

# A new view on differentially rotating neutron stars in general relativity

Dorota Gondek-Rosińska

Institute of Astronomy  
Univeristy of Zielona Góra

in collaboration with:

M. Ansorg(TPIUJ), I. Kowalska(OA,UW), M. Kucaba (IA,UZ),  
A. Studzińska (IA,UZ),M. Szkudlarek (IA,UZ), L. Villan (UFR)



# Differential rotation

## Astrophysical arguments

Differential rotation plays important role in :

- collapse of massive stars (and observed supernova),
  - NS binary merger.
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- the dynamics of compact astrophysical objects is a rich and complex topic involving **nuclear matter at very high density** and **gravitation in the strong field regim**
  - even in stationary situations, differential rotation can make the study of their structure and life much **more complicated** than in Newtonian physics
  - **realistic and precise numerical simulations** are needed and should enable to learn a lot on both astrophysics and fundamental physics
  - problems are challenging not only from the physical points of view, but also from the mathematical and numerical ones

# Equilibrium models of differentially rotating NS

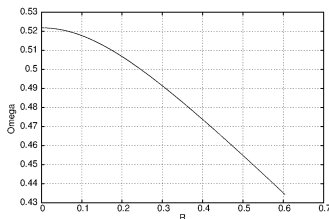
Astrophysically motivated (consistent with the core collapse results) a simple differential rotation law proposed by Komatsu, Eriguchi, Hachisu [1989]:

$$F(\Omega) = R_0^2(\Omega_c - \Omega)$$

$R_0$  length describing the degree of differential rotation ( $r = R_0: \Omega = \Omega_c/2$ ,  $\Omega_c$  is the 'angular velocity on the axis'. We use  $A^{-1} = \tilde{A} = R_e/R_0$  ( $R_e$  - equatorial radius, for **uniform rotation**  $R_0 \rightarrow \infty$ ,  $\tilde{A} \rightarrow 0$ ).

A polytropic EOS:  $P = K\rho^\Gamma$   
with a polytropic index  $\Gamma = 2$

Relativistic multidomain spectral code Flatstar  $\rightarrow$  **axisymmetric and stationary** solutions for broad ranges of stellar densities and degree of differential rotation  
 $0.01 < A^{-1} < 1.5$



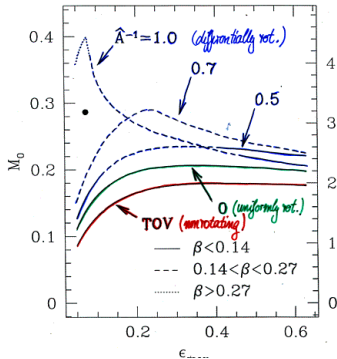
# The effect of the rotation on the maximum mass of NS

The effect of **rigid** rotation on the  $M_{max}$ :

**NS** up to 20% (e.g. Cook et al. 1994)

**SS**  $\sim$  44% (Gourgoulhon et al. 1999, Gondek-Rosińska et al. 2000)

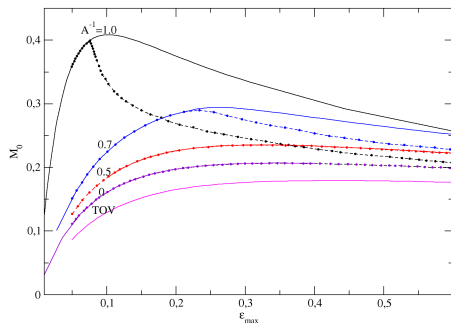
The effect of **differential** rotation on the  $M_{max}$  (Baumgarte et al. 2000, Morrison et al. 2004) depends on the degree of differential rotation  $A^{-1}$



Differential rotation significantly increases the maximum allowed mass of NS and may temporarily stabilize the remnant of BNS merger- delayed collapse. The outcomes - no, delayed, or prompt collapse depend on EOS, the maximum density and  $A^{-1}$ . GW observations of coalescing BNS or a core collapse may be able to distinguish these outcomes.

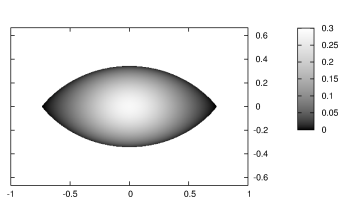
## Differentially rotating NS - comparison

Highly accurate and stable code (Ansorg, Gondek-Rosińska, Villain, 2009) allows to construct relativistic models of differentially rotating NS for whole parameter space (broad ranges of degrees of differential rotation, maximal densities and  $r_{\text{ratio}}$  from 1 to zero.

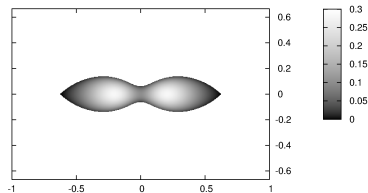


Solid lines - our results (Gondek-Rosinska et al. [2015], in preparation) dotted lines- Baumgarte, Shapiro, Shibata [2000] Good agreement for modest degree of differential rotation and/or small densities.

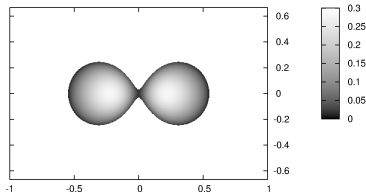
# Types of differentially rotating neutron stars



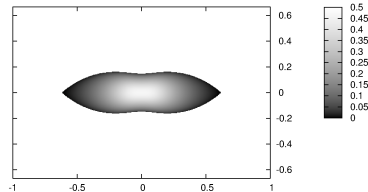
Type A,  $\tilde{A} = 0.3$  at mass-shed limit



Type B,  $\tilde{A} = 0.3$  at mass-shed limit



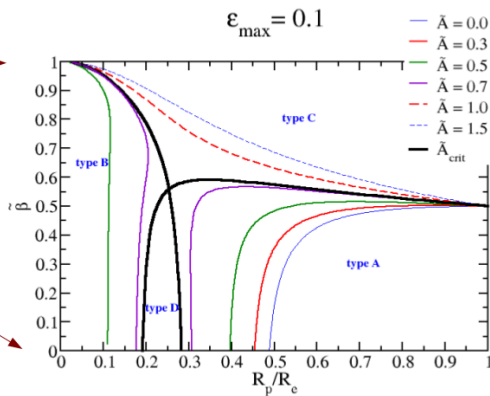
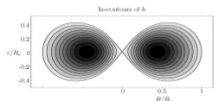
Type C,  $\tilde{A} = 1.0$  and  $r_{ratio} \sim 0$



Type D,  $\tilde{A} = 0.5$  at mass-shed limit

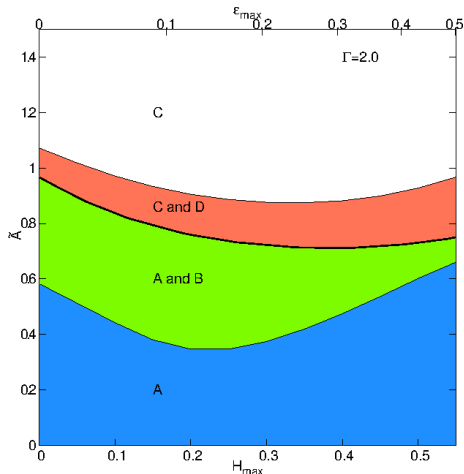
Studzińska, Gondek-Rosińska, Kucaba, Ansorg, Villain, 2015, in preparation

# Four types of differentially rotating neutron stars



$\tilde{\beta}$  - the shedding parameter,  $\tilde{\beta} = 0$  for mass-shedding limit;  $\tilde{\beta} = 0.5$  for non-rotating NS and 1 for toroidal models. A solid line corresponds to  $\tilde{A}_{\text{crit}}$ , the separatrix. Results for fixed maximum density-four types of solution: A, B, C and D

# Types of differentially rotating neutron stars

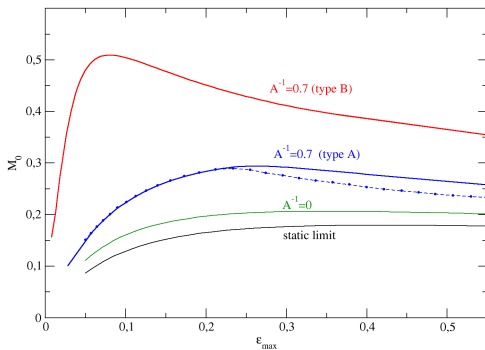


- **Type A** exist for  $\tilde{A} < \tilde{A}_{crit}$ , start at static configuration and ends at mass-shed limit,
- **Type C** exist for  $\tilde{A} > \tilde{A}_{crit}$ , start at static case and terminates for  $R_p/R_e = 0$ ,
- **Type B** also exist for  $\tilde{A}_B < \tilde{A} < \tilde{A}_{crit}$
- **Type D** exist for  $\tilde{A} > \tilde{A}_{crit}$ , for narrow range of  $\tilde{A}$ .

Gondek-Rosińska, Kowalska, Ansorg, Villain, 2015, in prep

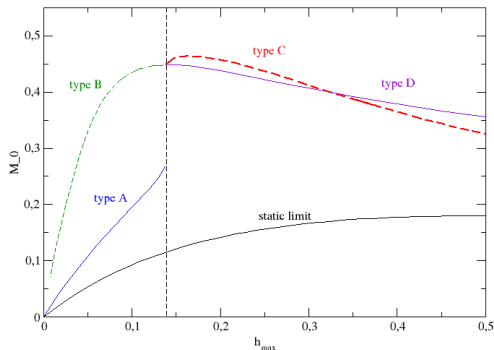


## The maximum mass for $\tilde{A} = 0.7$ , types A and B



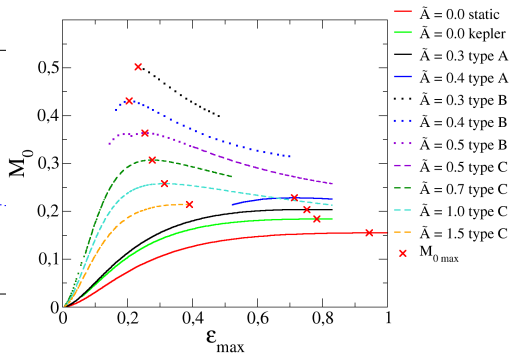
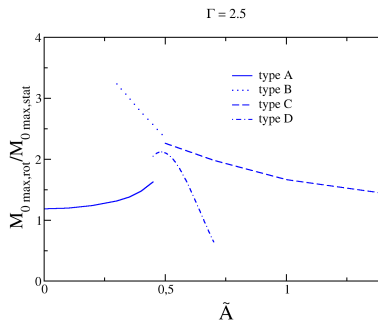
Maximum mass of new type B is much higher than maximum mass for type A with the same degree of differential rotation (eg. for polytrope with  $\Gamma = 2.0$ ).

## The maximum mass for $\tilde{A} = 0.8$ , types A, B, C, D



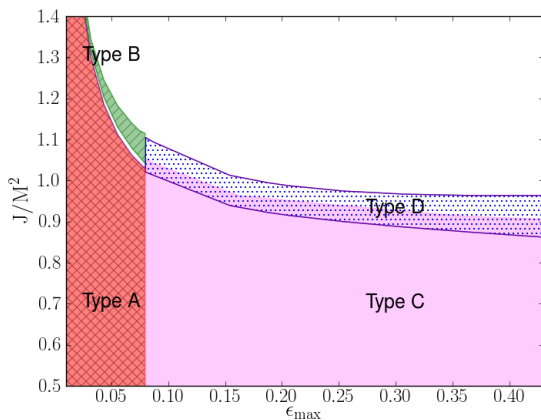
Maximum mass strongly depend on the type of solution. For type B is much higher than maximum mass for type A with the same degree of differential rotation. Type C and D have comparable masses (eg. for polytrope with  $\Gamma = 2.0$ )

# The maximum mass of differentially rotating NS



For type A the maximum mass is increasing function of the degree of differential rotation while for type B and C decreasing. The maximum mass is obtained for type B, the new type of configurations.

## Are they stable?



Areas of Kerr parameter for  $\Gamma = 2.0$  and  $\tilde{A} = 0.8$ . For  $J/M^2 > 1$  NS can be temporarily stabilized by differential rotation (Baumgarte et al. 2000, Giacomazzo et al. 2011).

## Summary

Using highly accurate code based on spectral method (Ansorg, Gondek-Rosińska, Villain [2009]) we have calculated relativistic models of axisymmetric rotating NS for broad ranges of degree of differential rotation

- We have found new types of solutions (existing for modest degree of differential rotation and  $r_p/r_e \lesssim 0.3$ ), which were not considered in previous works based on other algorithms, due to complexity of the problem and numerical limitations
- The maximum mass of differentially rotating NS for given EOS depends on the degree of differential rotation and a type of solution (classified as A,B,C,D)
- Differential rotation significantly increases up to 400% the maximum allowed mass of NS and may temporarily stabilize a new born protoneutron star or a remnant of binary NS merger.
- The highest increase of mass is obtained for the newly found types of differentially rotating NS
- Gravitational waves observations of coalescing binary NS may be able to distinguish the outcomes; prompt collapse, delayed collapse, a stable NS

## Work in progress

- Calculations for realistic finite temperature EOS
- Initial data for stability analysis (2D, 3D)
- Consider as sources of gravitational waves
- Testing different rotation law

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## Our results for differentially rotating NS (type A and C)

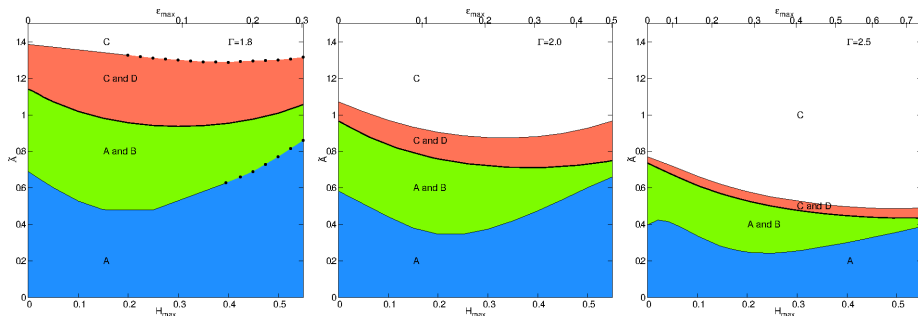


To construct a single NS for given EOS we need 3 parameters e.g.  $(\rho_{\max}, r_{\text{ratio}}, A)$  (for rigid rotation only 2 e.g.  $(\rho_c, \Omega)$  or  $(\rho_c, r_{\text{ratio}})$ ) Depending on the value of  $A^{-1}$  the maximum mass is obtained close to the mass-shed limit  $\rightarrow$  **type A** (solid lines) or for toroidal configurations ( $R_p/R_e = 0$ )  $\rightarrow$  **type C** (dashed lines). Existence of **separatrix**  $A_{\text{crit}}$



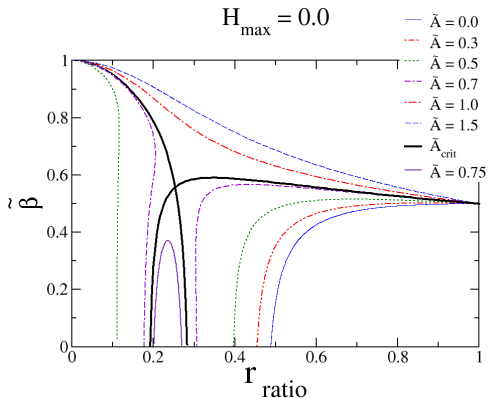
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# The effects of EOS on types for differentially rotating NS



The stiffer EOS is the larger region of type C configurations and narrower for types A,B and D

# Classifications of differentially rotating neutron stars



$\tilde{\beta}$  is 0 for mass-shedding limit; 0.5 for spheroidal and 1 for toroidal models.  
A solid line corresponds to the separatrix, type A - below separatrix, right corner; type B below separatrix left side; type C - above separatrix

# Effects of differential rotation and EOS on the maximum mass of NS

Depending on EOS  
and degree of  
differential rotation  
we can obtain very  
high increase of  
maximum mass.

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