# Five-body systems with Bethe-Salpeter equations

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## With G. Eichmann and M. T. Peña

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G. E. and R. D. Torres, Five-point functions and the permutation group S5, arXiv:2502.17225.
 G. E., M. T. P. and R.D. Torres, Five-body systems with Bethe-Salpeter equations, arXiv:2502.17944.



# **Motivation**



LHCb: Phys. Rev. Lett. 115, 072001 (2015).

Goal Solve the Bethe-Salpeter equation for a system of five scalar particles interacting by a scalar boson exchange, a massive Wick-Cutkosky model.

- We implement properties of the permutation group S<sub>5</sub>
- We extract the ground and excited states along with the spectra of two-, three and four-body equations.
- Our study serves as a building block for the calculation of pentaquark properties using functional methods.

# **Five-body equation**



G.Eichmann, M.T.Peña and R. D. Torres, arXiv:2502.17944.

Starting point The homogeneous Bethe-Salpeter equation for a five body system:

$$\Gamma^{(5)} = K^{(5)} G_0^{(5)} \Gamma^{(5)}$$

(1

 $K^{(5)}$  is the five-body interaction kernel.

is the product of five dressed propagators. is the five-body Bethe-Salpeter amplitude.

 $\Gamma^{(5)}$ 

# **Five-body equation**



The five-body BSE can be derived from the pole behavior of the 5-body scattering matrix  $T^{(5)}$ , which is a ten-point correlation function

$$T^{(5)} = K^{(5)} + K^{(5)} G_0^{(5)} T^{(5)}$$
 (2)

At a given bound-state or resonance pole with mass M,

$$T^{(5)} \longrightarrow \frac{\Gamma^{(5)}\overline{\Gamma}^{(5)}}{P^2 + M^2},$$
 (3)

# **Subtraction diagrams**



A naive summation of two body kernels leads to overcounting. Phys. Lett. B 718, 545 (2012).

In a five-body system there are ten possible two-body kernels

$$K_a \in \{K_{12}, K_{13}, K_{14}, K_{15}, K_{23}, K_{24}, K_{25}, K_{34}, K_{45}\},$$
(4)

and 15 independent double-kernel

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K_{a}K_{b} \in \{K_{12}K_{34}, K_{12}K_{35}, K_{12}K_{45}, K_{13}K_{24}, K_{13}K_{25}, K_{13}K_{45}, K_{14}K_{23}, K_{14}K_{25}, K_{14}K_{35}, K_{15}K_{23}, K_{15}K_{24}, K_{15}K_{34}, (5) K_{23}K_{45}, K_{24}K_{35}, K_{25}K_{34}\}.
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# Explicit form of the BSE



The BSE depends on five momenta  $p_1, \dots p_5$ , whose sum is the total onshell momentum P with  $P^2 = -M^2$ .

$$\Gamma(\{p_i\}) = \sum_{a}^{10} \Gamma_{(a)}(\{p_i\}) - \sum_{a \neq b}^{15} \Gamma_{(a,b)}(\{p_i\})$$
(6)

$$\Gamma_{(a)}(\{p_i\}) = \int \frac{d^4r}{(2\pi)^4} K(p_{a_1}, q_{a_1}, p_{a_2}, q_{a_2})$$
  
×  $D(q_{a_1})D(q_{a_2})\Gamma(\{p_i\}, a),$   
 $\Gamma_{(a,b,)}(\{p_i\}) = \int \frac{d^4r}{(2\pi)^4} K(p_{a_1}, q_{a_1}, p_{a_2}, q_{a_2})$   
×  $D(q_{a_1})D(q_{a_2})\Gamma_{(b)}(\{p_i\}, a).$ 

# Lorentz invariants



In practice we work with the total momentum P and four relative momenta p,q,k,l instead of the five particle momenta.

$$q = \frac{p_1 - p_5}{2}, \quad p = \frac{p_2 - p_5}{2}, \quad k = \frac{p_3 - p_5}{2}, \quad l = \frac{p_4 - p_5}{2}.$$
(7)

The amplitude  $\Gamma(q, p, k, l, P)$  depends on 15 Lorentz invariants

$$\begin{array}{ll}
q^{2}, & \omega_{1} = q \cdot p, \\
p^{2}, & \omega_{2} = q \cdot k, & \eta_{1} = q \cdot P, \\
p^{2}, & \omega_{3} = q \cdot l, & \eta_{2} = p \cdot P, \\
k^{2}, & \omega_{4} = p \cdot k, & \eta_{3} = k \cdot P, \\
l^{2}, & \omega_{5} = p \cdot l, & \eta_{4} = l \cdot P. \\
P^{2}, & \omega_{6} = k \cdot l,
\end{array}$$
(8)

These can be arranged into two singlets, two quartets and a quintet in  $S_5$ .

## **Permutation Group** S<sub>5</sub>



 $S_5$  consist of 5! = 120 elements and each permutation of an object  $f_{12345}$  can be reconstructed from two group elements, a transposition T and a 5 - cycle C.

G.E. and R. D. T., arXiv:2502.17225.

The Cayley graph can be visualized by 24 pentagons, which are connected to each other by transpositions. The members are obtained by two successive chains of the form (C<sup>2</sup>, T<sup>2</sup>, C<sup>2</sup>, T, CT, T).

## **Permutation Group** S<sub>5</sub>



For later use, we collect the elements in the first five squares (A, B, C, D, E) into five vectors  $f^{(n)}$  with  $n = 1, \dots, 5$ . Together with the transpositions  $Tf^{(n)}$ , this yields twelve elements for each vector.

The remaining five squares (F, G, H, I, J) define the vectors  $\tilde{f}^{(n)}$  with  $n = 1, \dots, 5$ . Again, combined with the transpositions  $T\tilde{f}^{(n)}$ , each vector  $\tilde{f}^{(n)}$  defines a closed path with twelve elements.

# **Permutation Group** S<sub>5</sub>



The 120 permutations transform under irreducible representations of  $S_5$  and are given by Young diagrams of  $S_5$ .

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# Permutation Group $S_5$ and five-body systems

One singlet is  $P^2$  and the other

$$S_0 = \frac{1}{5} \left( q^2 + p^2 + k^2 + l^2 - \frac{1}{2} \sum_{i=1}^6 \omega_i \right).$$
(10)

The quintet is given by

$$\mathcal{V} = \begin{bmatrix} \sqrt{\frac{2}{3}} (\omega_1 + \omega_2 - \omega_3 + \omega_4 - \omega_5 - \omega_6) \\ 2\omega_1 - \omega_2 - \omega_3 - \omega_4 - \omega_5 + 2\omega_6 \\ \sqrt{3} (\omega_2 - \omega_3 - \omega_4 + \omega_5) \\ \omega_2 + \omega_3 - \omega_4 - \omega_5 \\ \frac{1}{\sqrt{3}} (2\omega_1 - \omega_2 + \omega_3 - \omega_4 + \omega_5 - 2\omega_6) \end{bmatrix}$$

The two quartets are given by

$$Q_{1} = \begin{bmatrix} q^{2} - p^{2} - \frac{2}{3}v_{4} \\ \frac{1}{\sqrt{3}}(q^{2} + p^{2} - 2k^{2}) - \frac{2}{3}v_{5} \\ \frac{1}{\sqrt{6}}(q^{2} + p^{2} + k^{2} - 3l^{2}) - \frac{2}{3}v_{1} \\ -\frac{1}{\sqrt{10}}\frac{5}{3}(q^{2} + p^{2} + k^{2} + l^{2} - 8S_{0}) \end{bmatrix},$$

$$Q_{2} = \begin{bmatrix} \eta_{1} - \eta_{2} \\ \frac{1}{\sqrt{3}}(\eta_{1} + \eta_{2} - 2\eta_{3}) \\ \frac{1}{\sqrt{6}}(\eta_{1} + \eta_{2} + \eta_{3} - 3\eta_{4}) \\ \frac{1}{\sqrt{10}}(\eta_{1} + \eta_{2} + \eta_{3} + \eta_{4}) \end{bmatrix},$$
(11)

# Permutation Group $S_n$ and n-body systems

n	$\mathcal{S}_0$	$P^2$	$\eta_i$	$p_1^2 \dots p_n^2$	$\mathcal{M}$	Total	Indep.
2	1	1	1	_	_	3	3
3	1	1	2	2	_	6	6
4	1	1	3	3	2	10	10
5	1	1	4	4	5	15	14
6	1	1	5	5	9	21	18
n	1	1	n-1	n-1	n(n-3)/2	n(n+1)/2	4n - 6

•  $P^2$  is a singlet, and one singlet as the sum  $p_1^2 + \cdots + p_n^2$ .

- The variables  $p_1^2 \cdots p_n^2$  form another  $(n p_n)$ 1)-plet.
- n-1 angular variables  $\eta_i$  form an  $(n \bullet n(n-3)/2$  gives another multiplet  $\mathcal{M}$ . 1)-plet.

# Five-body system - dimensional constraint

$$P = \begin{bmatrix} 0\\0\\0\\\bullet\end{bmatrix}, q = \begin{bmatrix} 0\\0\\\bullet\\\bullet\end{bmatrix}, p = \begin{bmatrix} 0\\\bullet\\\bullet\\\bullet\\\bullet\end{bmatrix}, k = \begin{bmatrix} \bullet\\\bullet\\\bullet\\\bullet\\\bullet\end{bmatrix}, l = \begin{bmatrix} \bullet\\\bullet\\\bullet\\\bullet\\\bullet\end{bmatrix}, (12)$$

- $\bullet~n$  four-vectors depend on 4n-6 independent variables.
- $\bullet$  The five vectors only have 14 independent entries and thus only 14 independent Lorentz invariants.
- n-body system with  $n \ge 5$  independent four-momenta gives 4n - 6 independent Lorentz invariants (opposed to n(n+1)/2).

- In n = 5 yields one constraint equation.
- The constraint relates all variables.

$$\begin{bmatrix} (\omega_{12} \ \omega_{34} + \omega_{13} \ \omega_{24} + \omega_{14} \ \omega_{23})^2 - q_1^2 \ q_2^2 \ q_3^2 \ q_4^2 \end{bmatrix} P^2 + \sum_i \eta_i^2 \begin{bmatrix} q_j^2 \ q_k^2 \ q_l^2 - q_j^2 \ \omega_{kl}^2 - q_k^2 \ \omega_{jl}^2 - q_l^2 \ \omega_{jk}^2 \end{bmatrix} + 2 \sum_i \left( \eta_i^2 - q_i^2 \ P^2 \right) \omega_{jk} \ \omega_{jl} \ \omega_{kl} + \sum_{i < j} \eta_i \ \eta_j \begin{bmatrix} 2q_k^2 \ (\omega_{il} \ \omega_{jl} - q_l^2 \ \omega_{ij}) + q_l^2 \ \omega_{ik} \ \omega_{jk} \\ + \ \omega_{kl} \ (\omega_{ij} \ \omega_{kl} - \omega_{ik} \ \omega_{jl} - \omega_{il} \ \omega_{jk}) \end{bmatrix}$$
(13)  
$$+ P^2 \sum_{i < j} \omega_{ij}^2 \ \left( q_k^2 \ q_l^2 - \omega_{kl}^2 \right) = 0 ,$$

# Explicit form of the BSE



- Solutions of two-, three- and four-body systems show that the dependence on the angular variables  $\eta_i$  is usually small or negligible.
- Four-body BSE dynamically generates intermediate two-body poles in the solution process.
- $\bullet$  In a five body there are 10 possible two- and three-body configurations.

We reduce the momentum dependence to  $S_0$  but include two- and three-body poles:

$$\Gamma(p,q,k,l,P) \approx f(\mathcal{S}_0) \sum_{aa'} \mathcal{P}_{aa'},$$
 (14)

## with

$$\mathcal{P}_{(12)(345)} = \frac{1}{(p_1 + p_2)^2 + M_M^2} \frac{1}{(p_3 + p_4 + p_5)^2 + M_B^2} \,.$$

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# **Explicit form of the BSE**



- Procedure requires knowledge of boundstate masses  $M_M$ ,  $M_B$  of the two- and three-body equations in the same approach.
- We employ a dimensionless coupling constant c and mass ratio  $\beta$  via:

$$c = \frac{g^2}{(4\pi m)^2}, \quad \beta = \frac{\mu}{m}$$
 (15)

• Employing tree-level propagators for scalar particles with mass m and a ladder approximation for a boson exchange with mass  $\mu$ :

$$K(p_{a_1}, q_{a_1}, p_{a_2}, q_{a_2}) = \frac{g^2}{r^2 + \mu^2},$$
  

$$D(p) = \frac{1}{p^2 + m^2},$$
(16)

# **Explicit form of the BSEs**

The BSEs turn into eigenvalue equations of the form

$$\lambda_i(P^2)\Psi_i(P^2) = \mathcal{K}(P^2)\Psi_i(P^2),$$
 (17)

where  $P^2 \in \mathbb{C}$  is the five-body momentum squared,  $\mathcal{K}(P^2)$  is the kernel and the  $\Psi_i(P^2)$  are its eigenvectors with eigenvalues  $\lambda_i(P^2)$  for the ground (i = 0) and excited states (i > 0).

$$\Gamma(\{p_i\}) = \sum_{a}^{6} \Gamma_{(a)}(\{p_i\}) - \sum_{a \neq b}^{3} \Gamma_{(a,b)}(\{p_i\}).$$

$$(18)$$

# **Results**



n-body BSEs for  $\beta = 4$  and different values of coupling c.



Coupling ranges where n-body ground states are possible for different values of  $\beta$ .

# **Results**



Radially excited state masses  $M_{i>0}$  for  $\beta = 4$  and different values of the coupling c.



Eigenvalues of the *n*-body BSEs  $\beta = c = 0.5$ . Solid curves are full solutions, dotted singlet approx. and dashed singles  $\times$  pole approx.

# **Results**



BSE eigenvalues for  $\beta = 0.001$ , with c = 1/4 to ensure coexisting solutions for the two-, three-, four- and five-body BSEs.

# **Results - extra applications with** $S_5$ for five-point functions

 $p_{2}$   $p_{3}$   $p_{4}$   $p_{5}$   $p_{5$ 



• Five-point function depends on five incoming momenta with the sum  $p_1^{\mu} + \cdots + p_5^{\mu} = 0$ . Singlet vanishes and remaining four independent momenta form a quartet:

$$\mathcal{Q} = \begin{bmatrix} p_1^{\mu} - p_2^{\mu} \\ \frac{1}{\sqrt{3}} (p_1^{\mu} + p_2^{\mu} - 2p_3^{\mu}) \\ \frac{1}{\sqrt{6}} (p_1^{\mu} + p_2^{\mu} + p_3^{\mu} - 3p_4^{\mu}) \\ \frac{1}{\sqrt{10}} (p_1^{\mu} + p_2^{\mu} + p_3^{\mu} + p_4^{\mu} - 4p_5^{\mu}) \end{bmatrix} = \begin{bmatrix} p^{\mu} \\ q^{\mu} \\ k^{\mu} \\ l^{\mu} \end{bmatrix}.$$
(19)

• One obtains a singlet  $Q \cdot Q$ , a quartet  $Q \wedge Q$ , a quintet  $Q \cup Q$  and a sextet  $Q \star Q$ .

• Five-point functions can define ten Mandelstam variables

$$s_{ij} = (p_i + p_j)^2, \quad X = \frac{\sqrt{3}(s_{ik} - s_{jk})}{s_{ik} + s_{jk} + s_{ij}}, \quad Y = \frac{s_{ik} + s_{jk} - 2s_{ij}}{s_{ik} + s_{jk} + s_{ij}}$$

Intermediate resonances appear at fixed  $s_{ij}$ .

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# **Results - extra applications with** $S_5$ for five-point functions

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• Five-gluon vertex general form reads

$$\Gamma^{\mu\nu\alpha\beta\gamma}(p_1\dots p_5) = \sum_{ij} F_{ij}(\dots) \,\tau_i^{\mu\nu\alpha\beta\gamma} \,\mathsf{c}_{abcde}^{(j)} \,. \tag{20}$$





There are four types of color structures as seed elements

$$\begin{aligned} \delta_{ab} f_{cde} , & f_{abr} f_{cds} f_{ers} , & f_{ij} &= \delta_{ij} f_{klm} , \\ \delta_{ab} d_{cde} , & f_{abr} f_{cds} d_{ers} . & d_{ij} &= \delta_{ij} d_{klm} , \end{aligned}$$

$$\begin{aligned} & k < l < m , \\ \end{aligned}$$

- Ten permutations of  $d_{ii}$  can be grouped into a singlet, a quartet and a quintent.
- Ten of  $f_{ii}$  return an antiquartet and a sextet.
- The seed  $f_{abr} f_{cds} f_{ers}$  form a sextet.
- The seed  $f_{abr} f_{cds} d_{ers}$  yields an antisinglet and an antiquartet.

# Summary



• We developed the five-body Bethe-Salpeter formalism and solve the five-body equation for a scalar model in a ladder truncation.

• We discussed applications of the permutation group  $S_5$  for five-point functions and five-body wave functions.

• The approach developed in this work can be extended to QCD in view of investigating pentaquarks, and work in this direction is underway.

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# **Backup slides - Three-body equation**



The Bethe-Salpeter amplitude  $\Gamma(\{p_i\})$  for a three-body system depends on three momenta  $p_1, p_2, p_3$ , whose sum is the total onshell momentum P with  $P^2 = -M_B^2$ .

$$\Gamma(\{p_i\}) = \sum_{a}^{3} \Gamma_{(a)}(\{p_i\}) .$$

$$\Gamma_{(a)}(\{p_i\}) = \int \frac{d^4r}{(2\pi)^4} K(p_{a_1}, q_{a_1}, p_{a_2}, q_{a_2}) D(q_{a_1}) D(q_{a_2}) \Gamma(\{p_i\}, a) .$$
(22)

In this care the are three possible two-body kernels  $K_a \in \{K_{12}, K_{13}, K_{23}\}$  whose sum does not lead top overcounting in the three-body scattering matrix kernel  $T^{(3)}$ .

# **Backup slides - Three-body equation**



We furthermore employ a single  $\times$  pole approximation

$$\Gamma(q, p, P) \approx f(\mathcal{S}_0) \sum_a \mathcal{P}_a, \qquad \mathcal{P}_{12} = \frac{1}{(p_1 + p_2)^2 + M_M^2},$$
(23)

with  $M_M$  the mass of the two-body subsystem or 'diquark', and the singlet variable  $S_0$  is

$$S_0 = \frac{q^2}{3} + \frac{p^2}{4}.$$
 (24)

# **Backup slides - Four-body equation**



In this case there are six possible two-body kernels

$$K_a \in \{K_{12}, K_{13}, K_{14}, K_{23}, K_{24}, K_{34}\}$$
(25)

and three independent double-kernel configurations of the form

$$K_a K_b \in \{K_{12} K_{34}, K_{13} K_{24}, K_{14} K_{23}\}.$$
(26)

The four-body Bethe-Salpeter amplitude  $\Gamma(\{p_i\})$  depends on four-momenta  $p_1 \dots p_4$ , whose sum is the total onshell momentum P with  $P^2 = -M_T^2$  (T for 'tetra').

# **Backup slides - Four-body equation**



The four-body equation is the Faddeev-Yakubowsku equation and can be written as

$$\Gamma(\{p_i\}) = \sum_{a}^{6} \Gamma_{(a)}(\{p_i\}) - \sum_{a \neq b}^{3} \Gamma_{(a,b)}(\{p_i\}),$$

$$\Gamma_{(a)}(\{p_i\}) = \int \frac{d^4r}{(2\pi)^4} K(p_{a_1}, q_{a_1}, p_{a_2}, q_{a_2}) D(q_{a_1}) D(q_{a_2}) \Gamma(\{p_i\}, a),$$

$$\Gamma_{(a,b)}(\{p_i\}) = \int \frac{d^4r}{(2\pi)^4} K(p_{a_1}, q_{a_1}, p_{a_2}, q_{a_2}) D(q_{a_1}) D(q_{a_2}) \Gamma_{(b)}(\{p_i\}, a),$$
(27)

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# **Backup slides - Four-body equation**



In the four-body case we employ the singlet  $\times$  pole approximation

$$\Gamma(q, p, k, P) \approx f(\mathcal{S}_0) \sum_{a} \mathcal{P}_{aa'}, \qquad (28)$$

where the two-body poles for aa' = (12)(34) are given by

$$\mathcal{P}_{(12)(34)} = \frac{1}{(p_1 + p_2)^2 + M_M^2} \frac{1}{(p_3 + p_4)^2 + M_M^2}$$
(29)

and  $M_M$  is the mass of the two-body subsystem. The singlet variable  $S_0$  is

$$S_0 = \frac{k^2 + q^2 + p^2}{4}.$$
(30)

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