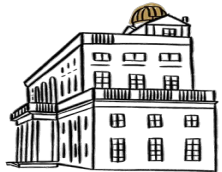


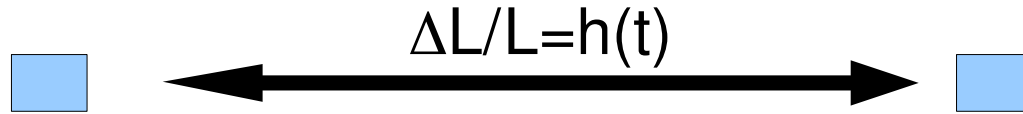
From black holes at the edge of the
Universe to observatories
underground:
the gravitational wave detection tale

Tomasz Bulik



**OBSERVATORIUM
ASTRONOMICZNE
UNIWERSYTETU
WARSZAWSKIEGO**

Basics



- The waves affect free floating bodies
- Space is curved
- There is no global flat coordinate system

Physical basics

- Spacetime oscillations
- Measurement with light



- Curvature – tensor of 4th order: R

Physical basics

- Transverse wave
- Distortions of perpendicular geometry
- Symmetry to rotation by 180 deg
- For the EM case – 360 deg
- Photon spin =1, graviton =2
- Two polarizations: EM 90 deg; GW 45deg

Multipole expansion

- Waves - amplitude goes as $1/r$
- Oscillating masses
- Multipole moments – mass, momentum
- Dimensional analysis
- Mass quadrupole moment
- Momentum quadrupole moment

The waves

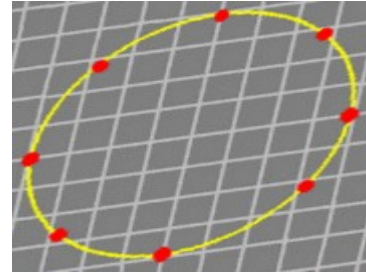
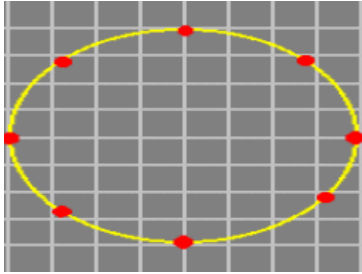
- Source: mass M , size L , period P
- Quadrupole moment ML^2

$$h = (G/c^4)(ML^2/P^2)/r$$

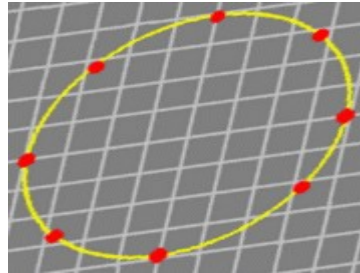
- Newtonian potential of the kinetic energy
- Higher moments – factors of (v/c)
- Maximally:
$$h \approx \frac{R_g}{D} \left(\frac{v}{c}\right)^2$$

Gravitational wave

Linear polarization

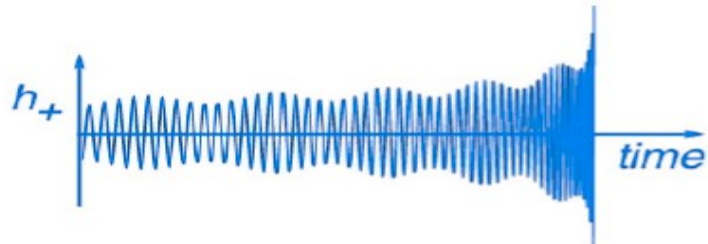
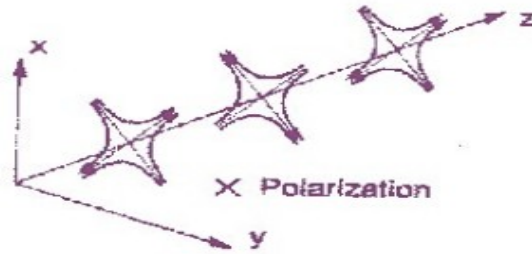
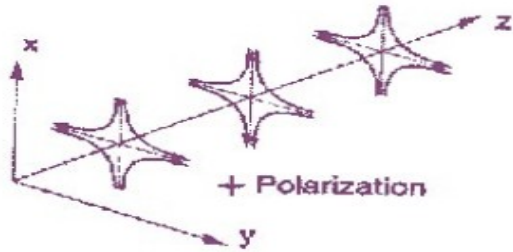


Circular polarization



Basics

- Two independent polarisations

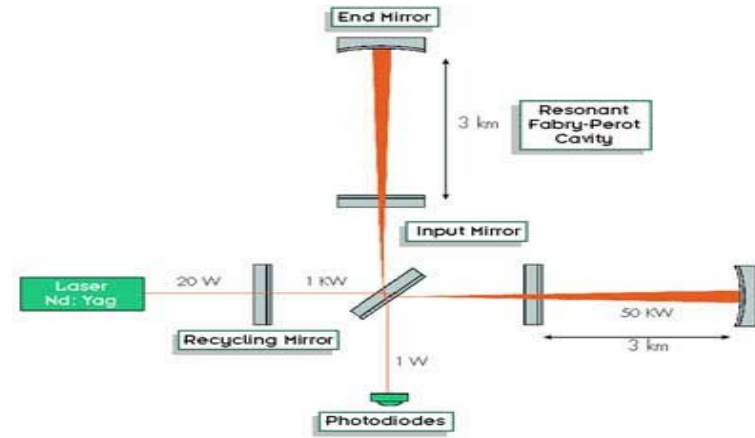


Wave propagation

- High frequency waves (wavelength smaller than curvature radius move along straight (geodesic) lines –geometrical optics
- Zero mass of graviton
- Redshift
- If wavelength comparable to curvature - scattering
- Dispersion: Negligible- less than one wavelength in propagation through the Universe

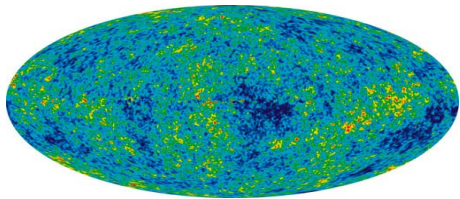
Spectrum

- 20 orders of magnitude
- Basics 4 ranges:
 - ELF $\log f = -16$ do -10
 - VLF $\log f = -10$ do -6
 - LF $\log f = -6$ do 0
 - HF $\log f = 0$ do 6



Cosmic observatories
LISA

Background
radiation



Pulsar timing



Interferometers

Resonant
detectors

-16

-8

0

8

log f

Sources

ELF

VLF

LF

HF

Big bang - inflation

Early Universe, strings, walls, phase transitions

Massive BH
 $M > 1000000 M_{\text{sun}}$
Galaxy formation

Small BH
Neutron stars
Supernovae

Basic wave generation

Look for perpendicular part

$$I_{jk} = \sum_A m_A (x_j^A x_k^A - \frac{1}{3} \delta_{jk} x_m^A x_m^A)$$

$$P_{ij} = \delta_{ij} - n_i n_j$$

$$I_{jk}^{TT} = P_{jk} P_{km} I_{lm} - \frac{1}{2} P_{jk} (P_{lm} I_{lm})$$

$$h_{jk}^{TT}(t, \vec{x}) = \frac{2}{r} \frac{G}{c^4} \ddot{I}_{jk}^{TT}(t - \frac{r}{c})$$

Expected amplitude

$$R_g = 2 \frac{GM}{c^2}$$

Gravitational radius

$$h \approx \frac{R_g}{D} \frac{v^2}{c^2}$$

For a fiducial source: two 30 solar mass black holes at 100Mpc

$$h \approx \frac{R_g}{D} \frac{v^2}{c^2} \approx 2 \times 10^{-21}$$

Energy and angular momentum

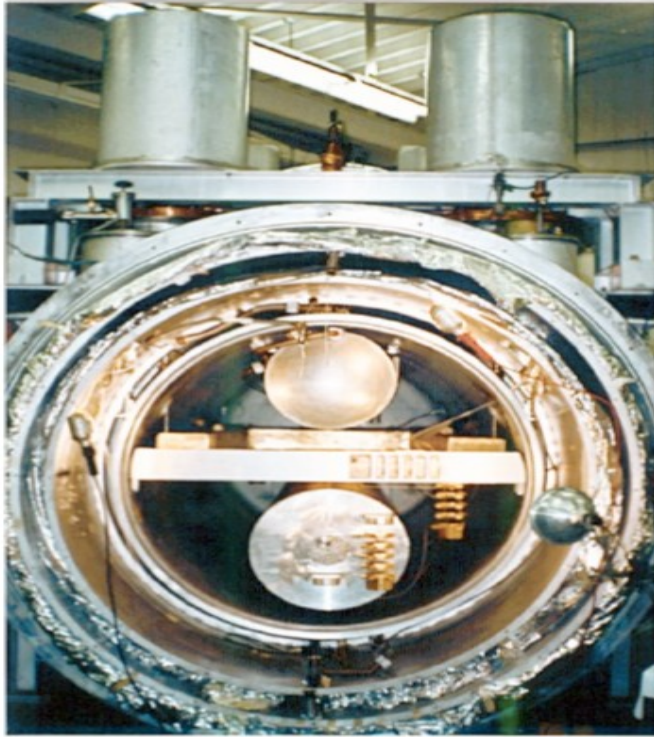
$$L_{GW} = \frac{1}{5} \frac{G}{c^5} \frac{d^3 I_{jk}}{dt^3} \frac{d^3 I_{jk}}{dt^3}$$

$$\frac{dJ_i}{dt} = -\frac{2}{5} \frac{G}{c^5} \epsilon_{ijk} \frac{d^2 I_{jm}}{dt^2} \frac{d^3 I_{km}}{dt^3}$$

Detection

- Test masses
- Measuring distances
- Need a network of detectors

First attempts: resonant detectors



Louisiana State U. - Allegro



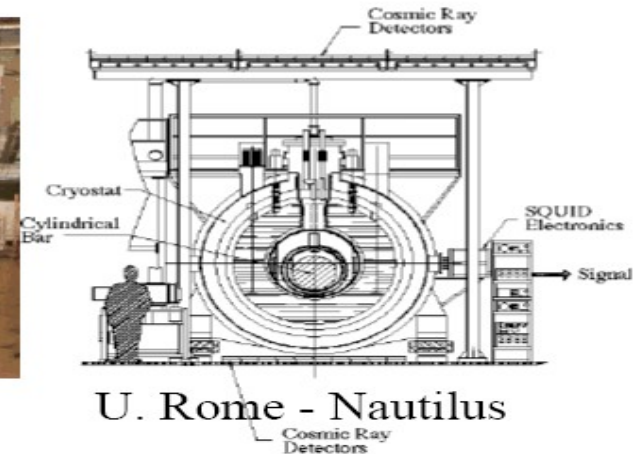
U. West Australia - Niobe



U. Padova - Auriga

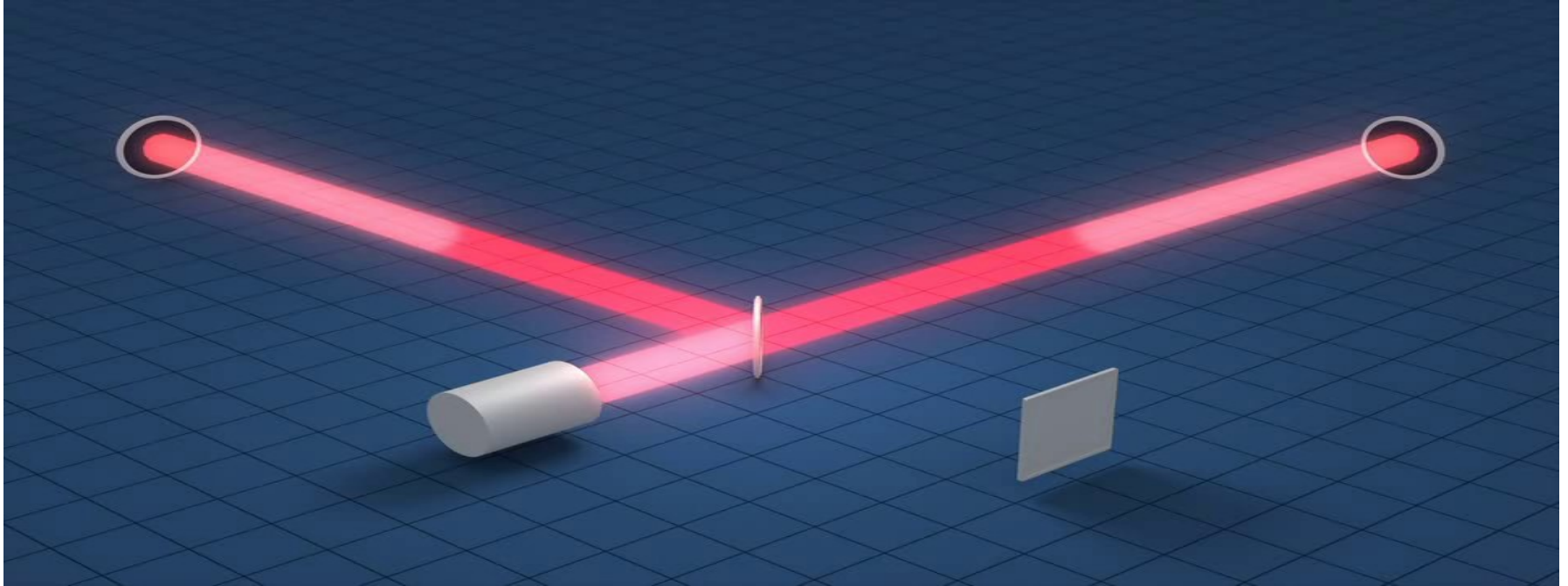


CERN - Explorer

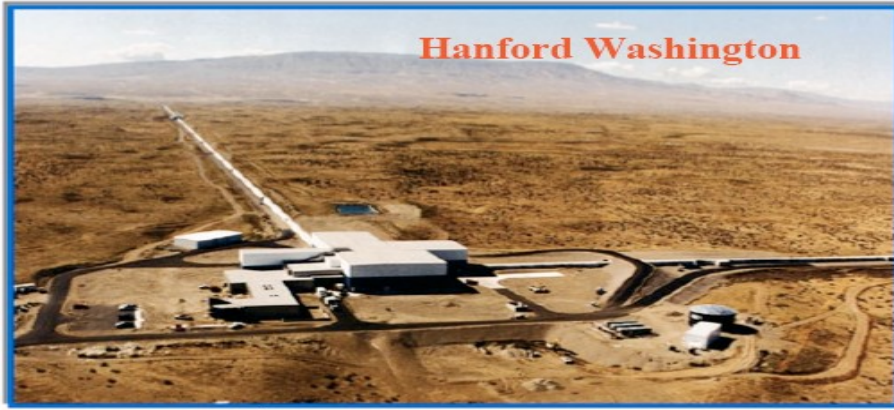


U. Rome - Nautilus

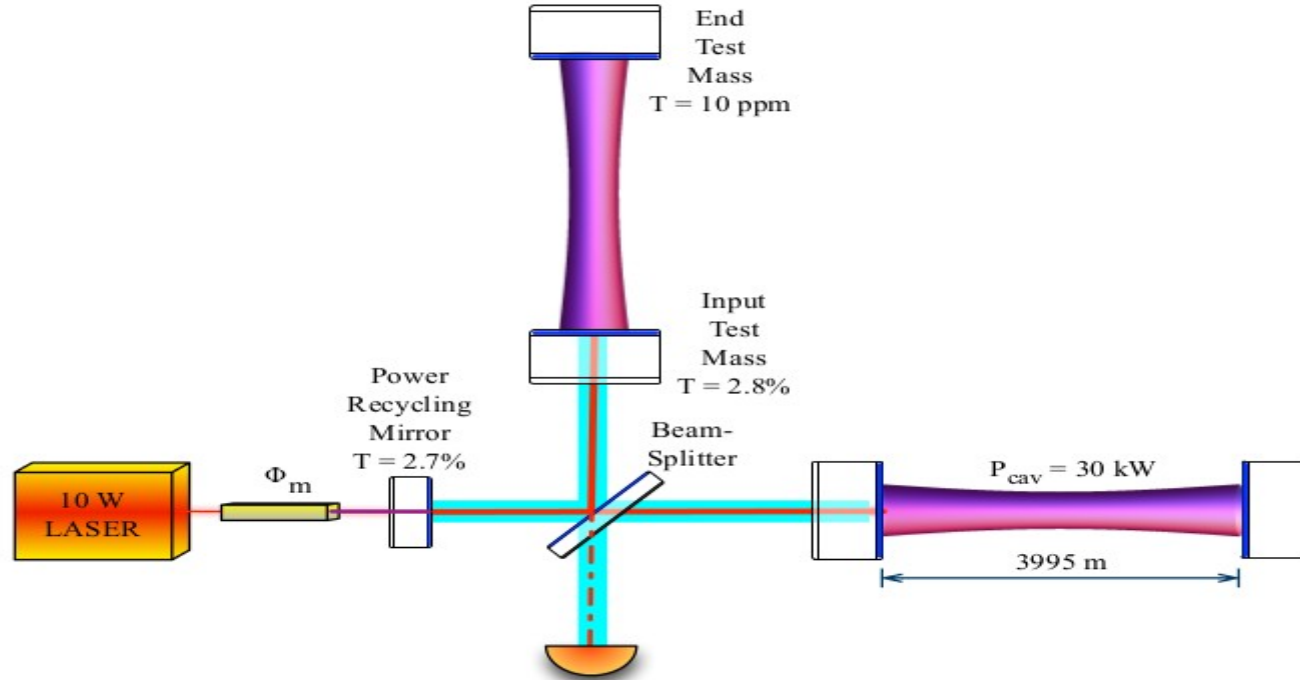
Interferometers



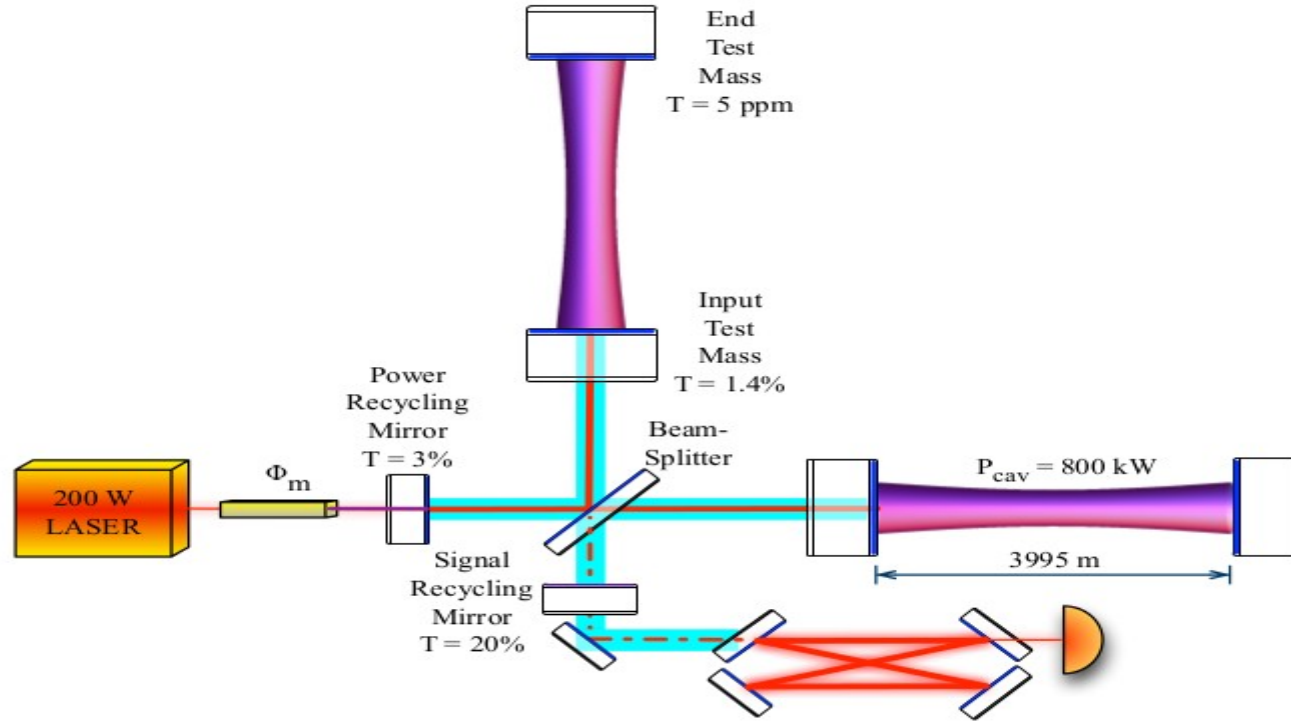
Interferometers - HF



Interferometers: initial



Second generation interferometers



Noise reduction

- Seismic noise quenched by 10 orders of magnitude
- Thermal noise – heavy mass, smart coating
- Quantum shot noise - laser power increase – about 100kW in the cavity
- But – note – fundamental quantum limit:
 - Low vs. high frequency

Order of magnitude estimates

$$\Delta L \approx 10^{-18} \text{m}$$

500 round trips, expected delay:

$$\Delta L_{eff} = 500 \times 10^{-18} \text{m} \approx 5 \times 10^{-16} \text{m}$$

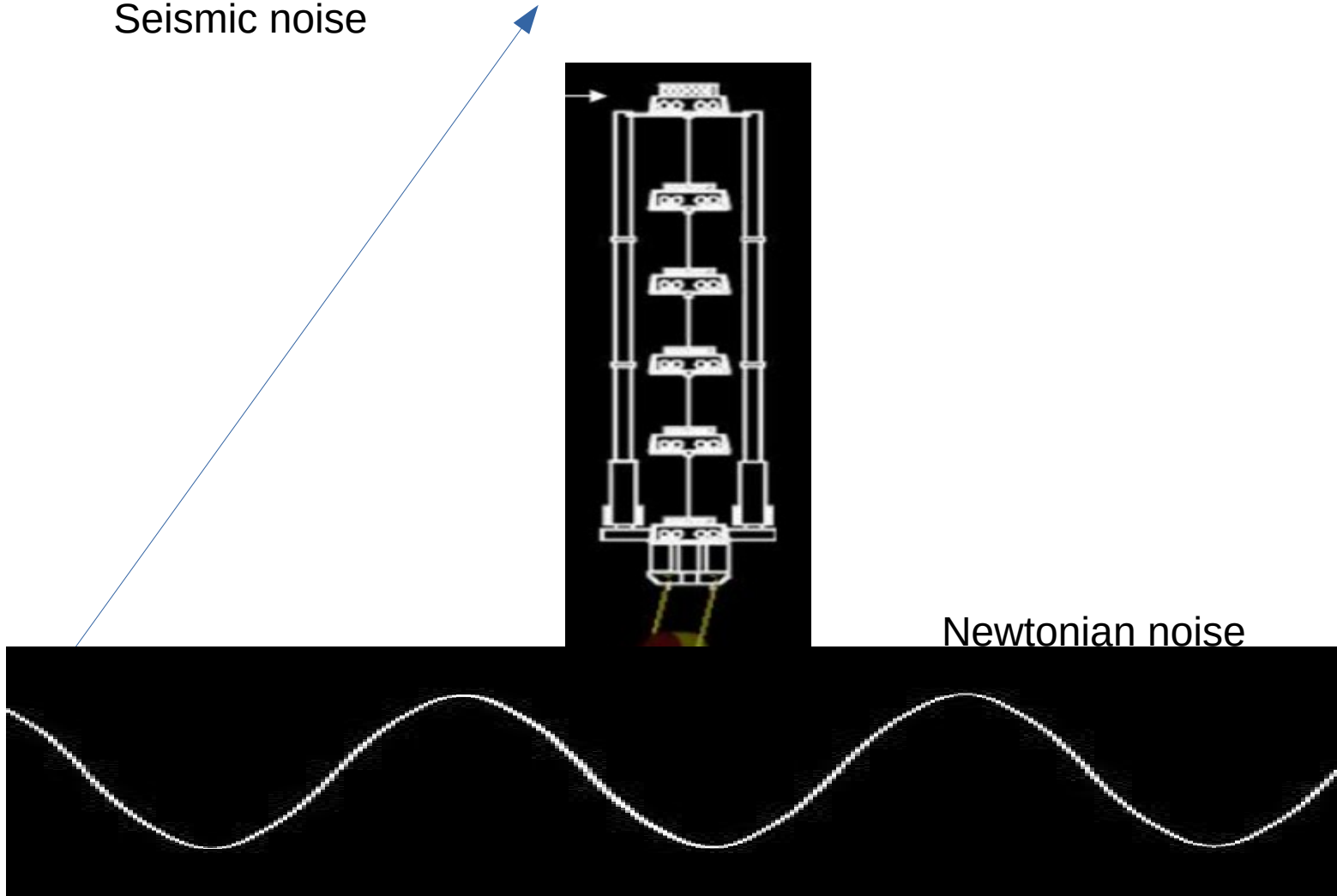
The laser wavelength is 1064nm. Expected phase amplitude:

$$\Delta\phi \approx 5 \times 10^{-16} / 10^{-6} = 5 \times 10^{-10}$$

With 100kW power the Poisson noise fluctuations are

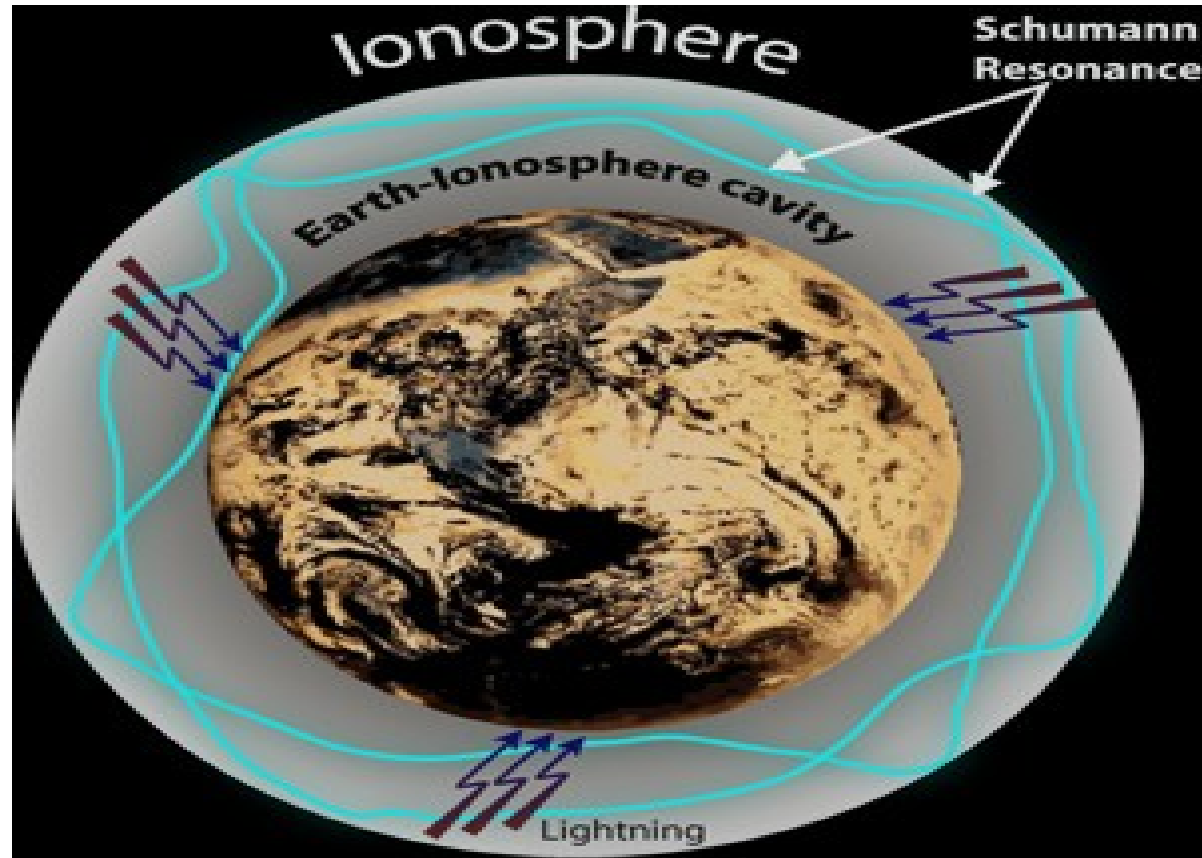
$$\delta\phi = N^{-1/2} = \sqrt{\frac{hc}{\lambda P \Delta T}} = \sqrt{\frac{10^{-19} \text{J}}{10^5 \text{W} 10^{-2} \text{s}}} \approx 10^{-11}$$

Seismic noise



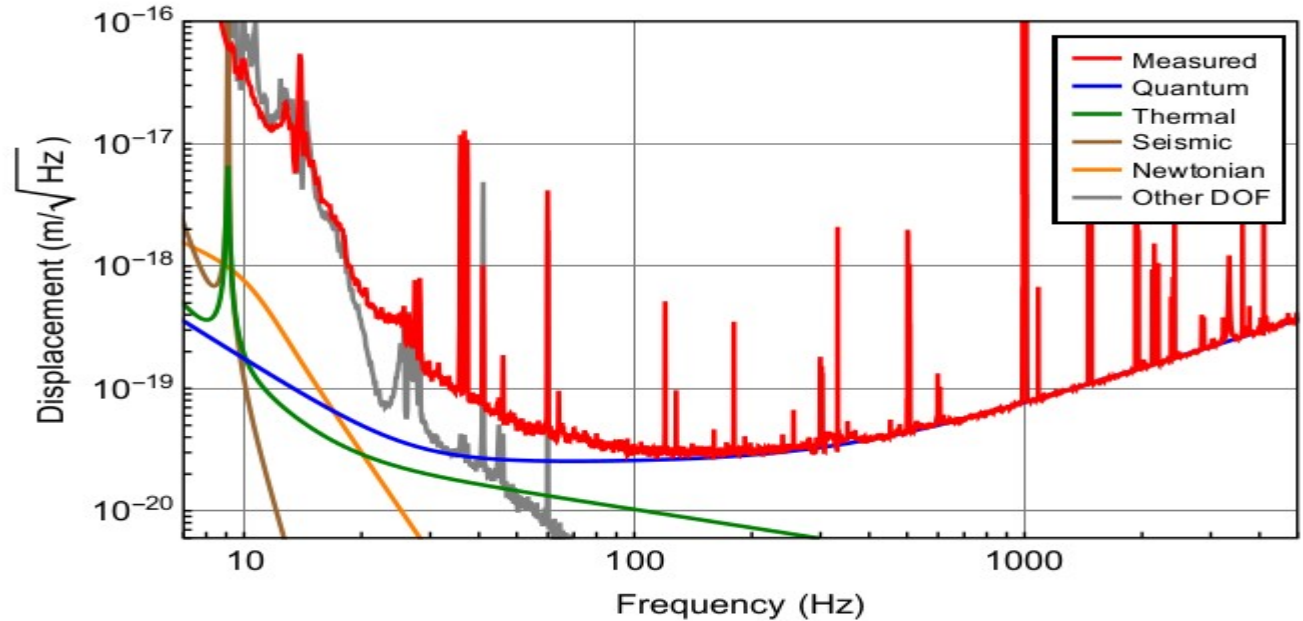
Newtonian noise

Magnetic noise



Technical challenges

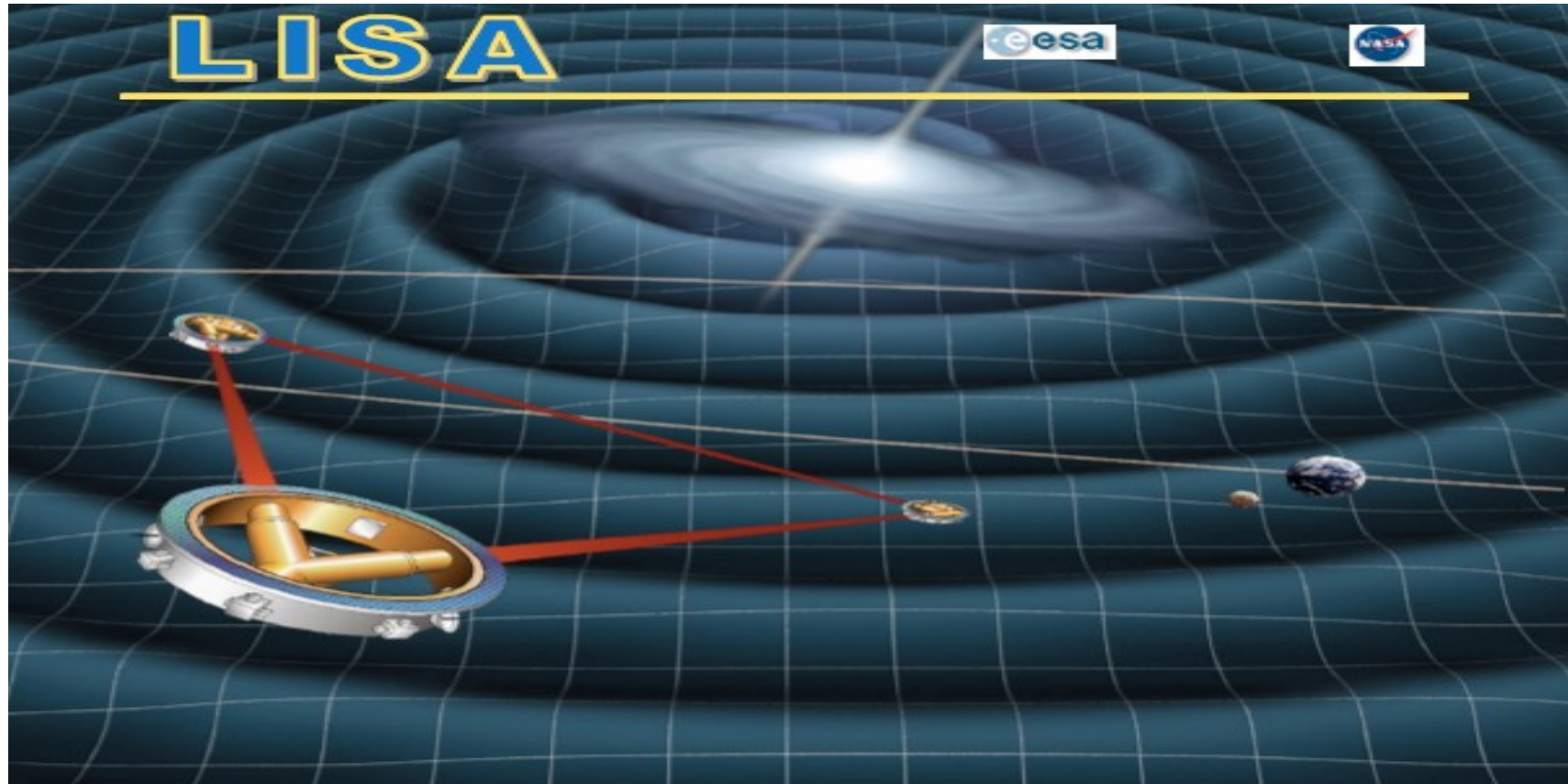
- Seismic isolation
- Vacuum system
- High power lasers
- Thermal noise
- Quantum fluctuations



Abbott et al 2016

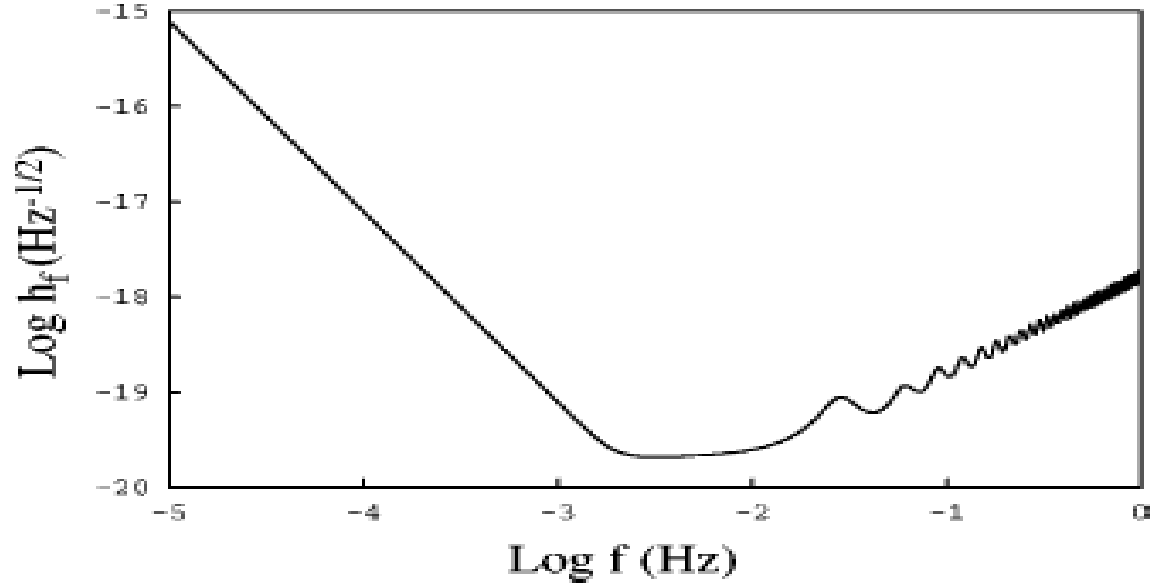
Also – newtonian noise, magnetic noise

LF instruments



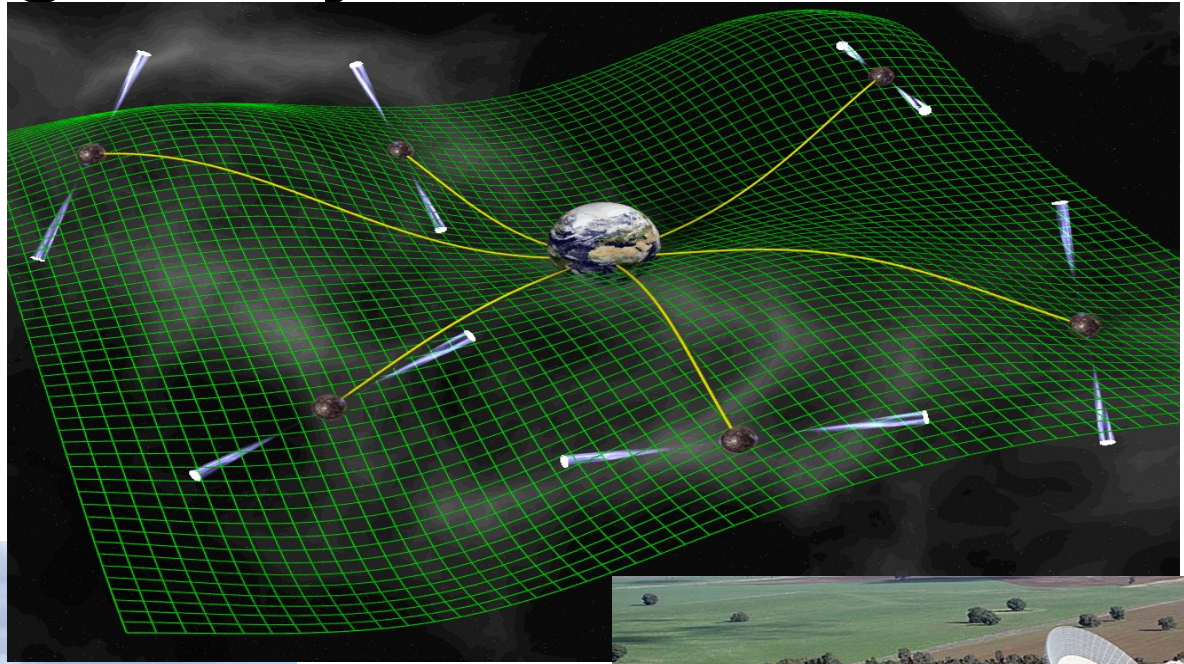
LISA

- Three satellites 5 Gm apart
- Lasers 1W
- Telescopes 30 cm
- Satellite motion
- Launch 2037
- DECIGO, BBO, ALIA



Pulsar Timing Arrays

- PPTA
- EPTA
- SKA

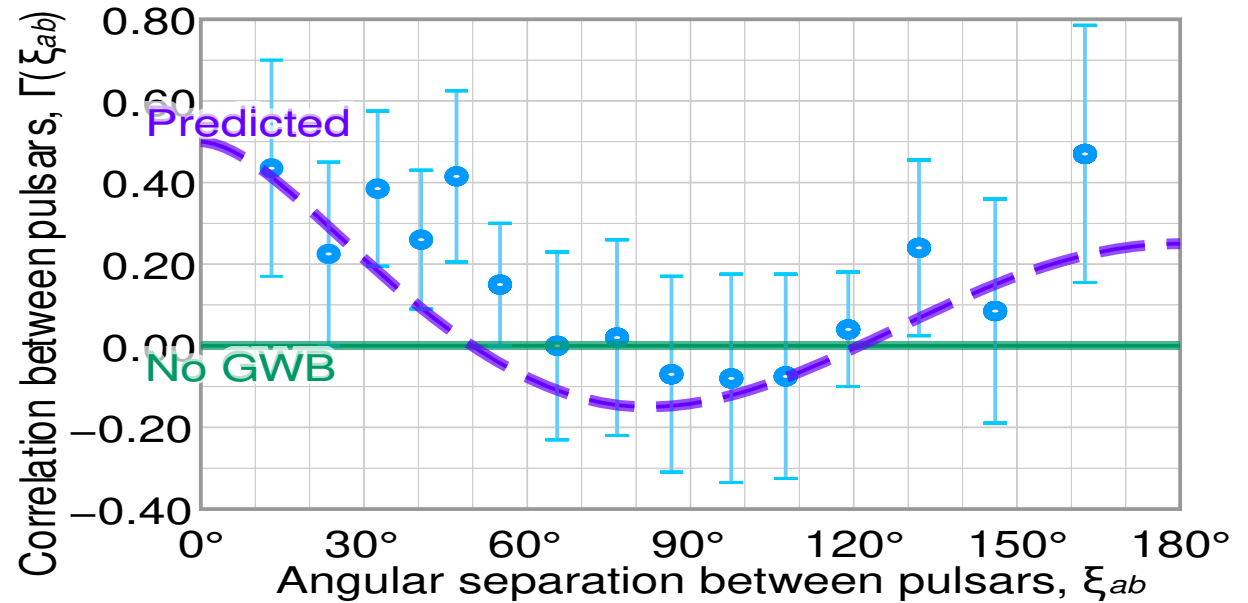


PTA search and detection

Correlation between timing residuals
of distant pulsars

Helling Downs curve.

Expect more in the coming months!



Detector sensitivities and readout

Detector provides a digitized output – a string of numbers.

h1 h2 h3 ... hn

$$\tilde{h}(f) = \mathcal{F}(x(t))(f) = \int_{-\infty}^{\infty} h(t) \exp(2\pi i f t) dt$$

$$h(t) = \mathcal{F}^{-1}(\tilde{h}(f))(t) = \int_{-\infty}^{\infty} \tilde{h}(f) \exp(-2\pi i f t) df$$

Power spectral density

$$\langle \tilde{h}(f) \tilde{h}^*(f') \rangle = \frac{1}{2} \delta(f - f') S_c(f)$$

Units!

Detector noise curve

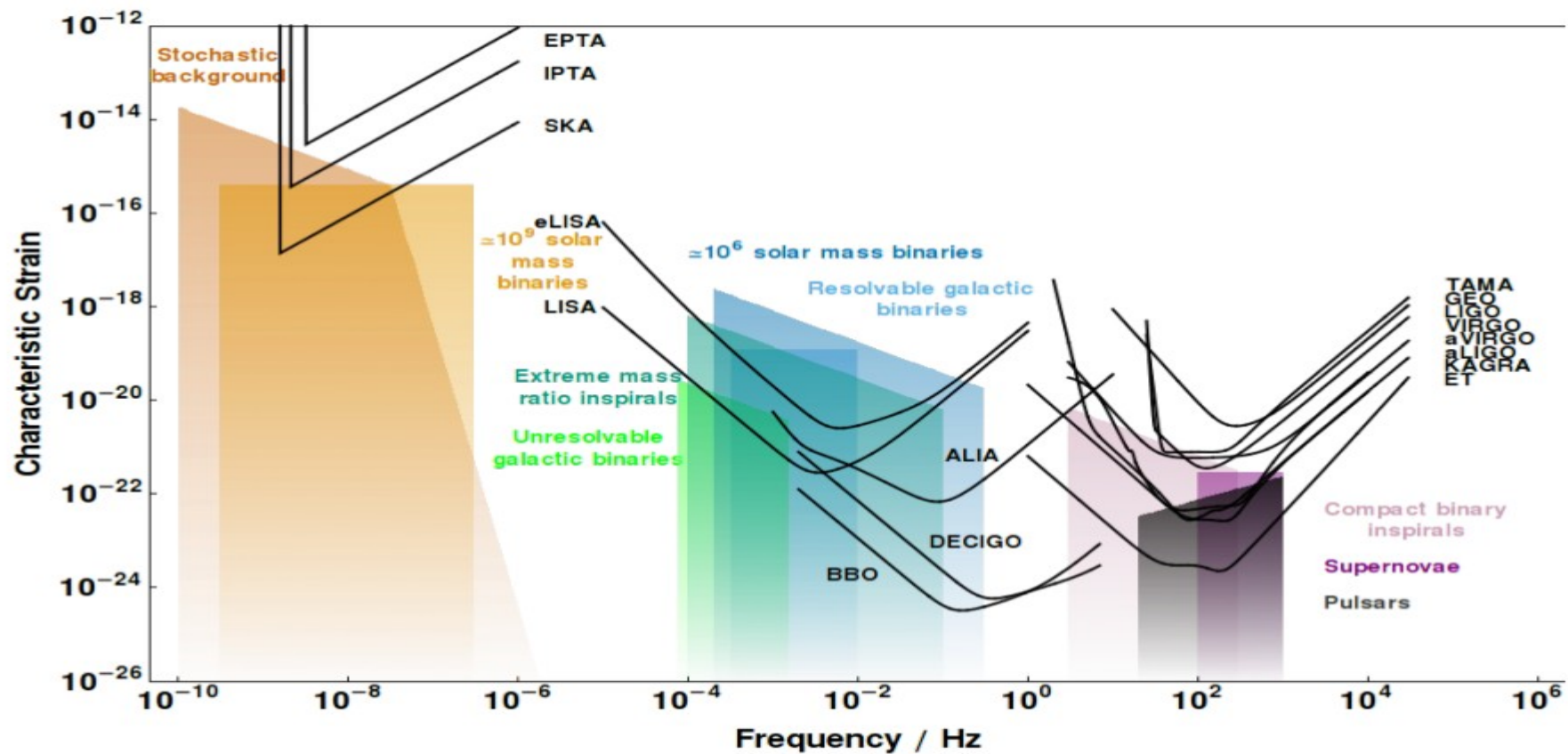
Characteristic strain

$$h_c(f) = \sqrt{f S_c(f)}$$

Signal to noise

$$\rho^2 = \int d(\log f) \frac{|h_c(f)|^2}{|h_n(f)|^2}$$

- + Easy to read the S/N off graphs
- does not correspond to signal amplitude
- + shows the rms in a given band

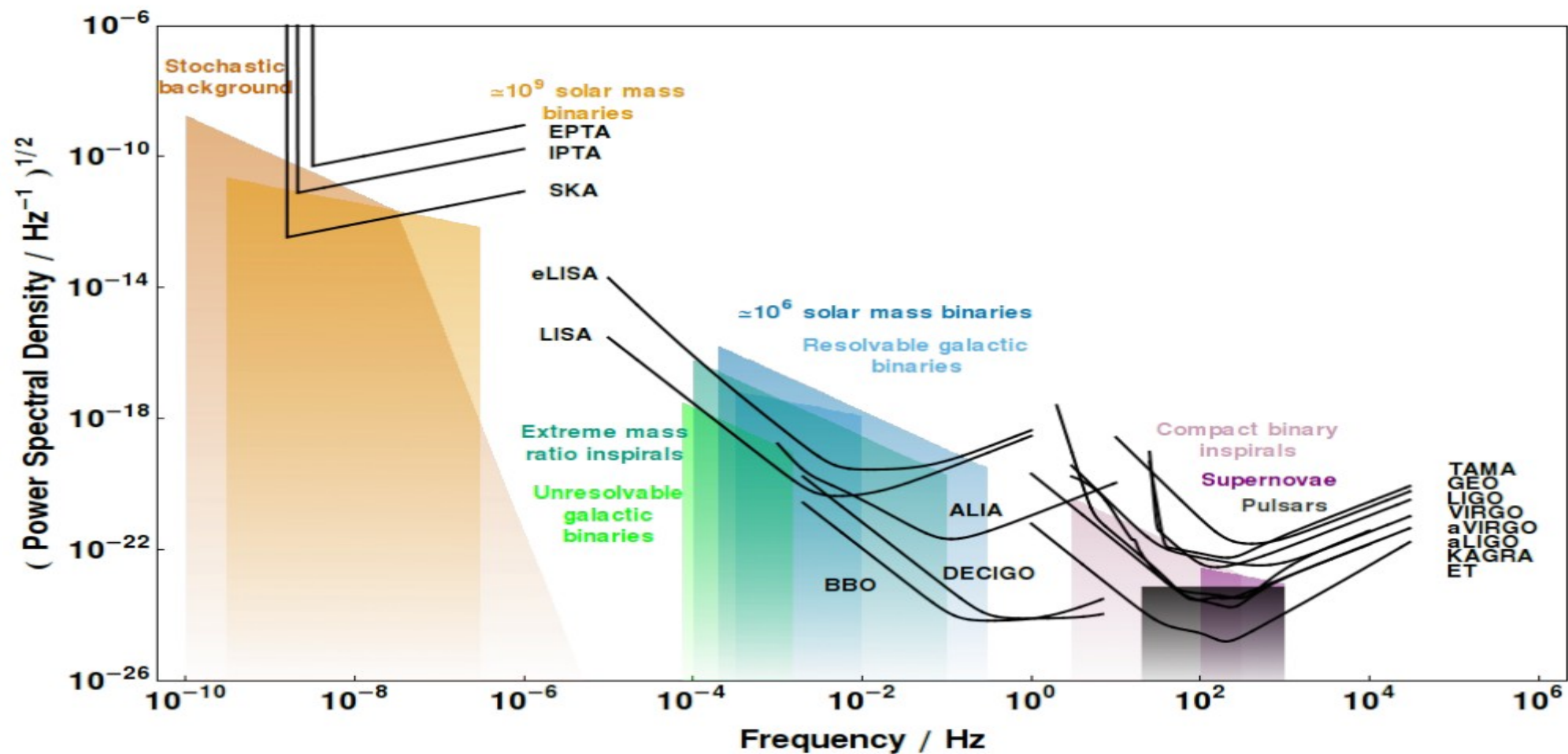


Detector noise curves

Amplitude spectral density (or root PSD)

$$\text{ASD}(f) = \sqrt{S_h(f)} = h(f) f^{-1/2}$$

- units
- mean square amplitude of the signal from PSD
- most commonly used



Detector noise curves

Energy density

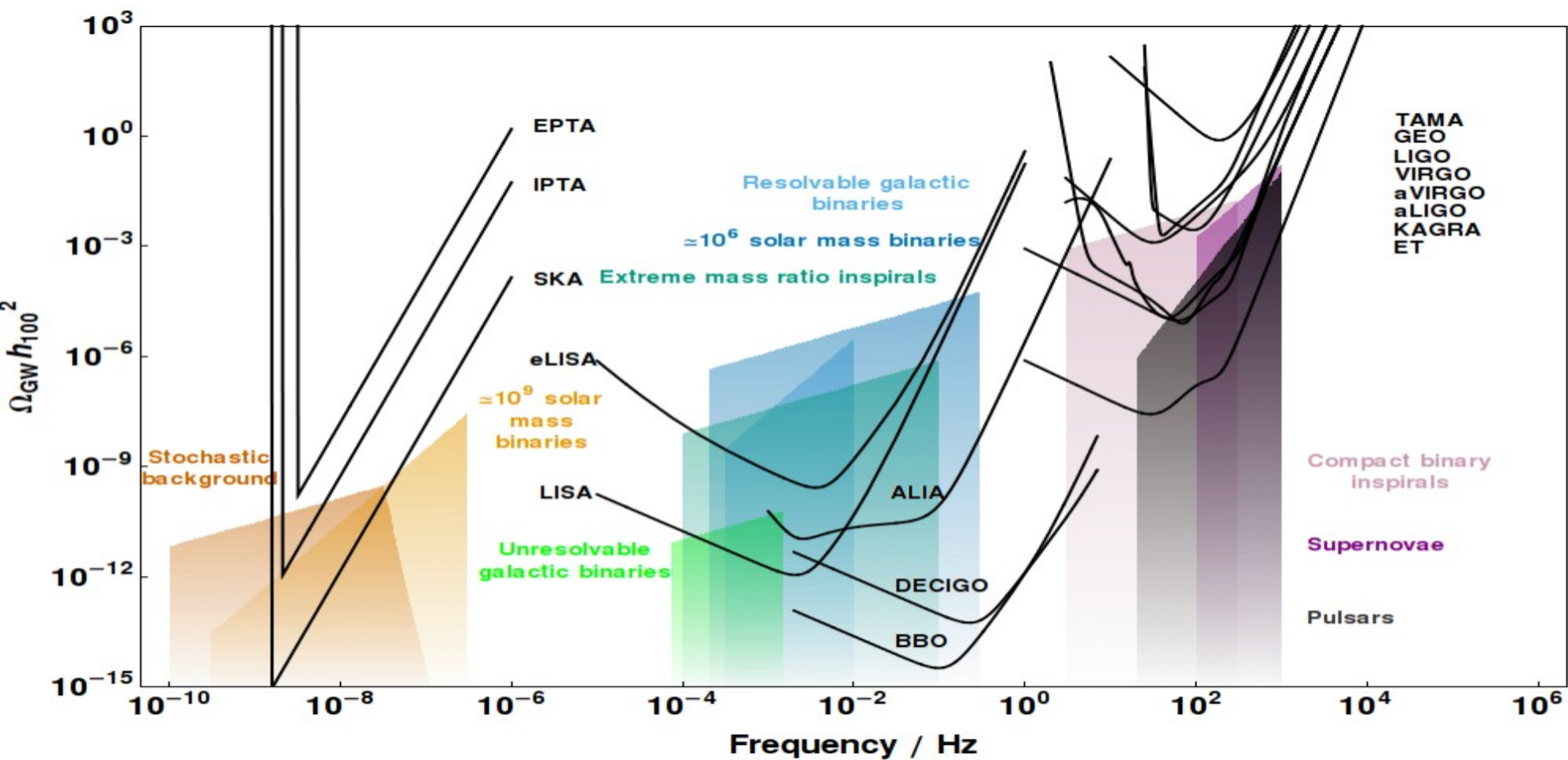
$$T_{\mu\nu} = \frac{c^4}{32\pi G} \langle \partial_\mu h_{\alpha\beta} \partial_\nu h_{\alpha\beta} \rangle$$

$$\rho c^2 = \frac{c^2}{16\pi G} \int_0^\infty df (2\pi f)^2 \tilde{h}(f) \tilde{h}^*(f) = \int_0^\infty df \frac{\pi c^2}{4G} f^2 S_h(f)$$

$$S_E(f) = \frac{\pi c^2}{4G} f^2 S_h(f)$$

Energy density per logarithmic frequency interval

$$\Omega_{GW}(f) = \frac{f S_E(f)}{\rho_c c^2} = \frac{8\pi G}{3H_0^2 c^2} f S_E(f)$$



Let us come down to Earth!

Conversions

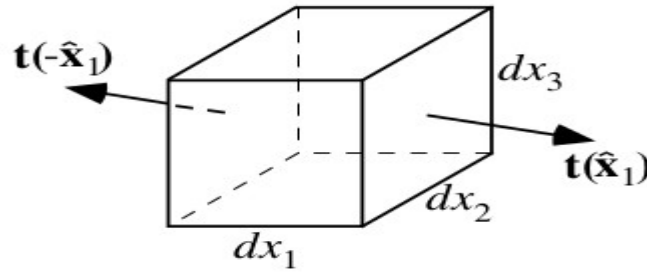
$$\Omega_{GW}(f) = \frac{8\pi G}{3H_0^2 c^2} f S_E(f) = \frac{2\pi^2}{3H_0^2} f^3 S_h(f) = \frac{2\pi^2}{3H_0^2} f^2 [h_c(f)]^2 = \frac{8\pi^2}{3H_0^2} f^4 \left| \tilde{h}(f) \right|^2$$

$$\frac{3H_0^2 c^2}{8\pi G} \frac{\Omega_{GW}(f)}{f} = S_E(f) = \frac{c^2 \pi}{4G} f^2 S_h(f) = \frac{c^2 \pi}{4G} f [h_c(f)]^2 = \frac{\pi c^2}{G} f^3 \left| \tilde{h}(f) \right|^2$$

$$ASD(f) = S_h(f)^{1/2} = \frac{|h_c(f)|}{f} = 2f |\tilde{h}(f)| = \sqrt{\frac{4G S_E(f)}{\pi c^2 f^2}} = \sqrt{\frac{3H_0^2 \Omega_{GW}}{2\pi^2 f^3}}$$

$$h_c(f) = f ASD(f)$$

Seismic waves 1



Stress tensor

$$\tau_{ij}$$

coordinates

$$u_i$$

Force on a volume element:

$$F_i = \partial_i \tau_{ij} dx_1 dx_2 dx_3$$

Seismic waves 2

Mass of the volume element:

$$m = \rho dx_1 dx_2 dx_3$$

Newton equation of motion:

$$\rho \frac{\partial^2 u_i}{\partial t^2} = \partial_j \tau_{ij} + f_i$$

stress

Body (external) forces

Seismic waves 3

We want to express stress tensor as a function of strain!

$$e_{ij} = \frac{1}{2}(\partial_i u_j + \partial_j u_i)$$

The stress tensor of an isotropic medium can be expressed as

$$\tau_{ij} = \lambda \delta_{ij} e_{kk} + 2\mu e_{ij}$$

λ and μ are Lamé coefficients. So

$$\tau_{ij} = \lambda \delta_{ij} \partial_k u_k + \mu (\partial_i u_j + \partial_j u_i)$$

Seismic waves 4

Insert this into the equation of motion

$$\begin{aligned}\rho \frac{\partial^2 u_i}{\partial t^2} &= \partial_j [\lambda \delta_{ij} \partial_k u_k + \mu (\partial_i u_j + \partial_j u_i)] \\ &= \partial_i \lambda \partial_k u_k + \lambda \partial_i \partial_k u_k + \partial_j \mu (\partial_i u_j + \partial_j u_i) + \mu \partial_j \partial_i u_j + \mu \partial_j \partial_j u_i \\ &= \partial_i \lambda \partial_k u_k + \partial_j \mu (\partial_i u_j + \partial_j u_i) + \lambda \partial_i \partial_k u_k + \mu \partial_i \partial_j u_j + \mu \partial_j \partial_j u_i.\end{aligned}$$

Or a little simpler:

$$\rho \ddot{\mathbf{u}} = \nabla \lambda (\nabla \cdot \mathbf{u}) + \nabla \mu \cdot [\nabla \mathbf{u} + (\nabla \mathbf{u})^T] + (\lambda + \mu) \nabla \nabla \cdot \mathbf{u} + \mu \nabla^2 \mathbf{u}.$$

Seismic waves 5

$$\nabla \times \nabla \times \mathbf{u} = \nabla \nabla \cdot \mathbf{u} - \nabla^2 \mathbf{u}$$

$$\nabla^2 \mathbf{u} = \nabla \nabla \cdot \mathbf{u} - \nabla \times \nabla \times \mathbf{u}.$$

The seismic wave equation:

$$\rho \ddot{\mathbf{u}} = \nabla \lambda (\nabla \cdot \mathbf{u}) + \nabla \mu \cdot [\nabla \mathbf{u} + (\nabla \mathbf{u})^T] + (\lambda + 2\mu) \nabla \nabla \cdot \mathbf{u} - \mu \nabla \times \nabla \times \mathbf{u}.$$

For an isotropic medium

$$\rho \ddot{\mathbf{u}} = (\lambda + 2\mu) \nabla \nabla \cdot \mathbf{u} - \mu \nabla \times \nabla \times \mathbf{u}.$$

Seismic waves 6

Simple solutions:

Take div of the seismic equation:

$$\frac{\partial^2(\nabla \cdot \mathbf{u})}{\partial t^2} = \frac{\lambda + 2\mu}{\rho} \nabla^2(\nabla \cdot \mathbf{u})$$

$$\nabla^2(\nabla \cdot \mathbf{u}) - \frac{1}{\alpha^2} \frac{\partial^2(\nabla \cdot \mathbf{u})}{\partial t^2} = 0,$$

Wave equation with velocity

P - wave

$$\alpha = \sqrt{\frac{\lambda + 2\mu}{\rho}}$$

Seismic waves 7

Take curl of the seismic equation:

$$\frac{\partial^2(\nabla \times \mathbf{u})}{\partial t^2} = -\frac{\mu}{\rho} \nabla \times \nabla \times (\nabla \times \mathbf{u}).$$

$$\frac{\partial^2(\nabla \times \mathbf{u})}{\partial t^2} = \frac{\mu}{\rho} \nabla^2(\nabla \times \mathbf{u})$$

Wave equation: S wave

$$\nabla^2(\nabla \times \mathbf{u}) - \frac{1}{\beta^2} \frac{\partial^2(\nabla \times \mathbf{u})}{\partial t^2} = 0,$$

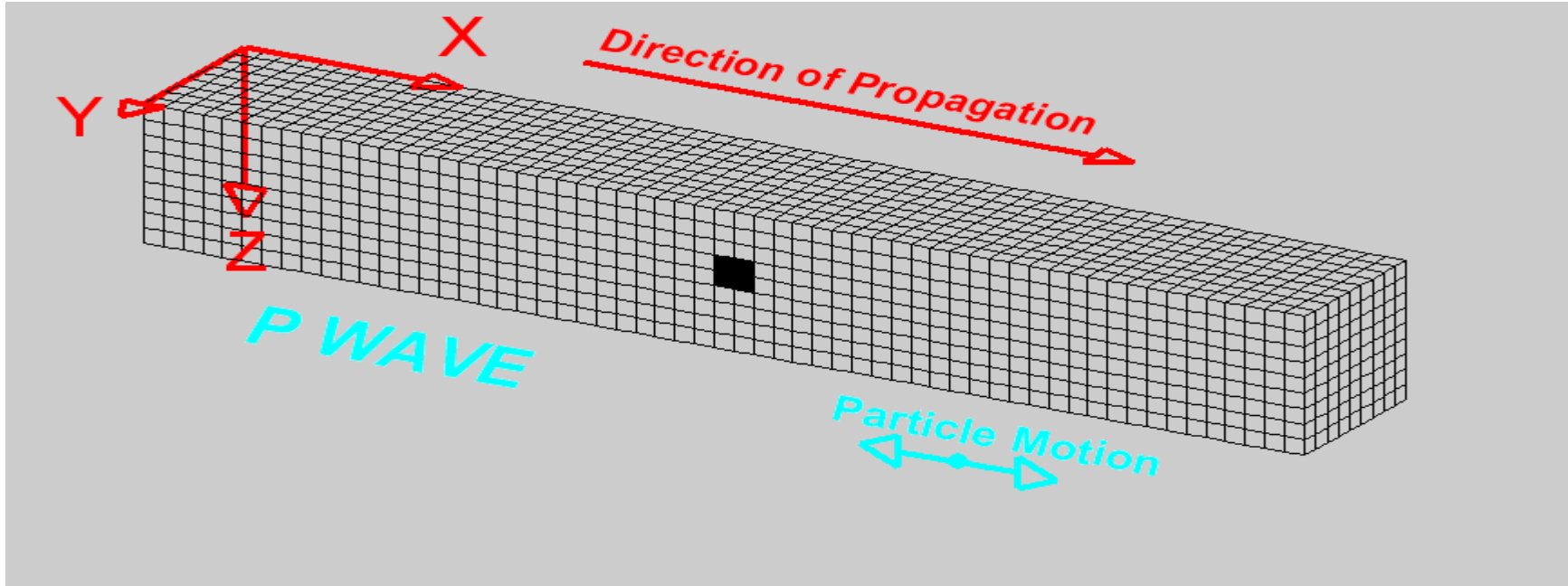
velocity

$$\beta = \sqrt{\frac{\mu}{\rho}}$$

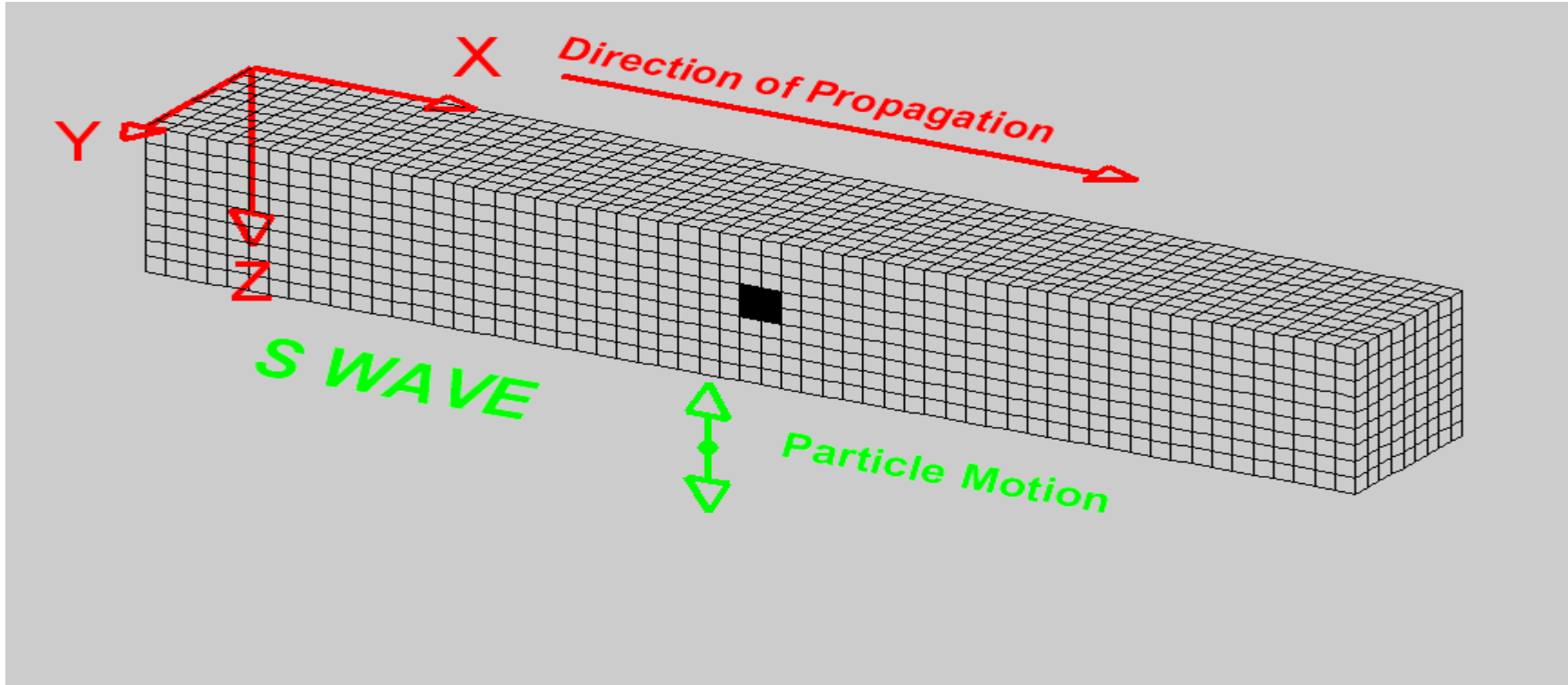
Body waves

- P-wave (primary wave)
- S-wave (secondary wave)

P-wave



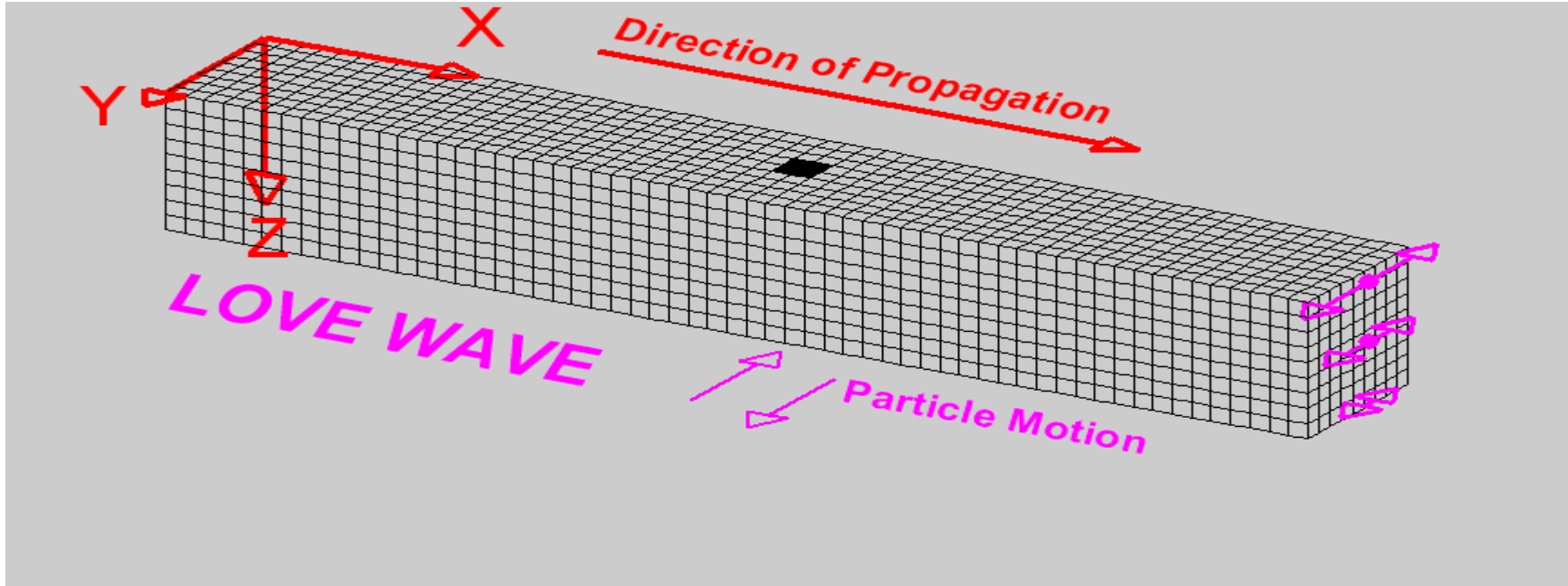
S-wave



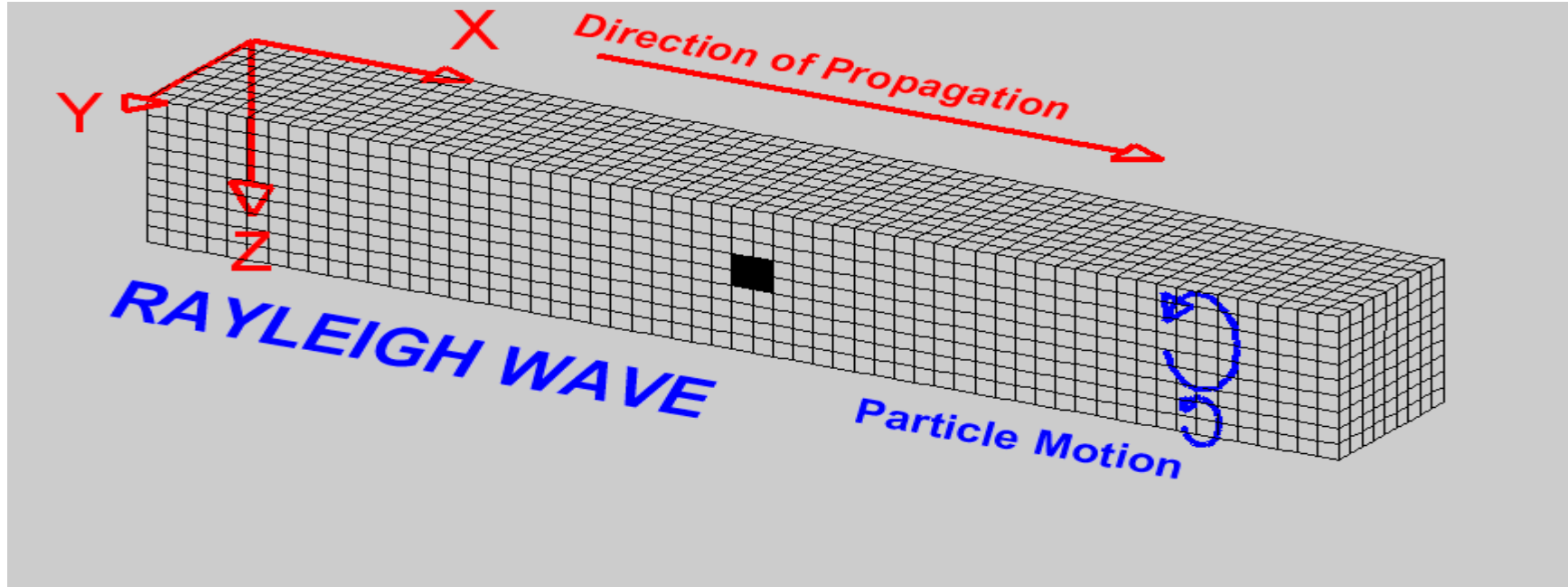
Surface waves

- Need to solve the equation with specific boundary conditions
- Space- half uniform density, half zero density
- Displacement vanished at -infinity
- Solutions can be thought as linear combinations of S and P wave that are reflected off the boundary (surface)

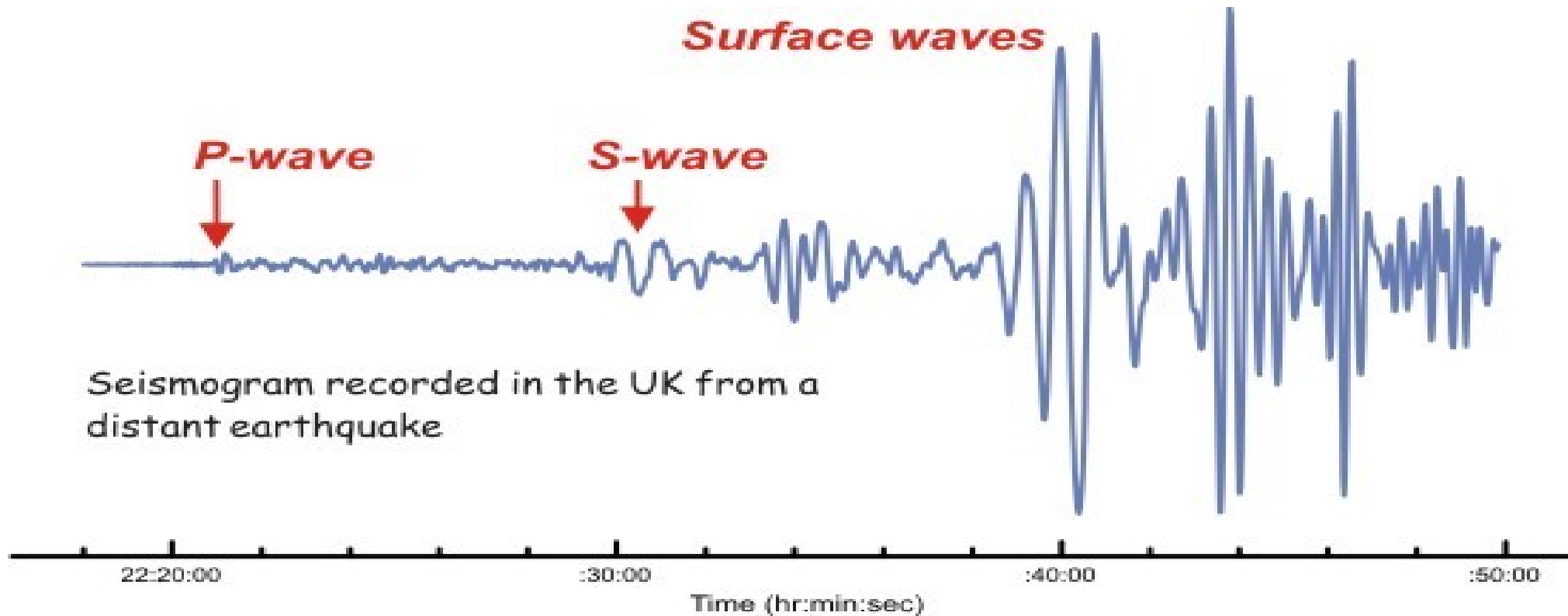
Love wave



Rayleigh wave



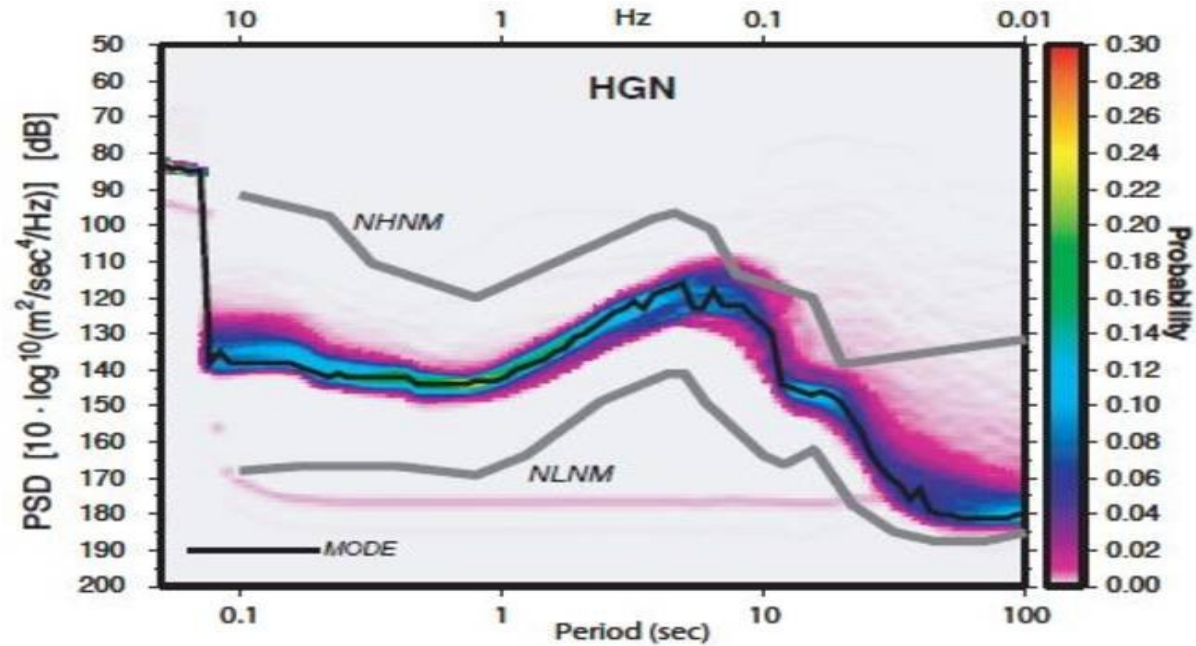
Earthquakes



Seismic noise

- Originates in
 - Wind
 - Waves
 - Seismicity
 - Human activity

Seismic noise



A note on units

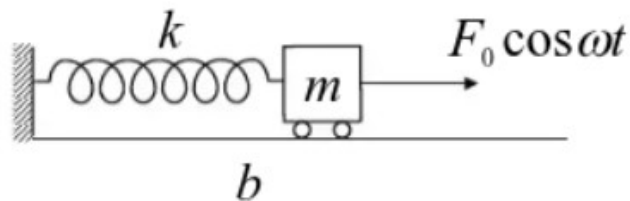
- Displacement, velocity, acceleration
- Time series $u(t)$, $v(t)$, $a(t)$
- Power spectral density, e.g. m^2/Hz
- Amplitude spectral density e.g. $\text{m}/\sqrt{\text{Hz}}$

Influence of seismic noise on gravitational interferometers

- Mechanical coupling
- Gravitational coupling

Forced Harmonic Oscillator

$$\gamma = \frac{b}{2m}; \quad \omega_0 = \sqrt{\frac{k}{m}}$$



$$\frac{d^2x}{dt^2} + 2\gamma \frac{dx}{dt} + \omega_0^2 x = \frac{F_0}{m} \cos \omega t$$

Solution: $x(t) = x^H(t) + \frac{F_0/m}{\sqrt{(\omega_0^2 - \omega^2)^2 + 4\gamma^2 \omega^2}} \cos(\omega t - \varphi)$

General solution of associated
homogeneous equation

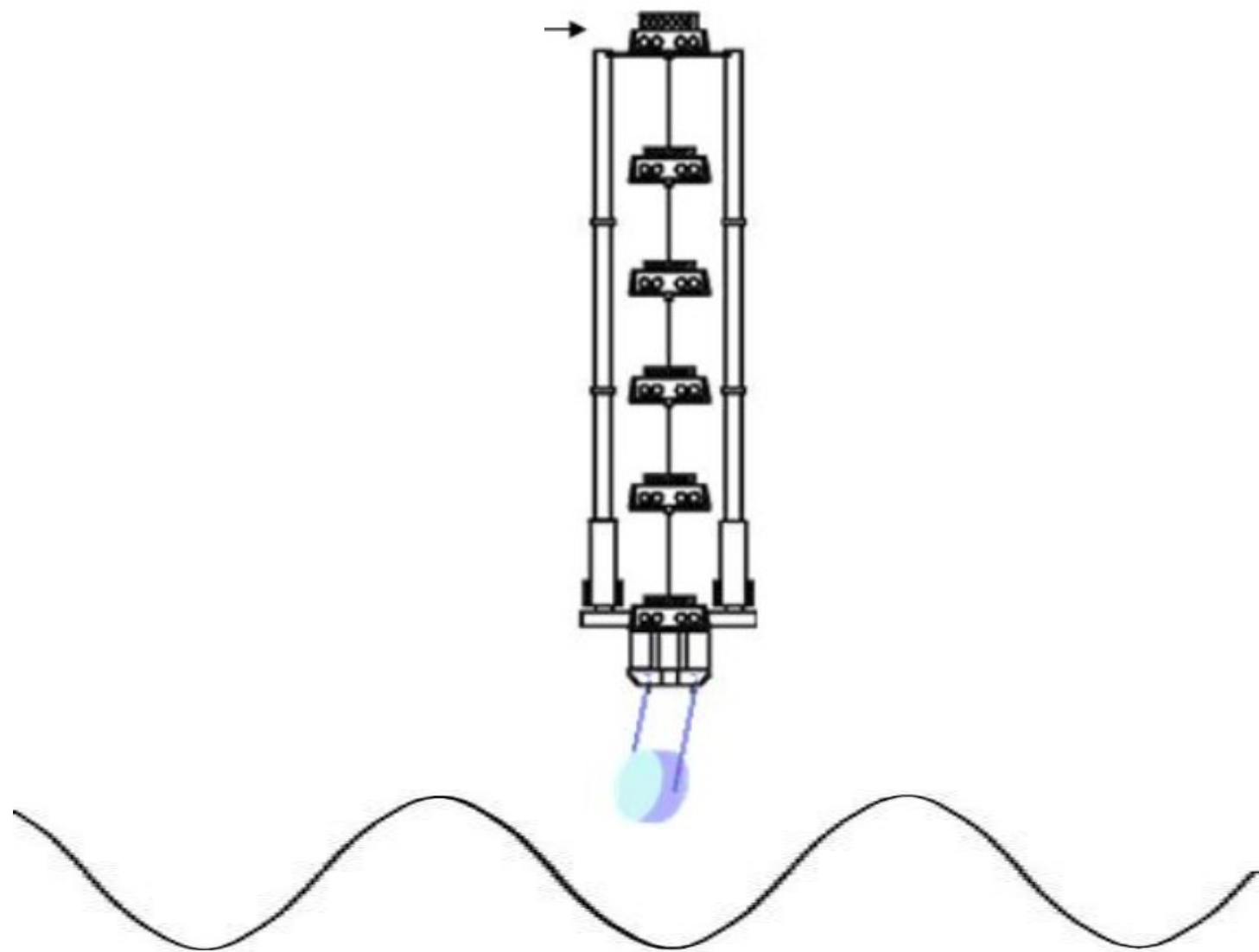
(Transient Term)
(Decays to zero as $t \rightarrow \infty$)

Particular solution of
inhomogeneous equation
(Steady State Term)

$$\tan \varphi = \frac{2\gamma\omega}{\omega_0^2 - \omega^2}$$

Mechanical filtering

- Forced oscillators are mechanical low pass filters
- A series of mechanical filters can quench the mechanical noise sufficiently



Gravity perturbation from seismic waves

Density fluctuation

$$\delta\rho = -\nabla(\rho(\vec{r})\vec{\zeta}(\vec{r}, t))$$

Potential fluctuation

$$\delta\phi = -G \int dV \frac{\delta\rho(\vec{r}, t)}{|\vec{r} - \vec{r}_0|}$$

A little algebra

$$\delta\phi = -G \int dV \frac{\nabla(\rho(\vec{r}, t)\vec{u}(\vec{r}, t))}{|\vec{r} - \vec{r}_0|}$$

Integration by parts

$$\delta\phi = -G \int dV \rho(\vec{r}, t)\vec{u}(\vec{r}, t) \nabla \frac{1}{|\vec{r} - \vec{r}_0|}$$

Change of volume to
surface integral (Gauss
theorem)

So finally

$$\delta\phi = -G \int dV \rho(\vec{r}, t)\vec{u}(\vec{r}, t) \frac{\vec{r} - \vec{r}_0}{|\vec{r} - \vec{r}_0|^3}$$

And now acceleration

$$\vec{a} = \nabla \phi$$

$$\delta \vec{a}(\vec{r}_0, t) = G \int dV \rho(\vec{r}) \vec{\zeta}(\vec{r}, t) \nabla_0 \frac{\vec{r} - \vec{r}_0}{|\vec{r} - \vec{r}_0|^3}$$

In the case of surface waves

Half space:

$$\rho = \rho_0 \Theta(-\sigma(\vec{r}))$$

$$\delta\phi = G\rho \int dV \frac{\nabla(\Theta(-\sigma(\vec{r}))\vec{u}(\vec{r}, t))}{|\vec{r} - \vec{r}_0|}$$

$$\delta\phi = G\rho \int \frac{dV}{|\vec{r} - \vec{r}_0|} [\Theta(-\sigma(\vec{r}))\nabla\vec{u}(\vec{r}, t) - \delta(-r)\vec{n}(\vec{r})\vec{u}(\vec{r}, t)]$$

$$\delta\phi = G\rho \int dV \frac{\nabla\vec{u}(\vec{r}, t)}{|\vec{r} - \vec{r}_0|} + G\rho \int dS \frac{n(\vec{r})\vec{u}(\vec{r}, t)}{|\vec{r} - \vec{r}_0|}$$

Bulk

surface

Which waves contribute to gravity fluctuations?

An example

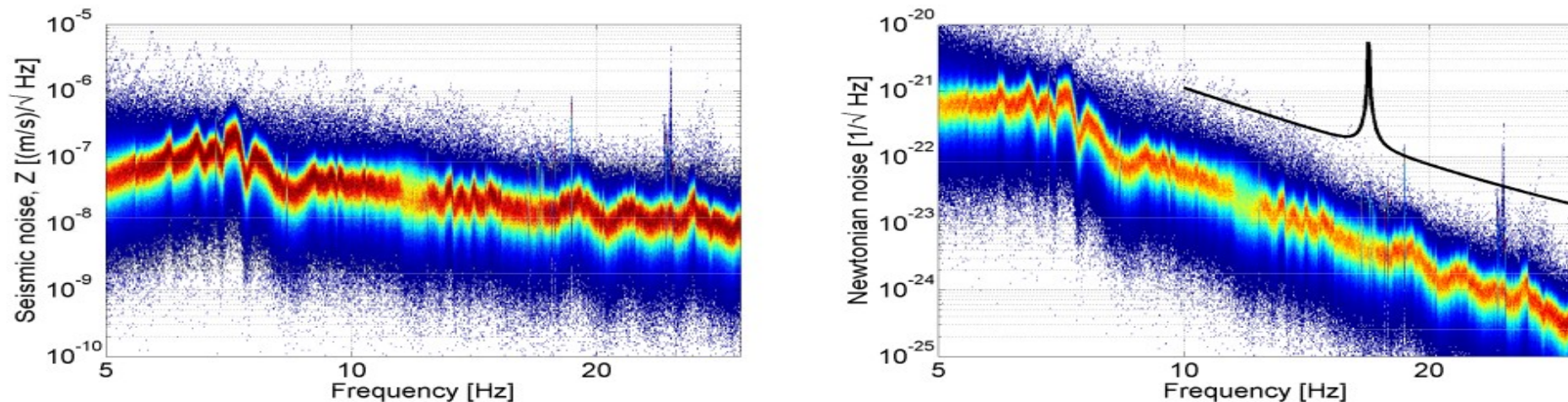


Figure 14: Histograms of seismic spectra at the central station of the Virgo detector and modelled Rayleigh-wave Newtonian noise. A sensitivity model of the Advanced Virgo detector is plotted for comparison. (Seismic data stem from channel SEBDCE06 between June 4, 2011, UTC 00:00 and September 3, 2011, UTC 00:00.)

And another

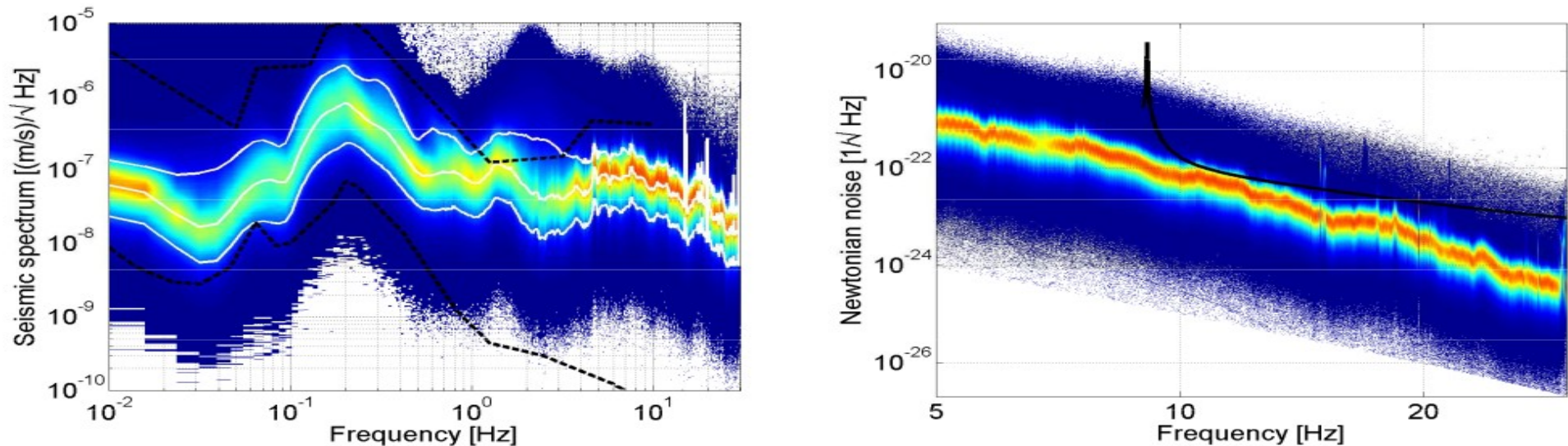


Figure 15: Histograms of seismic spectra at the central station of the LIGO Livingston detector and modelled Rayleigh-wave Newtonian noise. In the left plot, the dashed black curves are the global seismic high-noise and low-noise models. The white curves are the 10th, 50th, and 90th percentiles of the histogram. In the right plot, a sensitivity model of the Advanced LIGO detector is plotted for comparison. (Seismic data stem from channel L0:PEM-LVEA_SEISZ between August 1, 2009, UTC 00:00 and August 1, 2010, UTC 00:00.

Gravity gradients mitigation strategy

- Measure and subtract
- Use networks of sensors
- Find the best combinations
- Use Wiener filter techniques
- Best subtraction – a factor of a few
- Move detector underground!

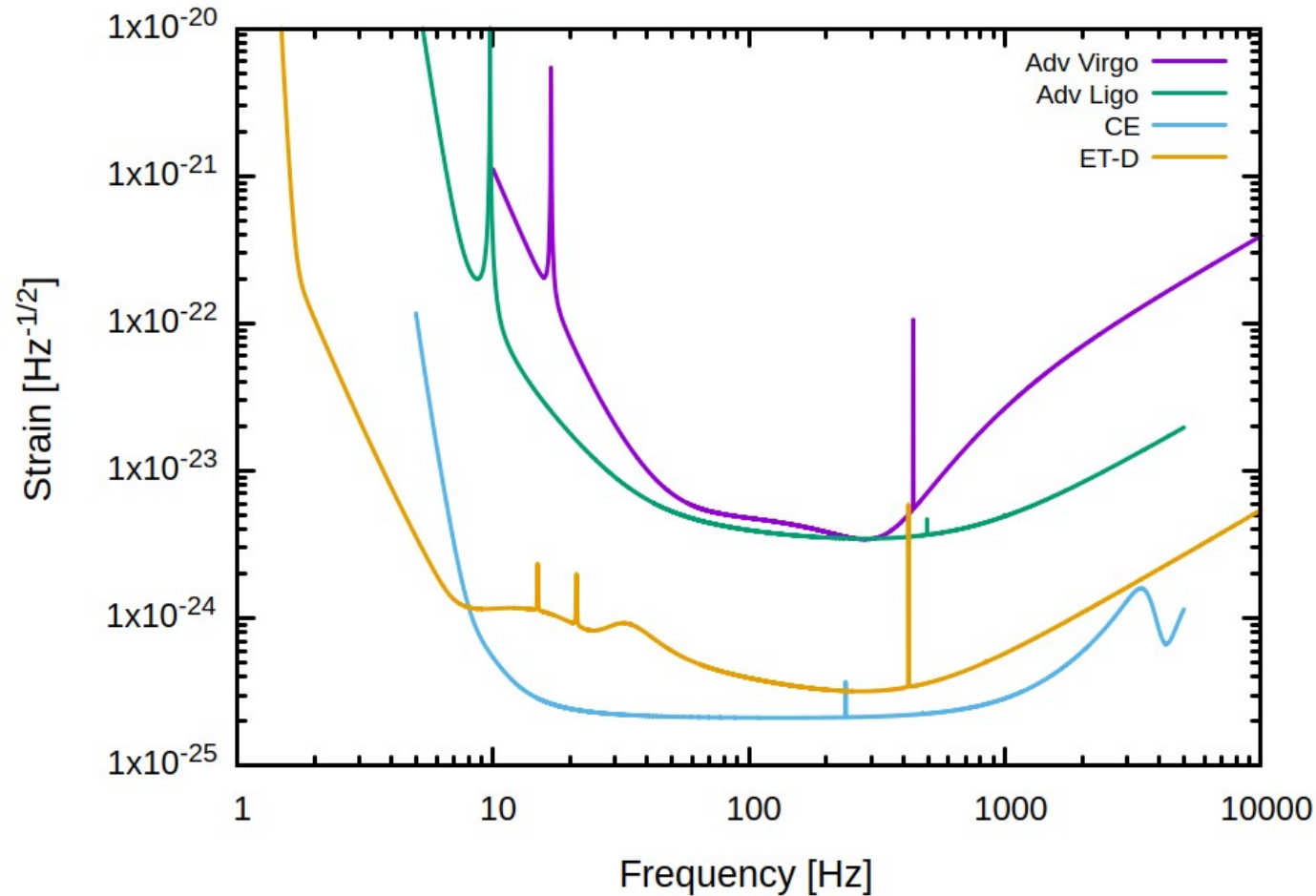
Einstein Telescope

What is Einstein Telescope (ET)?



- ET pioneered the concept of a 3rd generation GW observatory, evolved in the following key requirements
 - **ET must be a 3rd generation GW observatory**, and thus its sensitivity aims to be at least one order of magnitude better with respect to the nominal sensitivity of advanced detectors in all the detection frequency band
 - **ET must be both a precision measurement and a new discovery project**, and thus it aims to be a wide frequency band observatory,
 - **ET science has a special focus on massive (or intermediate mass) black holes**, and thus it aims to have an extraordinary sensitivity at low frequency (few Hz)
 - **ET must have a high reliability**, and thus it aims to obtain a high observation duty cycle
 - **ET must be able to make science in a standalone configuration**; ET aims to have localisation and GW polarisation disentanglement capabilities and to show a more uniform sky coverage. Nevertheless, it is worth to note that the ET full science potential will be achieved in a 3G network, and it is important that other projects, like the Cosmic Explorer (CE) project in US, are developed in parallel to ET. In case of a full 3G global network, this requirement can be revised.
 - **ET must have a lifetime of several decades**, (50 years in the ET proposal), being capable to host the evolution of the detectors, without limiting their sensitivity.
- ET path in the last decade:
 - A conceptual design
 - Few enabling technologies
 - A scientific collaboration (currently under definition)
 - An official ET project (recently entered in the ESFRI roadmap and whose structure is under definition by the funding agencies engaged on ET)

ET planned sensitivity



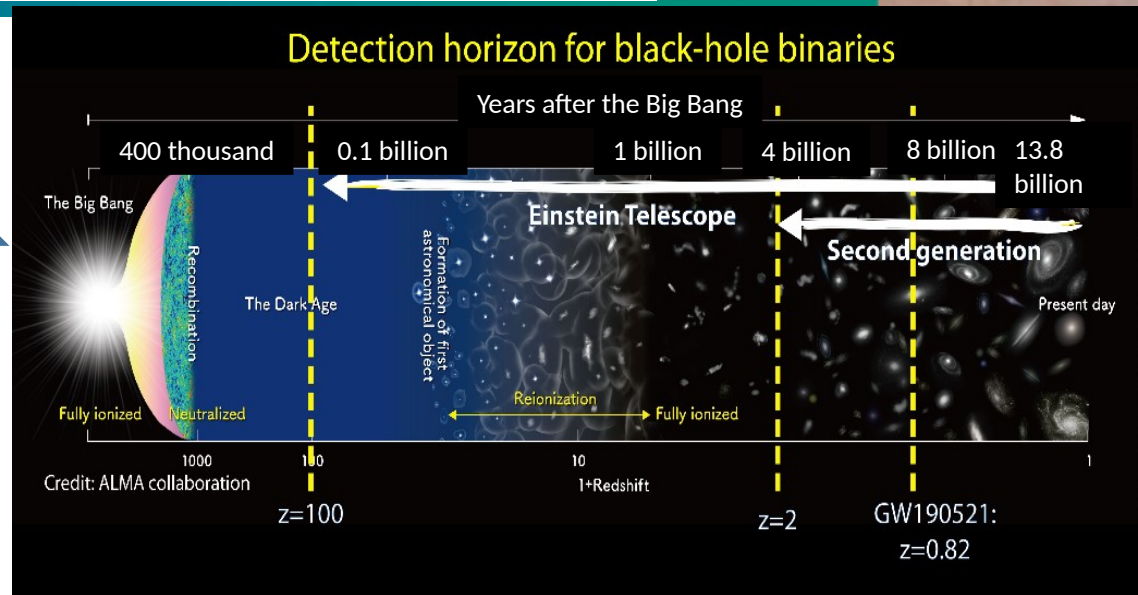
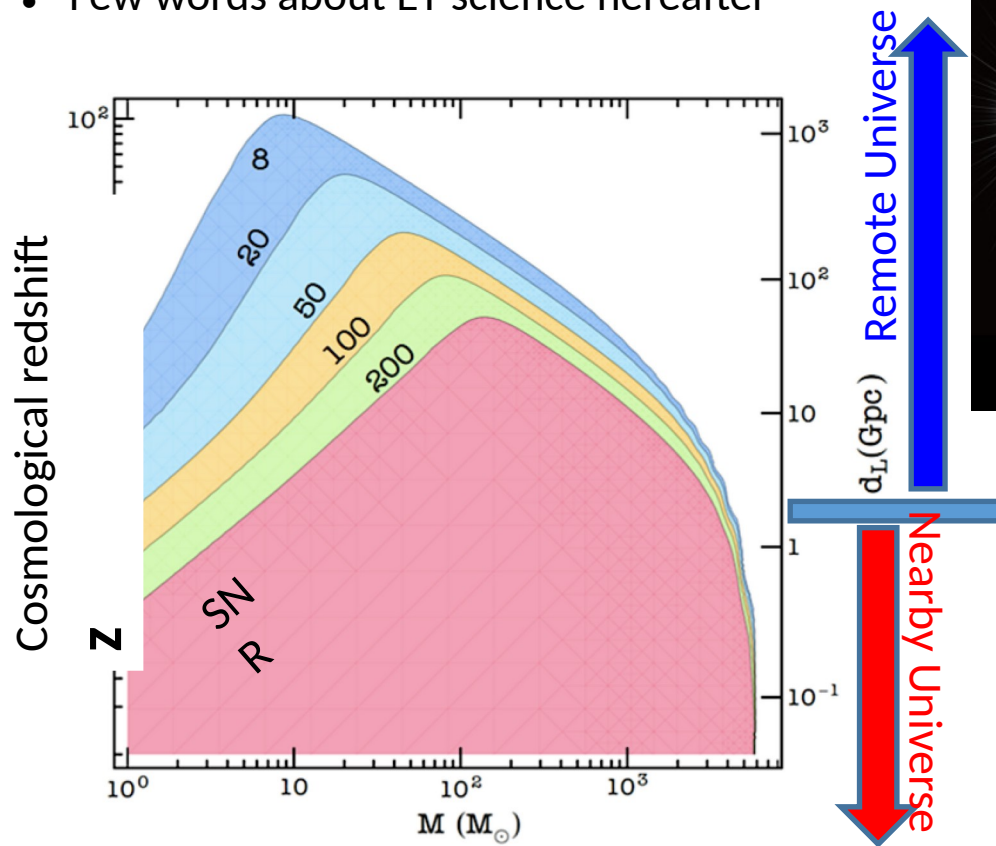
ASTROPHYSICS

- **Black hole properties**
 - origin (stellar vs. primordial)
 - evolution, demography
- **Neutron star properties**
 - interior structure (QCD at ultra-high densities, exotic states of matter)
 - demography
- **Multi-band and -messenger astronomy**
 - joint GW/EM observations (GRB, kilonova,...)
 - multiband GW detection (LISA)
 - neutrinos
- **Detection of new astrophysical sources**

FUNDAMENTAL PHYSICS AND COSMOLOGY

- **The nature of compact objects**
 - near-horizon physics
 - tests of no-hair theorem
 - exotic compact objects
- **Tests of General Relativity**
 - post-Newtonian expansion
 - strong field regime
- **Dark matter**
 - primordial BHs
 - axion clouds, dark matter accreting on compact objects
- **Dark energy and modifications of gravity on cosmological scales**

- ET will be both a discovery machine and a precision measurement instrument
- Few words about ET science hereafter



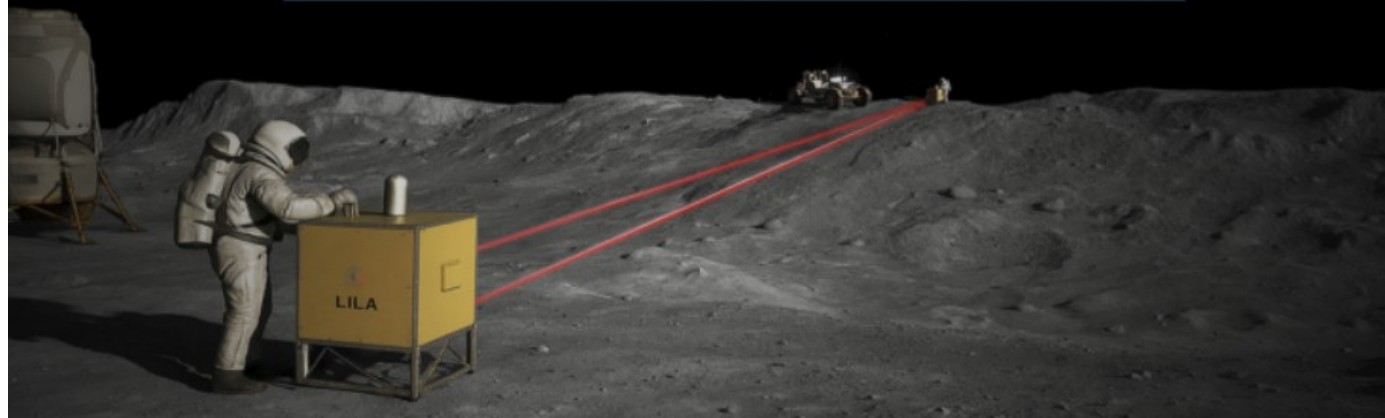
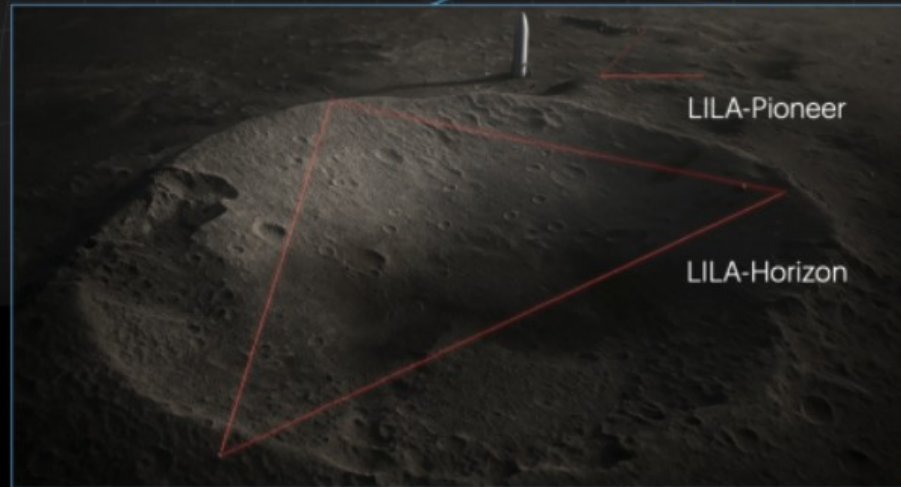
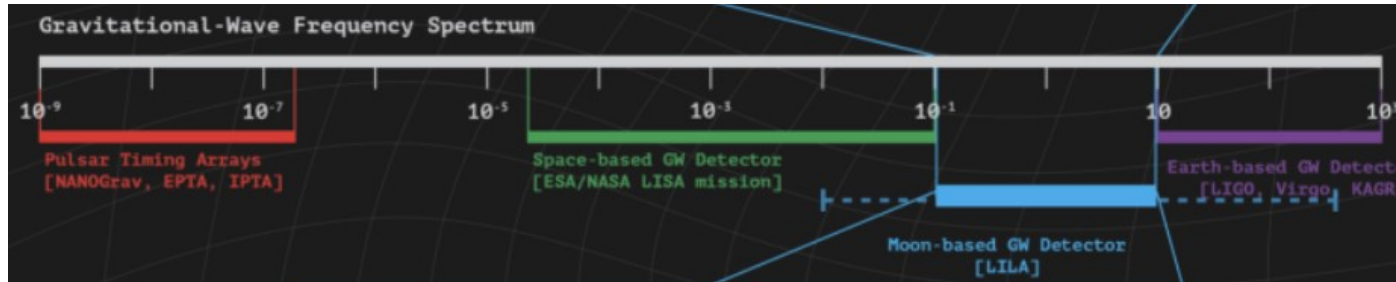
The combination of

- distances and masses explored
- number of detections
- detections with very high SNR

will provide a wealth of data expected to generate **revolutions in astrophysics, cosmology**

Going extraterrestrial: the Moon

- Lunar Gravitational Wave Antenna concept
- Laser Interferometer Lunar Antenna



Further reading

Jan Harms, “Terrestrial gravity fluctuations” Living Reviews of Relativity.

Peter Shearer, “Introduction to seismology”, Cambridge University Press

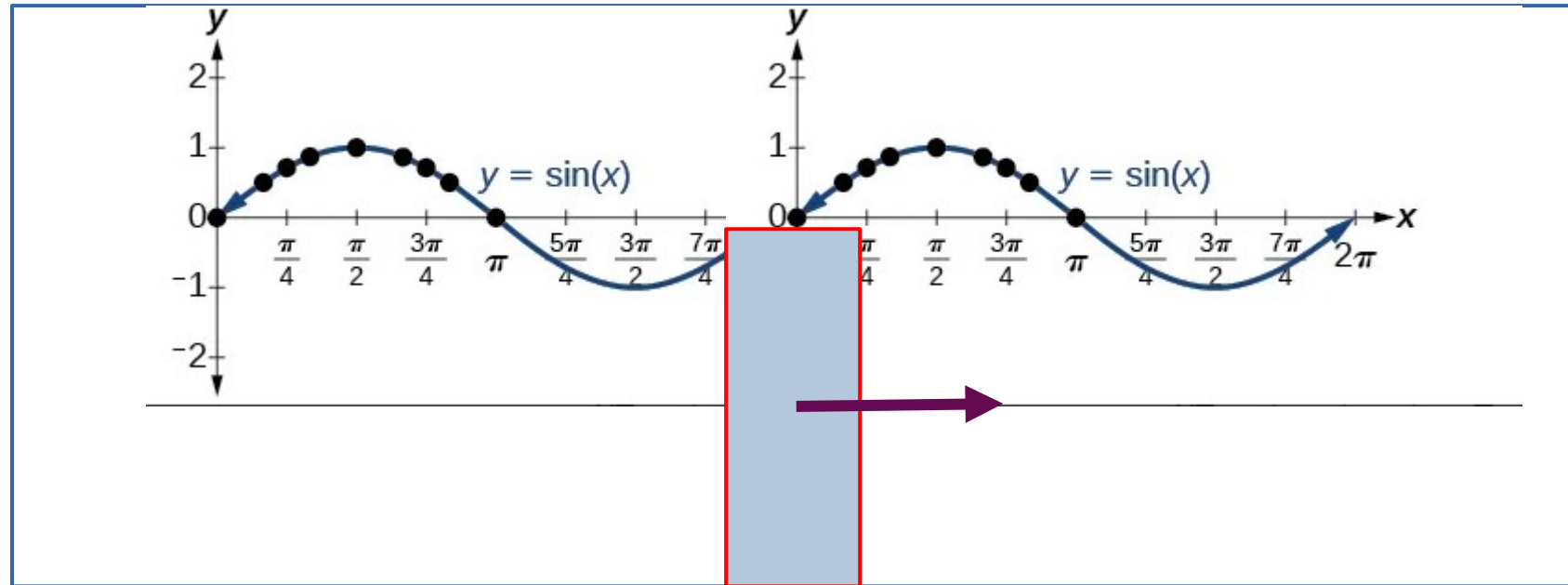
Hands on

Infrasound induced Newtonian Noise

$$\begin{aligned}
S_{\text{tot}}(\vec{r}_0, \omega) = & S_{\text{int}}(\vec{r}_0, \omega) + S_{\text{ext}}(\vec{r}_0, \omega) = \\
& \frac{1}{(L\omega^2)^2} S_{\delta p}^{\text{int}}(\omega) \langle |a_{\text{int}}(z_0, \theta, \phi, \omega)|^2 \rangle + \\
& \frac{1}{(L\omega^2)^2} S_{\delta p}^{\text{ext}}(\omega) \langle |a_{\text{ext}}(z_0, \theta, \phi, \omega)|^2 \rangle, \quad (15)
\end{aligned}$$

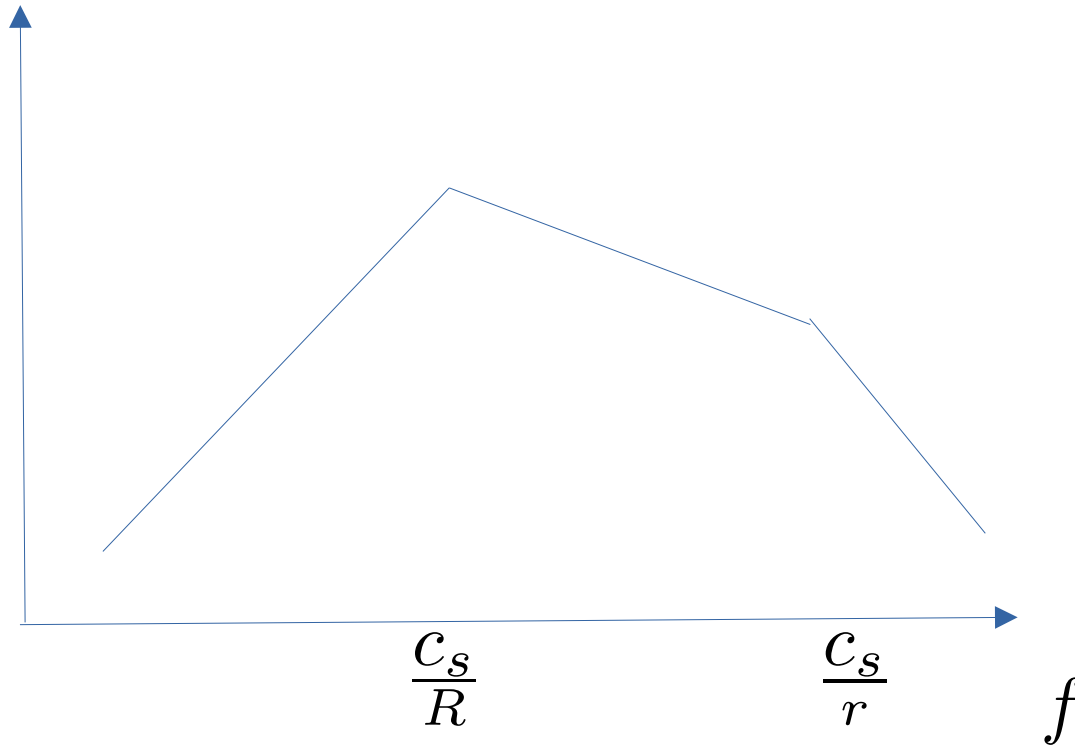
Important scales

Cavern size R , wavelength λ ,



Vacuum tower
width r , height h

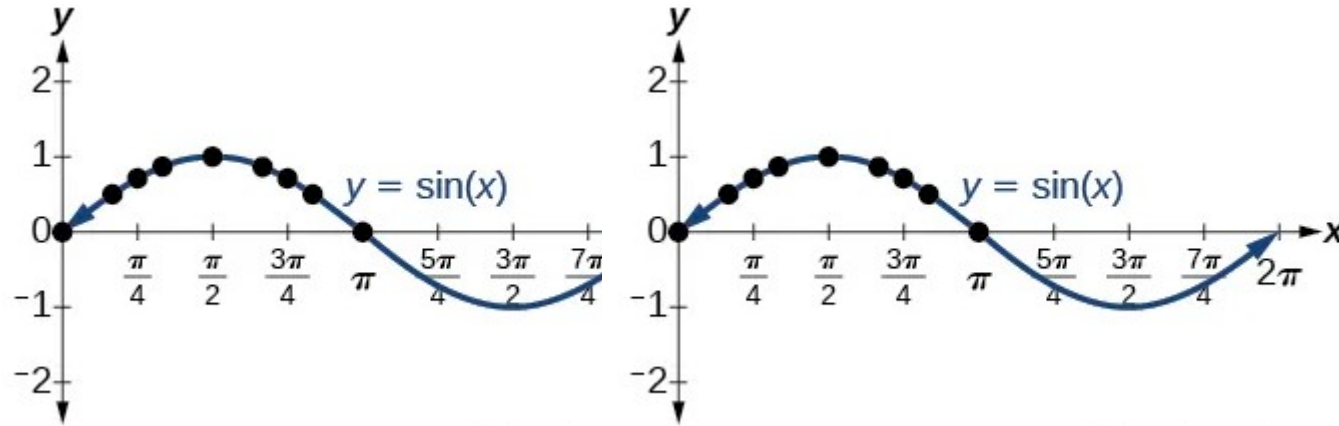
Transfer function



Mitigation

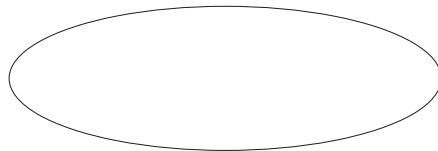
- Make R small - divide caverns or make them small
- Make caverns quiet – what is the ultimate silence limit with all machinery and ventilation?
- Total fantiasy: decrease pressure in caverns :-)

The case of the surface waves

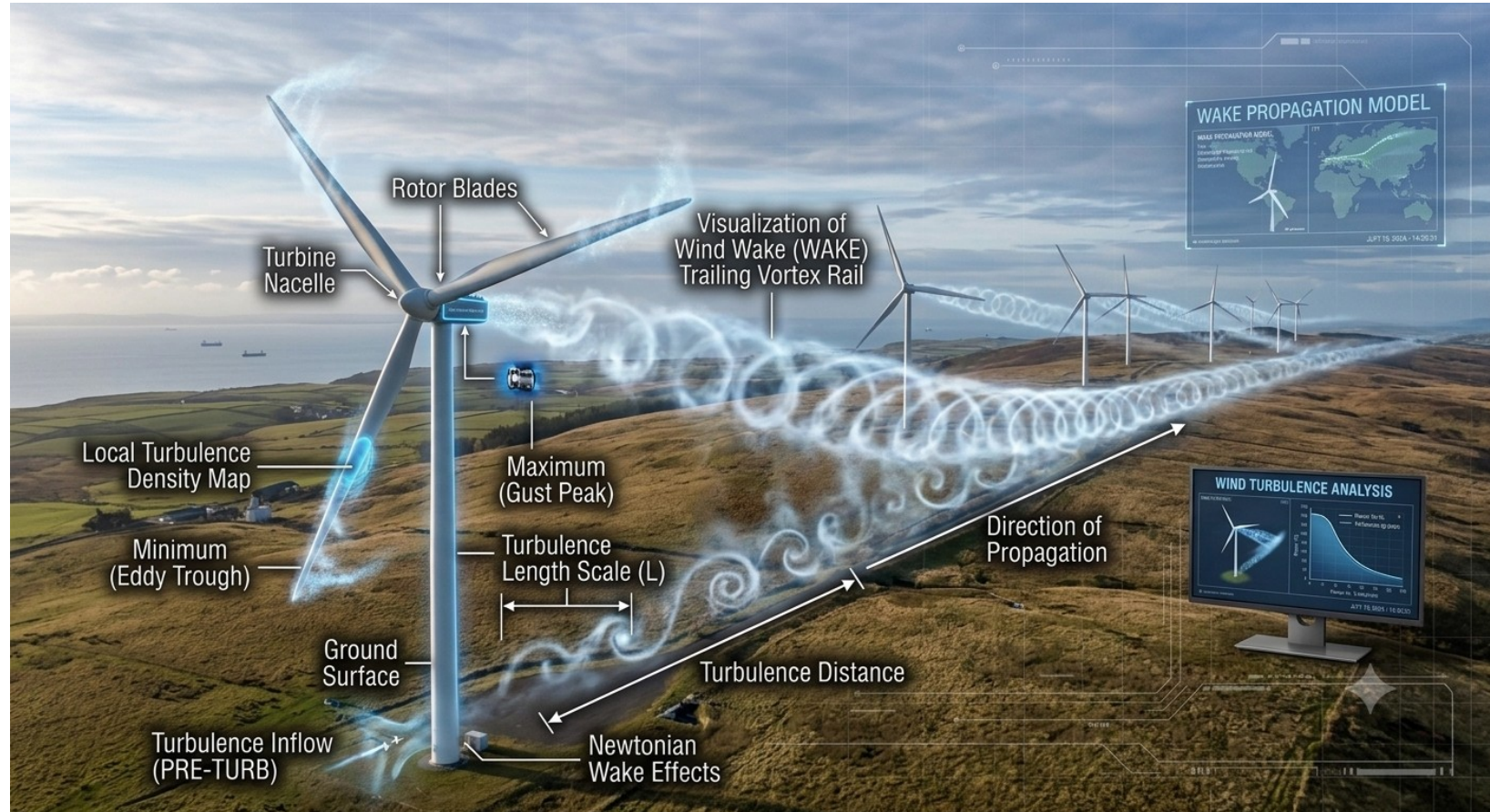


Depth D
wavelength λ ,

But what are the integration limits?



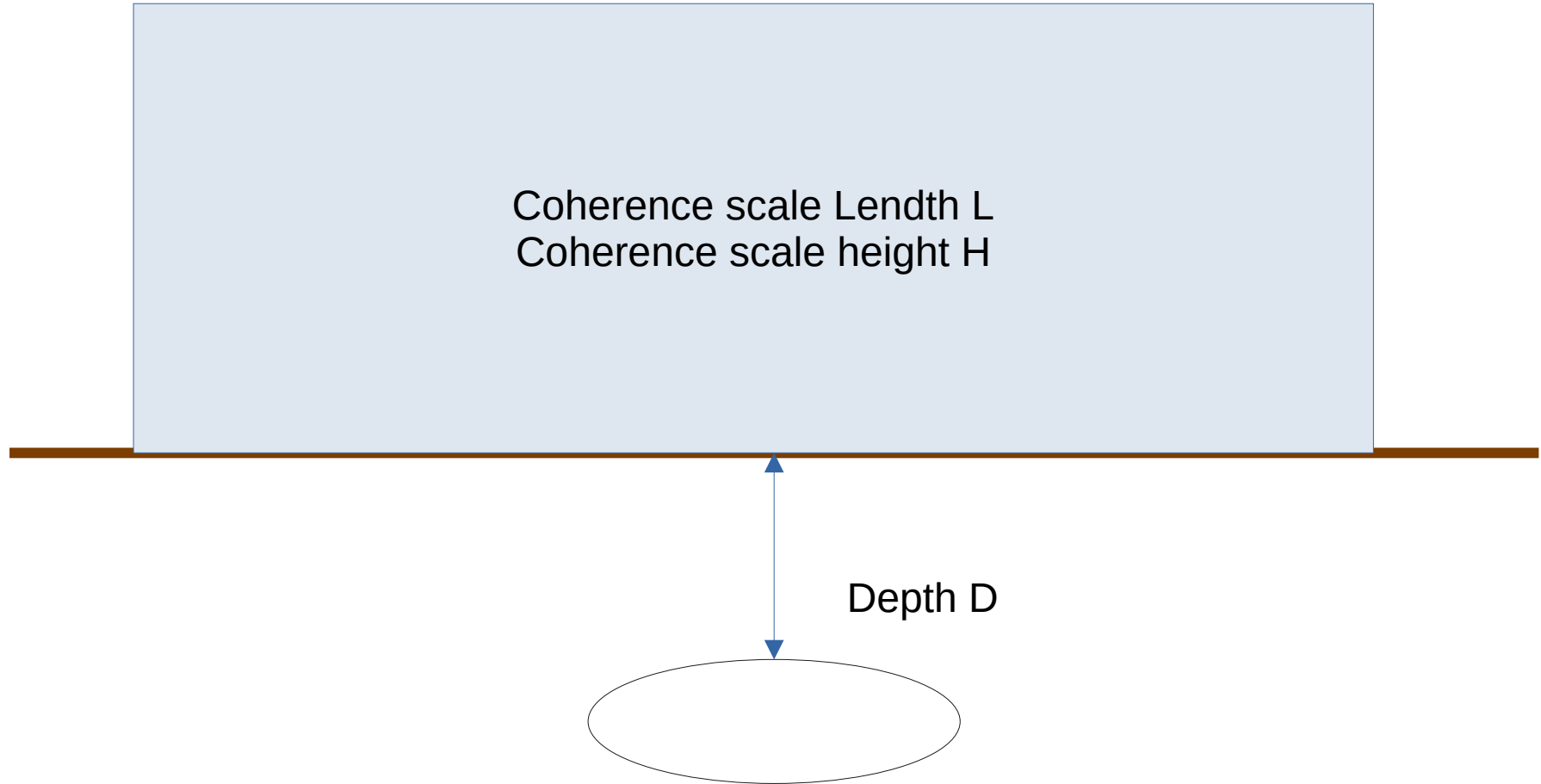
How far a wave is wave?



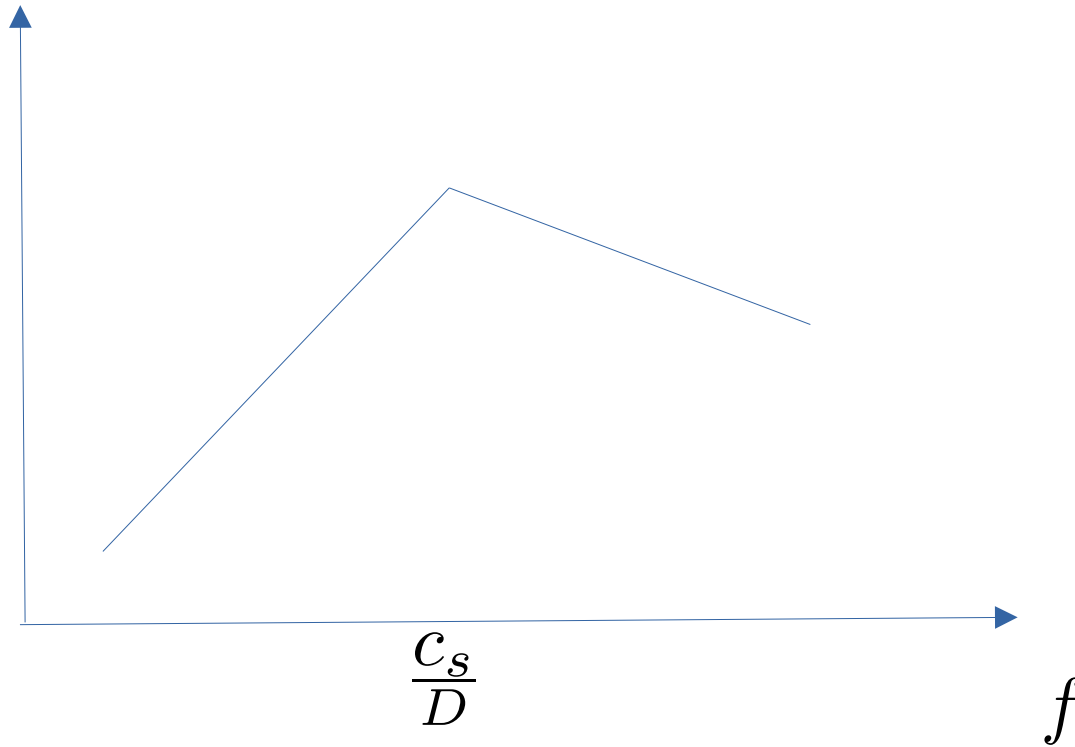
What we need to measure

- Infrasound wave spectrum, and variability
- Coherence length scale of the wave
- Coherence height scale of the waves

Integration region



Transfer function



Level depends on
volume of integration
 $H \cdot L \cdot L$

Real case - cavern

DarkSide campaign

Measure the seismic and infrasound noise at the DarkSide location

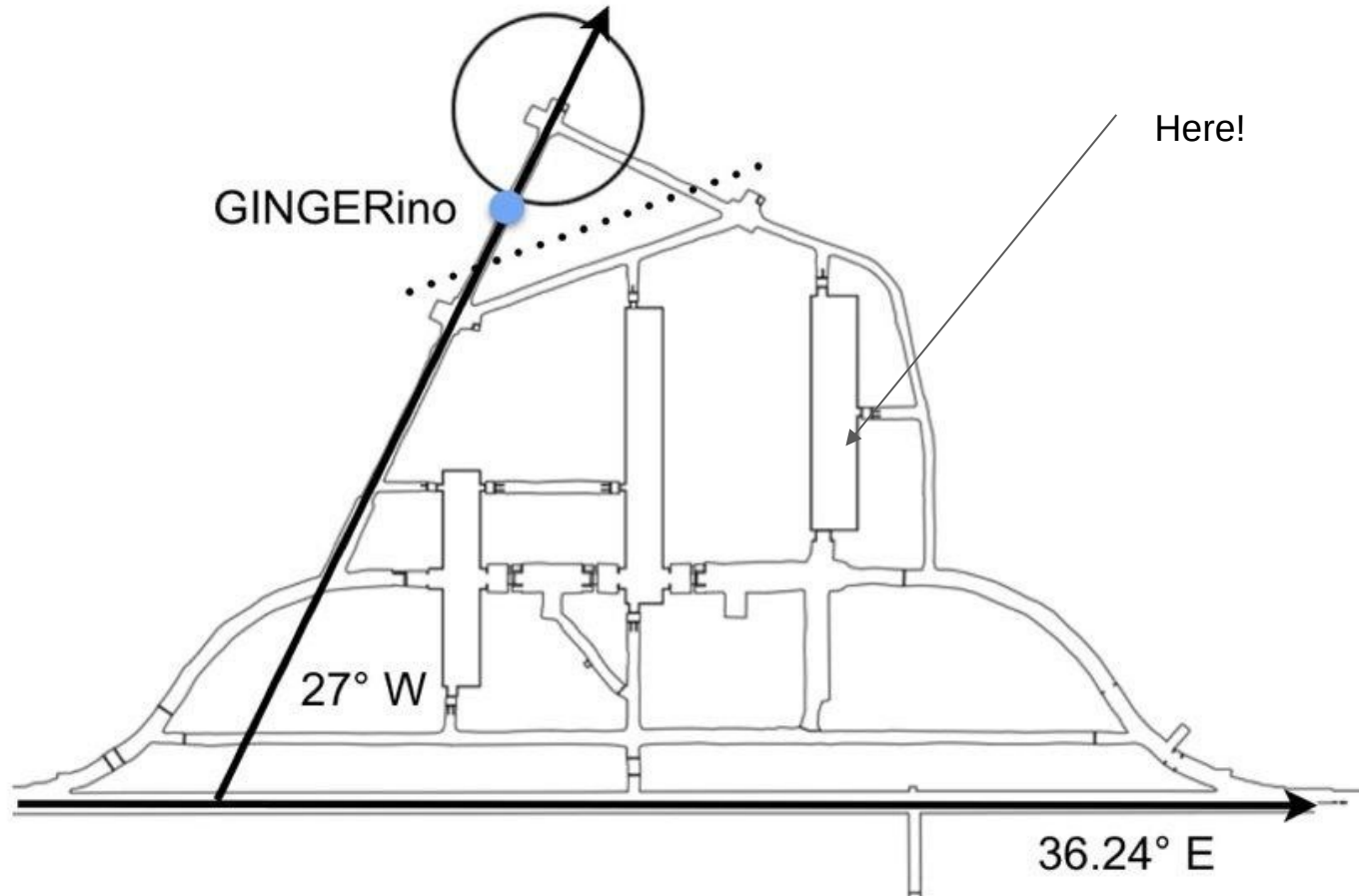
3 week campaign

2 microphones

Hall 1 with existing experiments

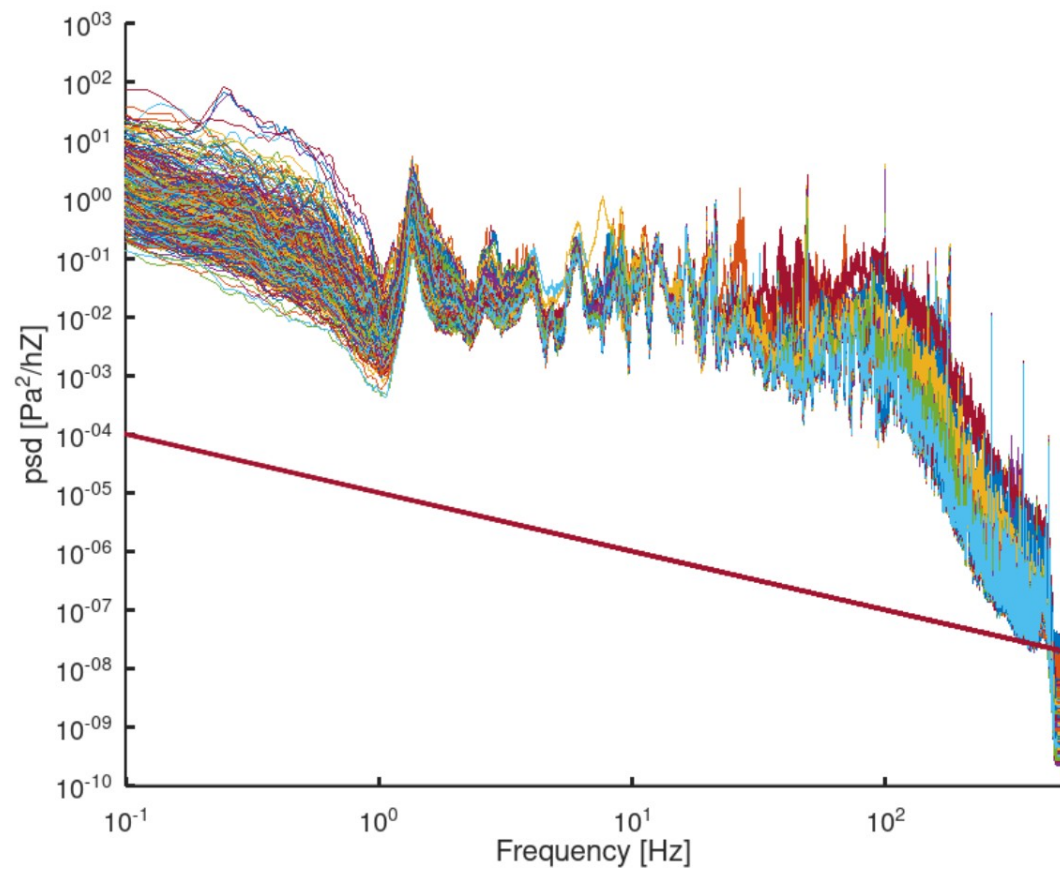


Where were the measurements taken?



Sound spectra

Ambient noise model
Bowman et al. 2005



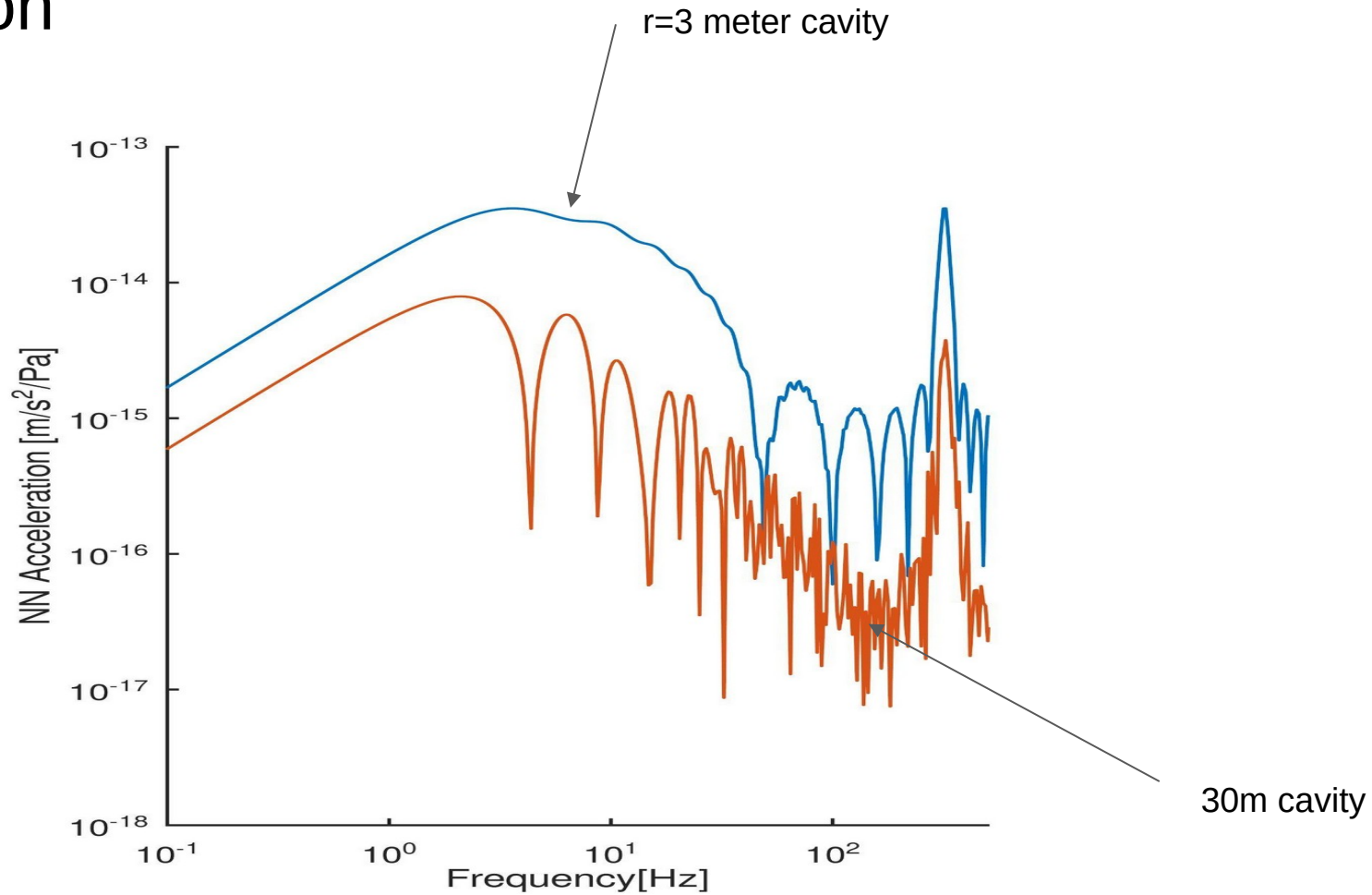
Calculating the Newtonian noise

1. Assume a geometry of detector: hall 100m x 20m x 25 m
2. Assume position of test mass in the center 3 m above the ground
3. Calculate NN acceleration per unit pressure fluctuation as function of frequency - straightforward numerical calculation
4. Assume four test masses have similar uncorrelated noise
5. Follow the calculations in Fiorucci et al. 2018

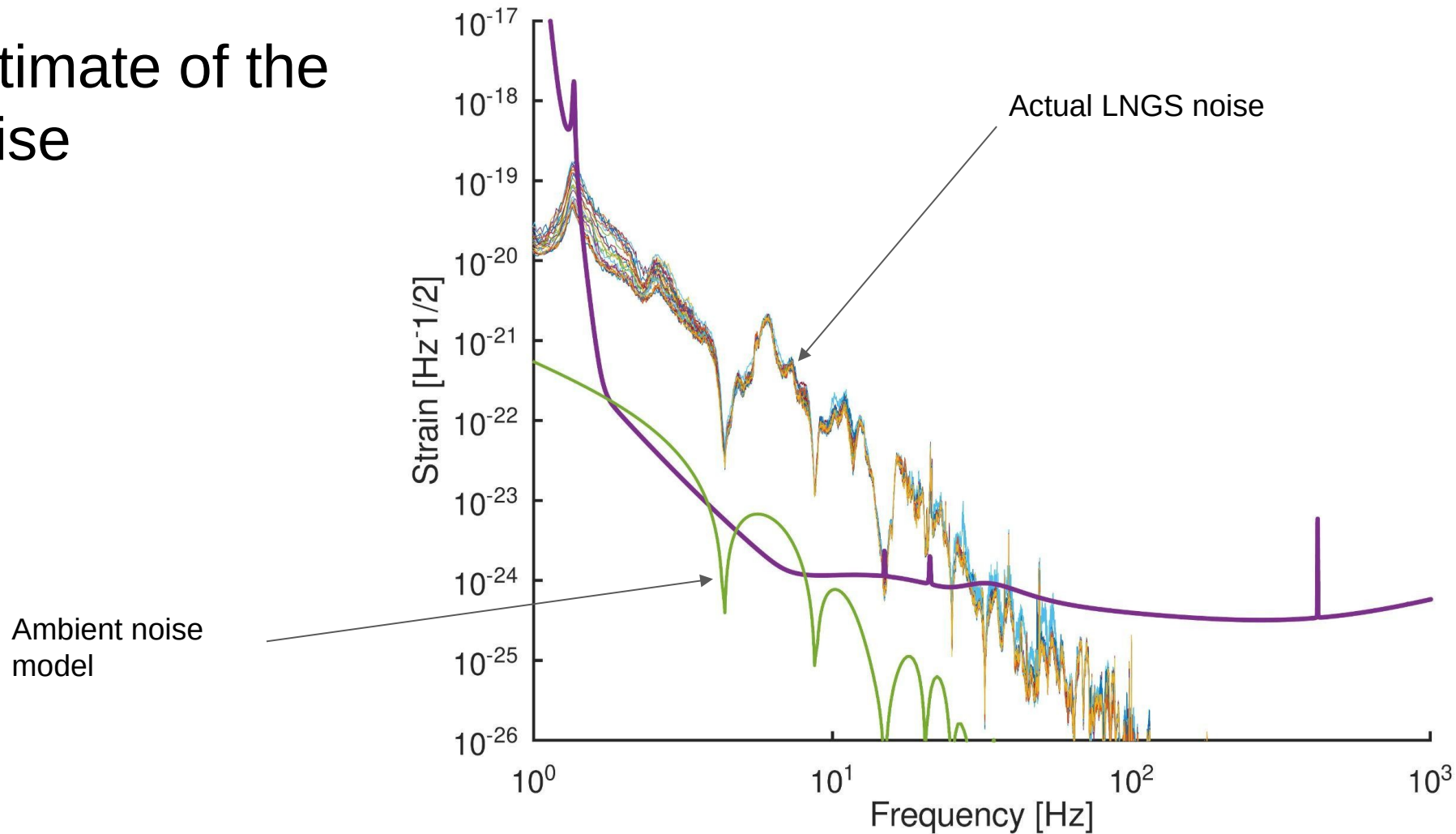
$$S_{\text{tot}}(\vec{r}_0, \omega) = S_{\text{int}}(\vec{r}_0, \omega) + S_{\text{ext}}(\vec{r}_0, \omega) =$$
$$\frac{1}{(L\omega^2)^2} S_{\delta p}^{\text{int}}(\omega) \langle |a_{\text{int}}(z_0, \theta, \phi, \omega)|^2 \rangle +$$
$$\frac{1}{(L\omega^2)^2} S_{\delta p}^{\text{ext}}(\omega) \langle |a_{\text{ext}}(z_0, \theta, \phi, \omega)|^2 \rangle, \quad (15)$$

$$S_{\text{tot}}^{\text{Adv}}(\omega) = 2 \times S_{\text{tot,CEB}}(\omega) +$$
$$S_{\text{tot,NEB}}(\omega) + S_{\text{tot,WEB}}(\omega)$$

NN acceleration



Estimate of the noise



External noise

