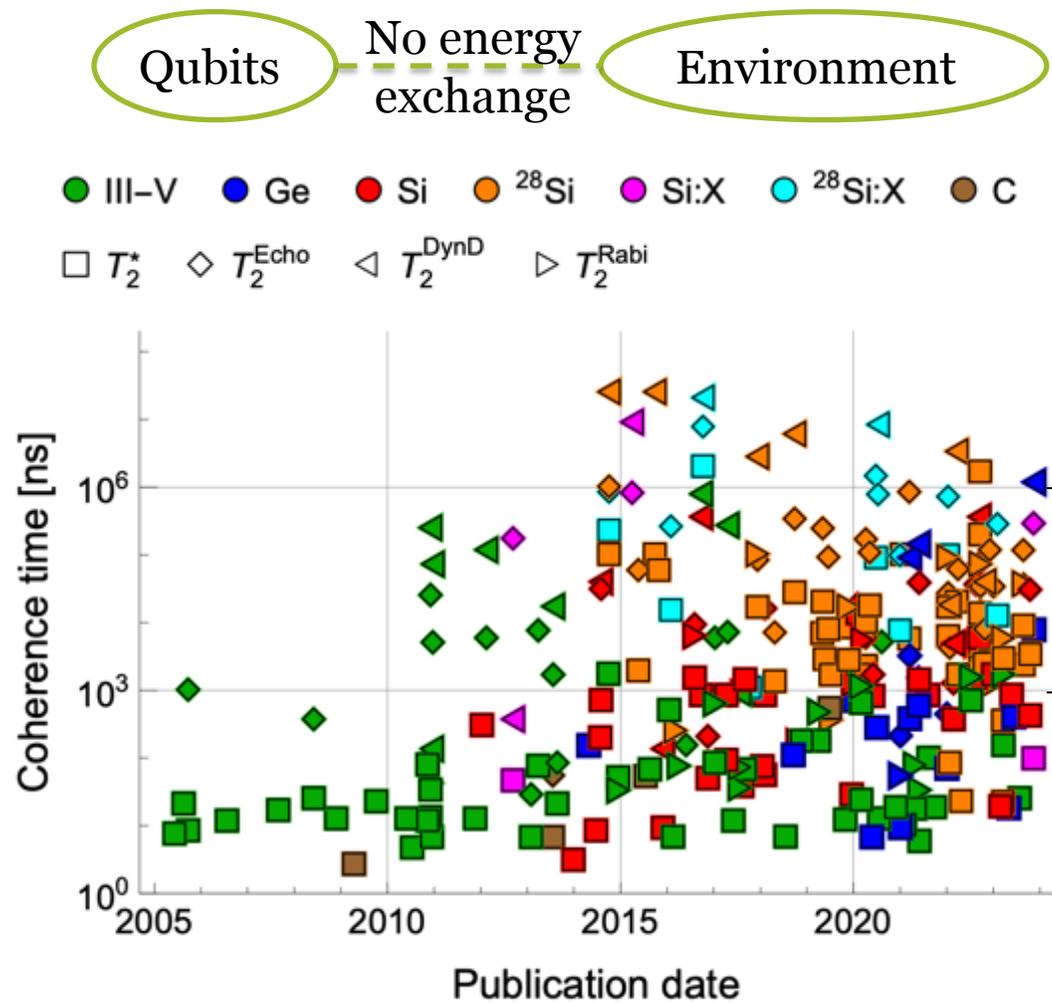


Łukasz Cywiński



Marcin Kępa

# Because the noise is classical...

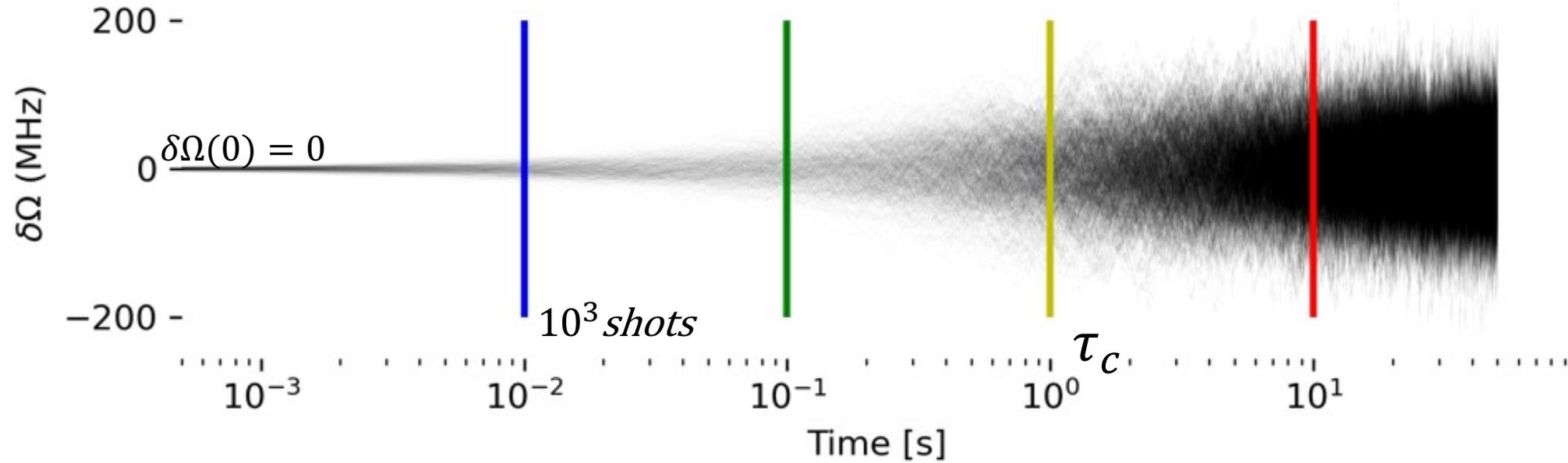


$$T_2 \gg T_1$$

# Example: Nuclear noise

$$\sigma^2(t) = \sigma_f^2 - [\sigma_f^2 - \sigma^2(0)]e^{-2t/\tau_c}$$

$$\mu(t) = \delta\Omega(0)e^{-t/\tau_c}$$



$$\delta W = \frac{1}{2N} \langle\langle \delta\Omega_n^2 \rangle\rangle \tau^2 = \frac{\sigma_f^2 \tau^2}{2} \left(1 - \frac{1}{N} \sum_n e^{-n\Delta t/\tau_c}\right) = \frac{\sigma_f^2 \tau^2}{2} \left(1 - \frac{1 - e^{-N\Delta t/\tau_c}}{e^{\Delta t/\tau_c} - 1}\right)$$