

# Thermodynamics of friction

Noa Mitsui

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- tectonics & earthquakes
- theory of earthquakes
- relation between earthquakes and friction

## 2. Purpose: thermodynamic modeling of rock friction

## 3. Research

- introduction: rock experiments
- thermodynamic modeling

## 4. Summary

# Tectonics & earthquakes in the world

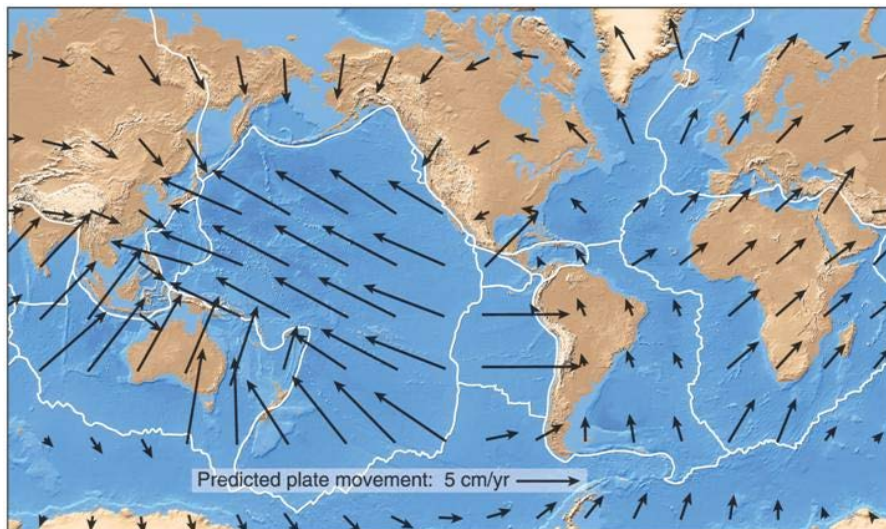


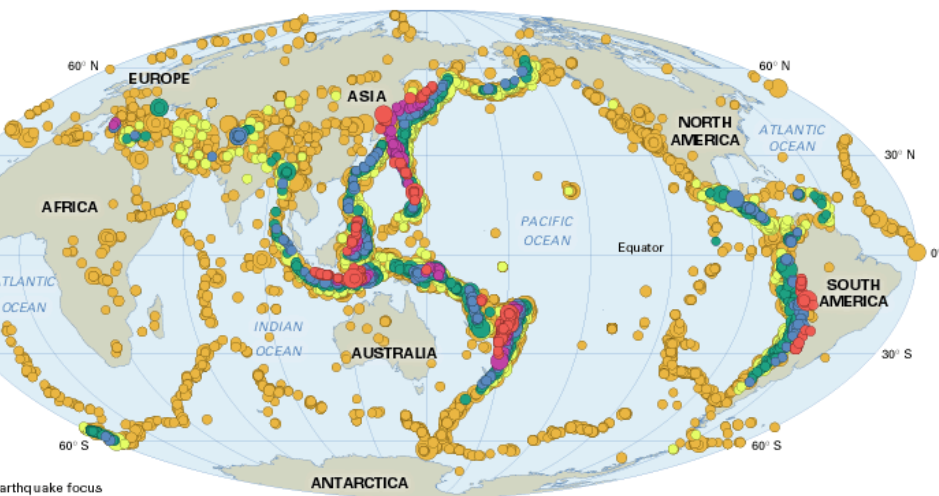
Plate movements and their boundaries

- Plates move relatively at several cm/yr
- Japan locates on some boundaries

GI earthquakes of magnitude 5.5 and greater

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Fig 12.37



earthquake focus

- mi
- 0
- 21
- 43
- 93
- 186
- 311
- 497

0 1000 2000 3000 mi

0 2000 4000 km

Scale is true only on the Equator.

Earthquake epicenter ( $M_{5.5} <$ )

$$M = -3.2 + 0.67 \log_{10} E \quad (E: \text{energy})$$

# Tectonics & earthquakes in the world

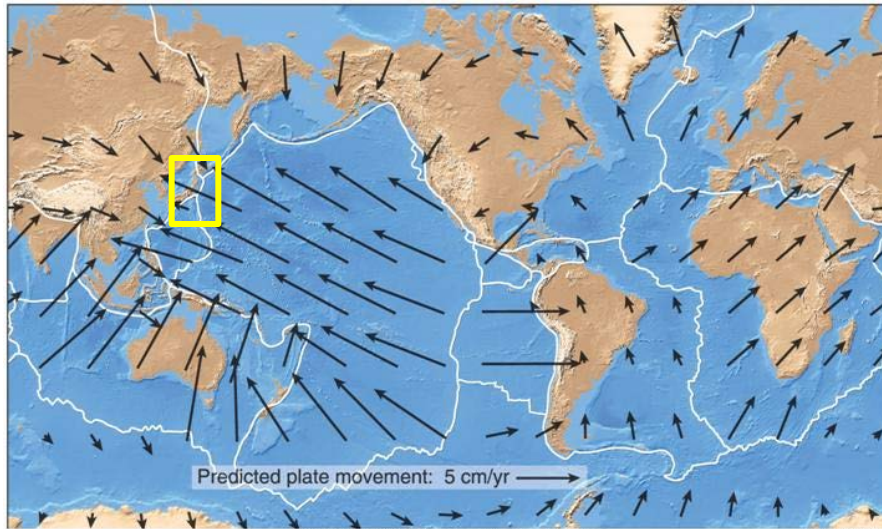


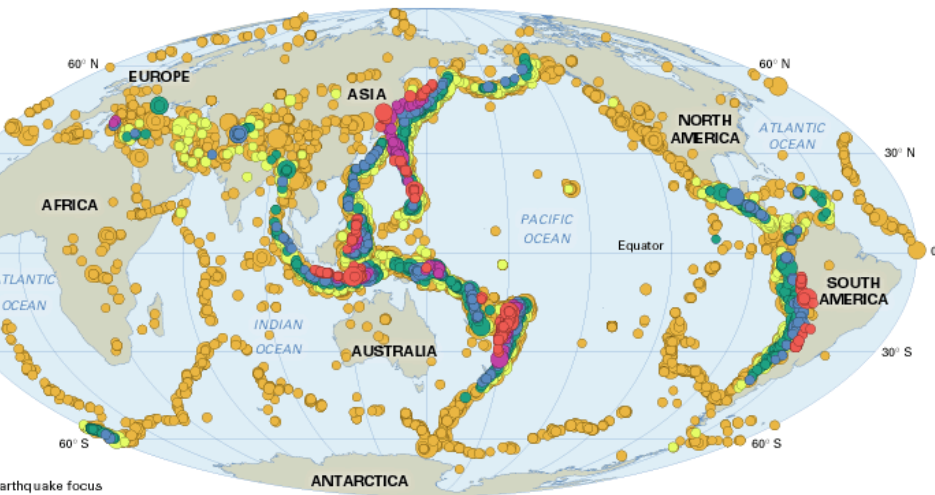
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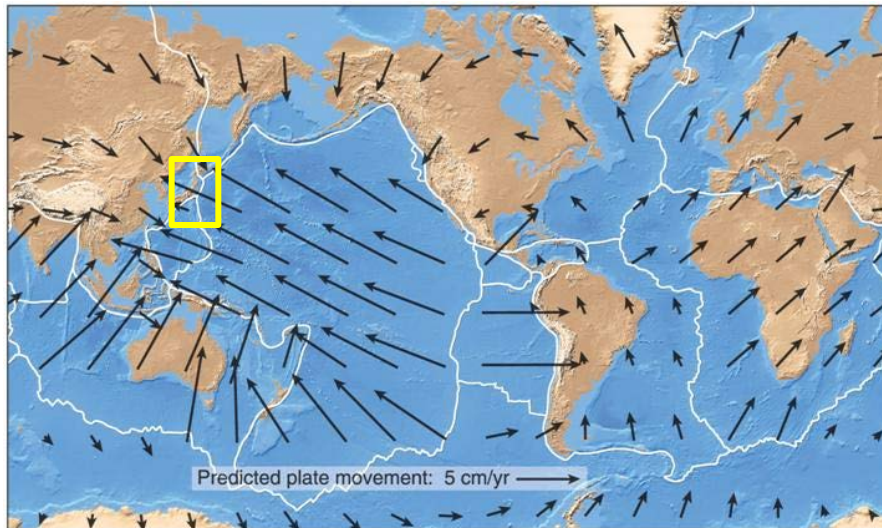


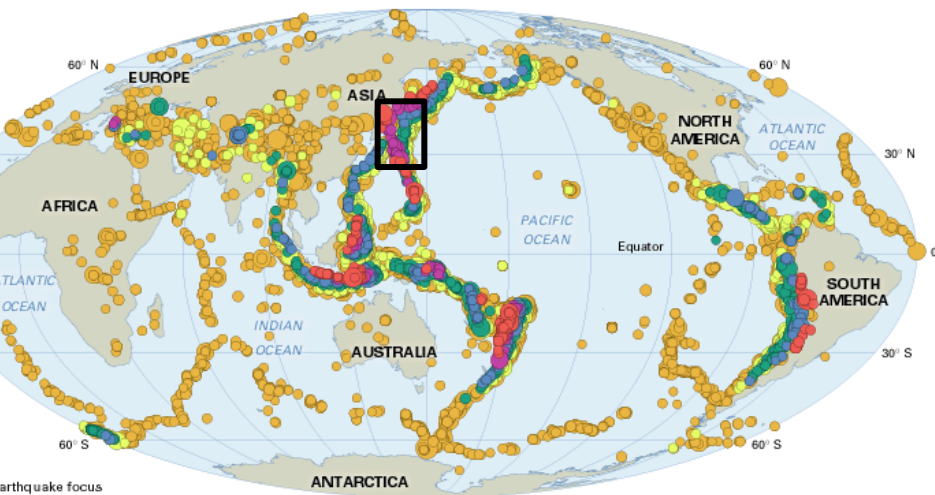
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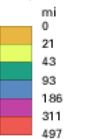
Fig 12.37

earthquakes of magnitude 5.5 and greater



- Many earthquakes occur around Japan

earthquake focus



0 1000 2000 3000 mi

0 2000 4000 km

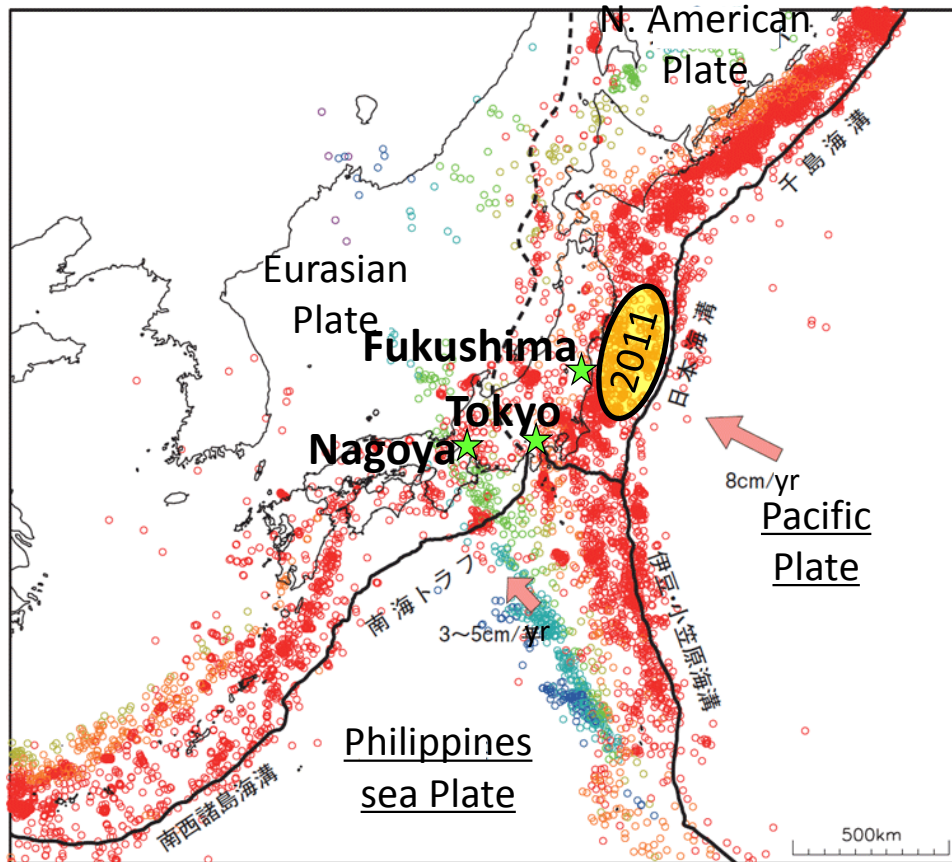
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Earthquake epicenter ( $M_{5.5} <$ )

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# Difficulty in understanding of earthquake

earthquakes distribution (seismicity)  
along plate boundaries



震央 (1998年~2007年、M4以上) は、気象庁による。  
矢印は、ユーラシアプレートに対する太平洋プレートとフィリピン海プレートの相対的な進行方向と速さを示す。  
太い実線はプレート境界、破線は不明瞭なプレート境界を示す。

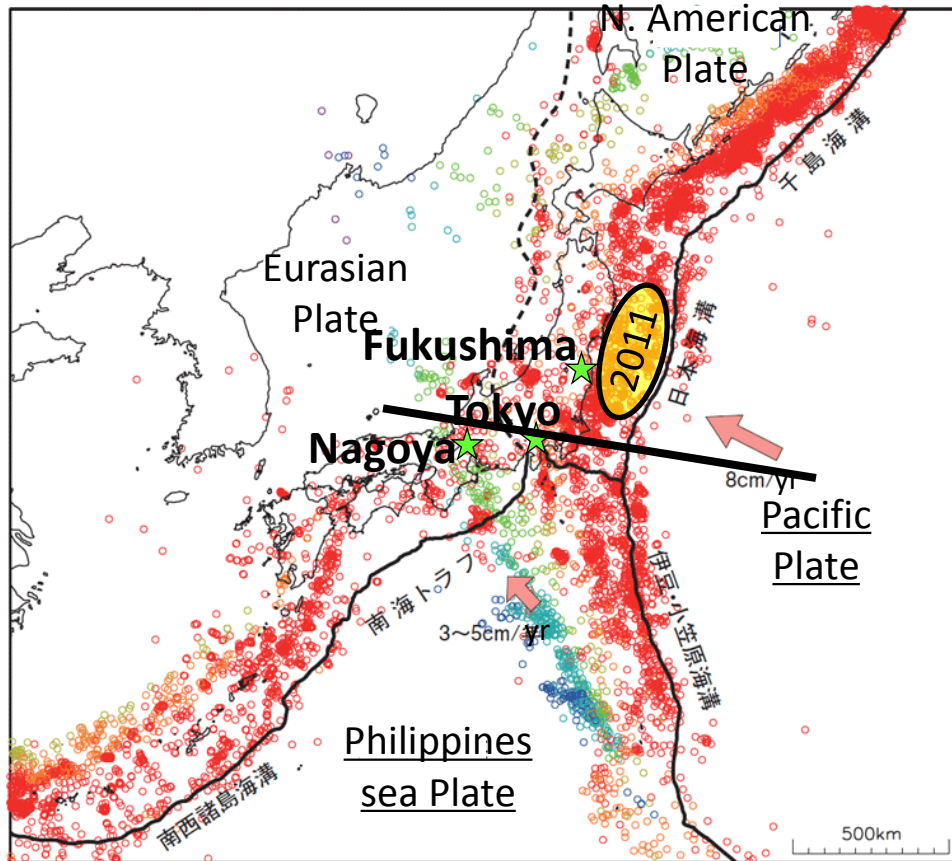
- People want to know “WHEN & WHERE” earthquakes will happen

Difficulty of the forecast  
||  
Incompleteness of theory

(Source area= ruptured area  
estimated by detected seismic waves)

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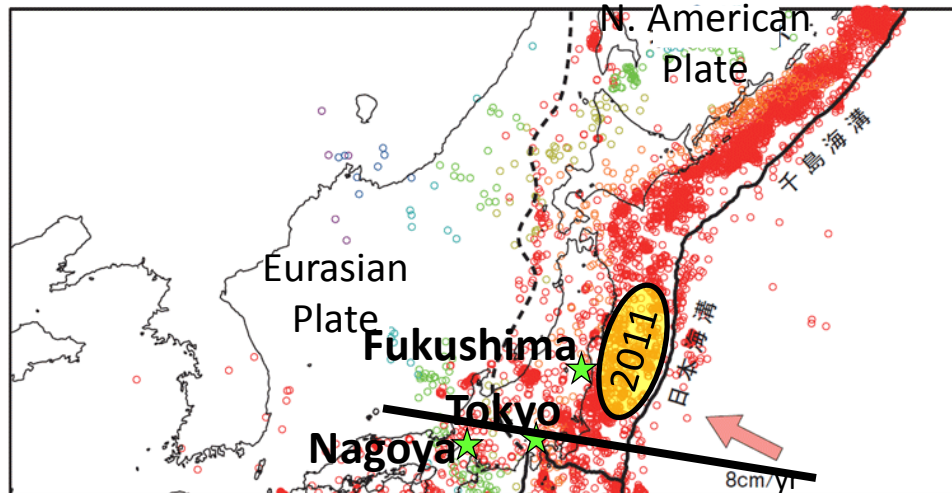
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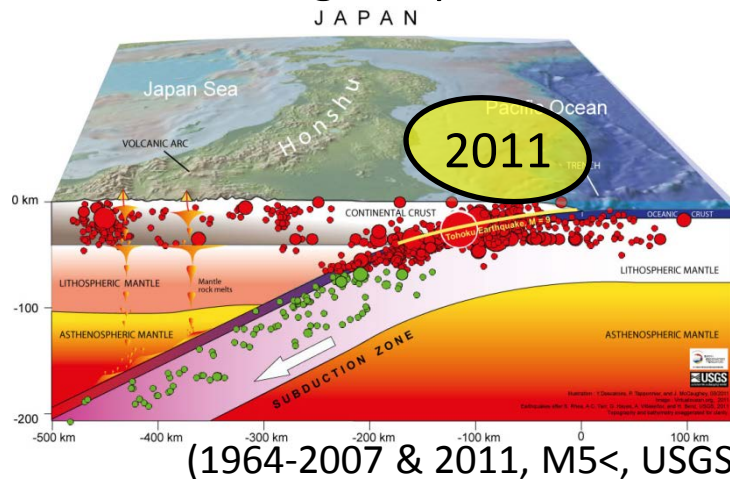
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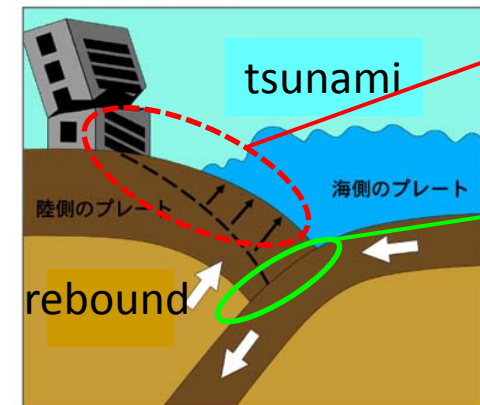
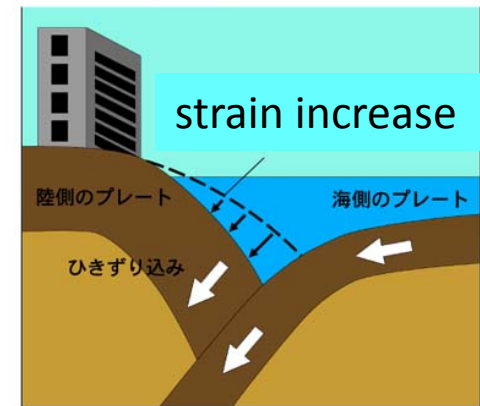
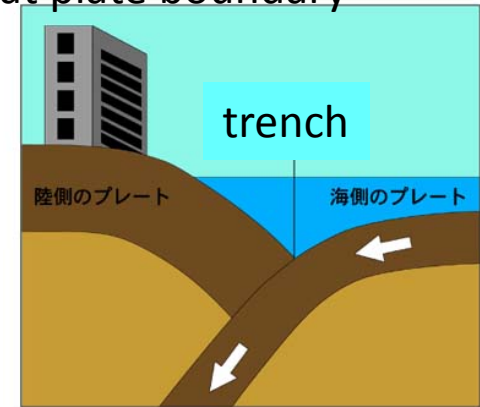
Cross section along the plate movement





# Incomplete theory = elasticity

Schematic diagram of deformation  
at plate boundary



All strain released  
Slip only at boundary  
Only in theory

- current bases of seismology:  
All strain released by slip  
at contact surface  
|  
plate boundary

It cannot explain  
small earthquakes (=seismicity)  
occurring in the plate  
↓  
realistic deformation theory  
is necessary (= motive)

# Main theme of today's talk

☆ How we can obtain deformation theory of medium?

(bases of the earthquakes occurrences)

fracture and deformation in the earth's crust

Research object: friction law in rock experiments

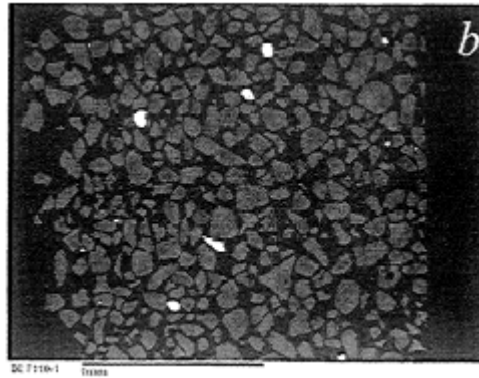
- earthquakes are compared to frictional slips along the tectonic plate boundary
- easiness to understand: rock experiment > earthquakes

I will focus on the rate- and state-dependent friction law

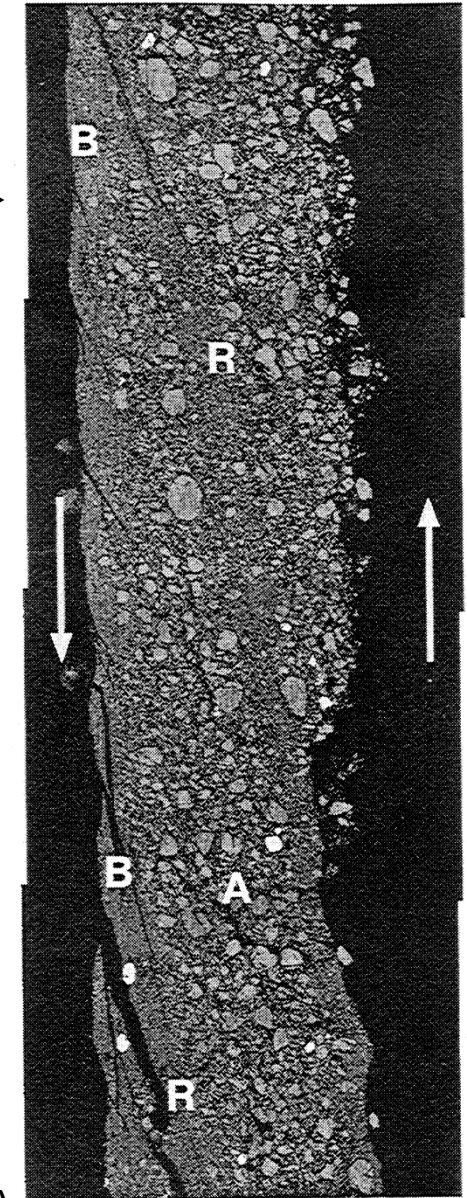
(Dieterich, 1979)

# Sand particles in frictional layer between rocks

Before dislocation



After dislocation



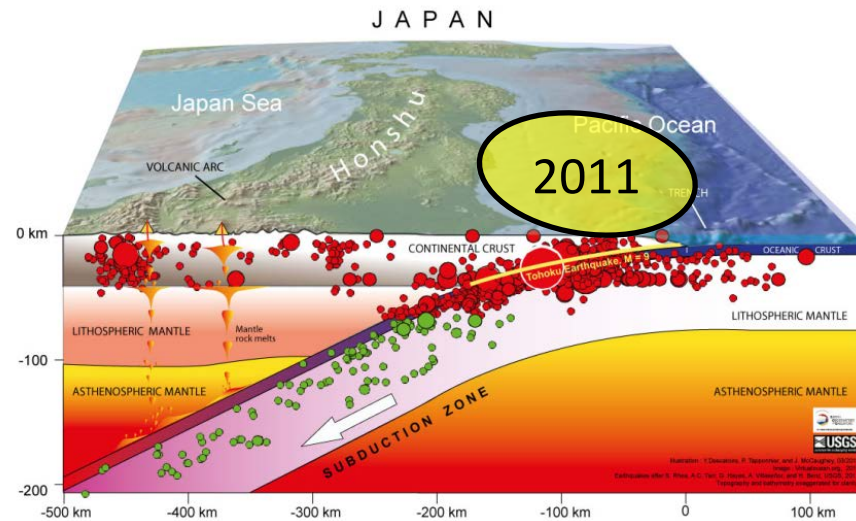
- Even in the small frictional layer, sand particles are deformed, crushed, compacted.
- These phenomena probably causes the complexity of friction
- The mechanism of friction can be related to that of earthquakes

(Mair & Marone, 1999)

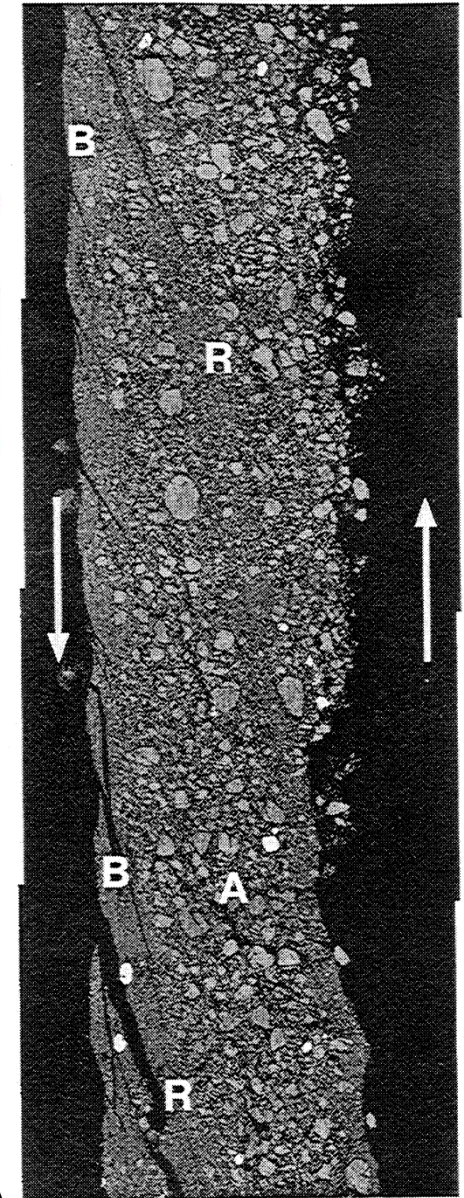
1mm

(from Mair and Marone, 1999)

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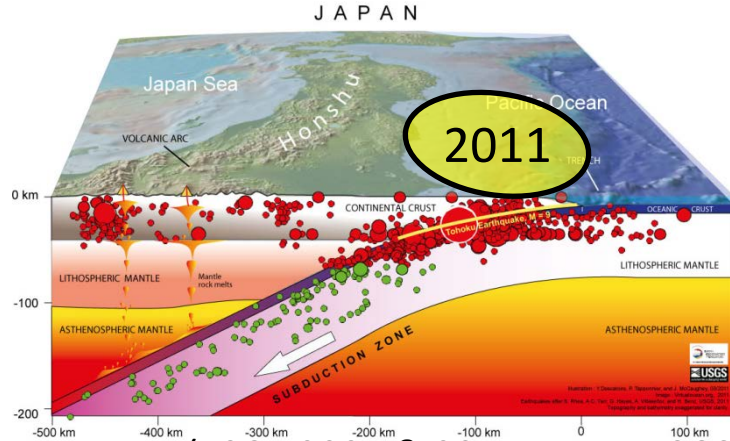
(Mair & Marone, 1999)

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# Wideness of earthquakes

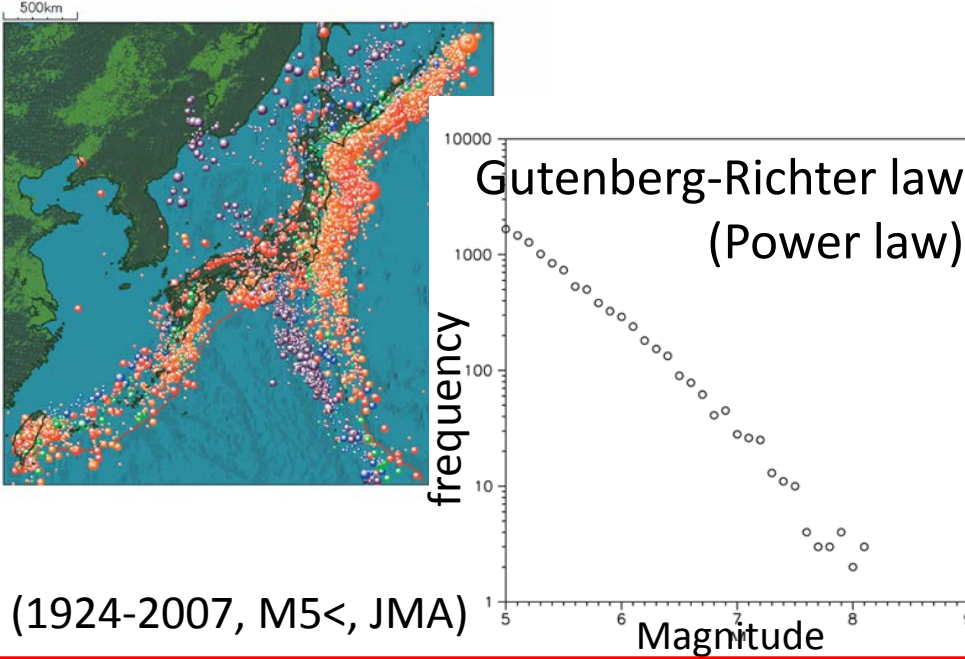
Cross section along the plate movement



(1964-2007 & 2011, M5<, USGS)

- wide distribution along the plate boundary
- Magnitude: M9.0-M2 (detectable limit)

Magnitude-frequency diagram



(1924-2007, M5<, JMA)

The mechanism can be related to them

← Another model of G-R law called as "cumulative Gompertz distribution" can have the same entropy formula as that in heavy ion physics (Biro et al, 2015)

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(It causes the earthquakes occurrences)

fracture and deformation in the earth's crust

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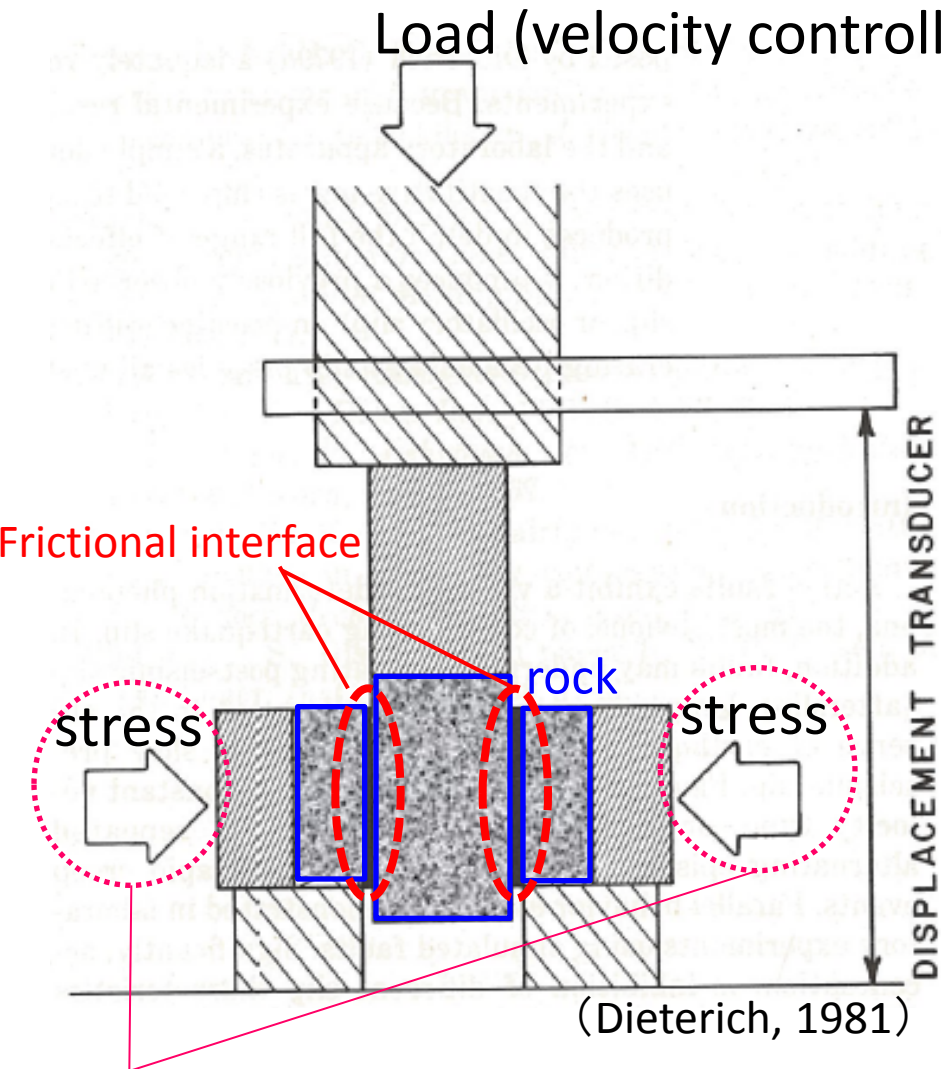
## 2. Purpose: thermodynamic modeling of rock friction

## 3. Research

- introduction: rock experiments
- thermodynamic modeling

## 4. Summary

# Outline of rock experiments



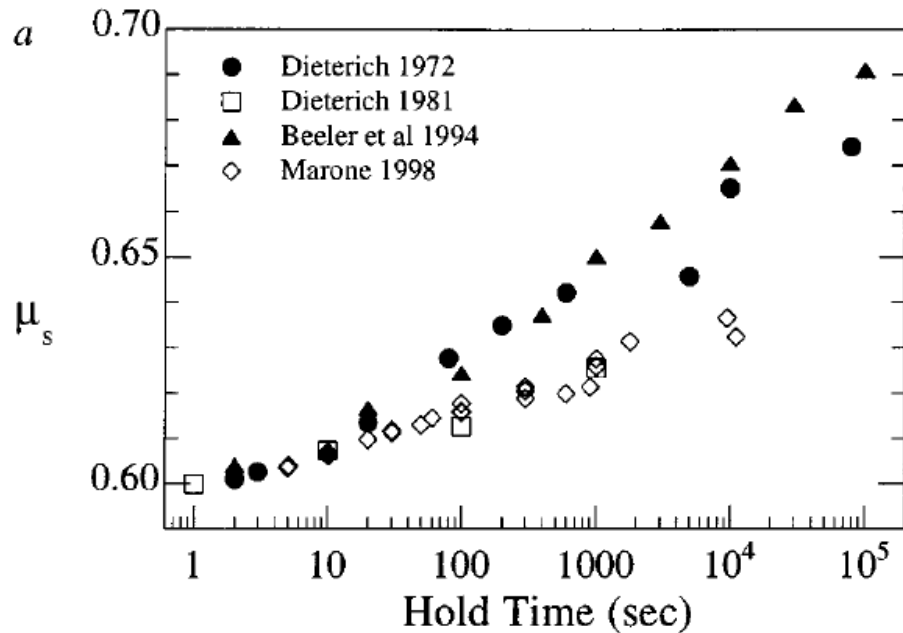
- Static & dynamic friction are tested with various condition:

( rock type, temperature, humidity, normal stress with/without sand at the interface )

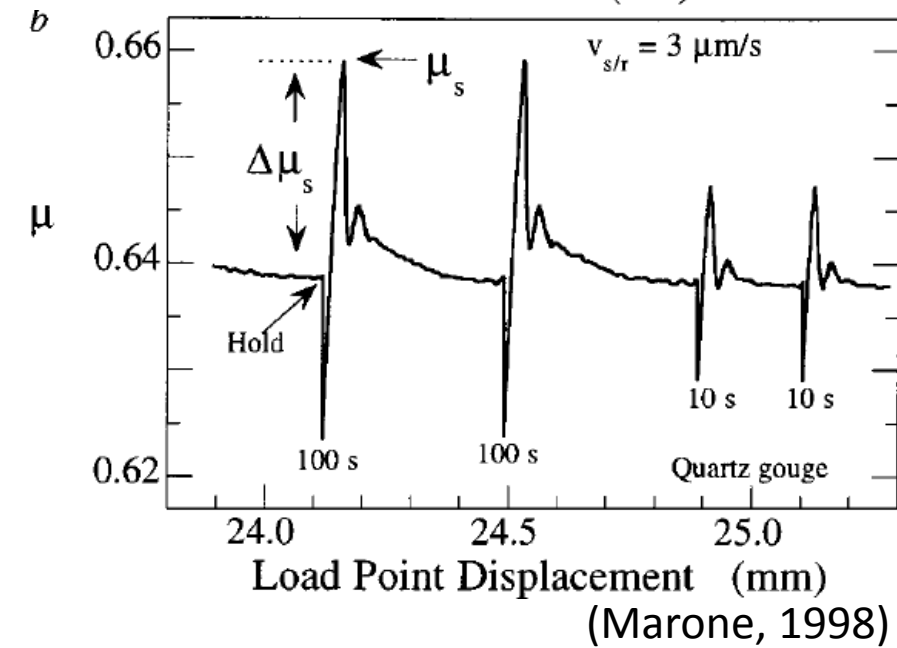
Servocontrolled to constant



# Static friction increases with time

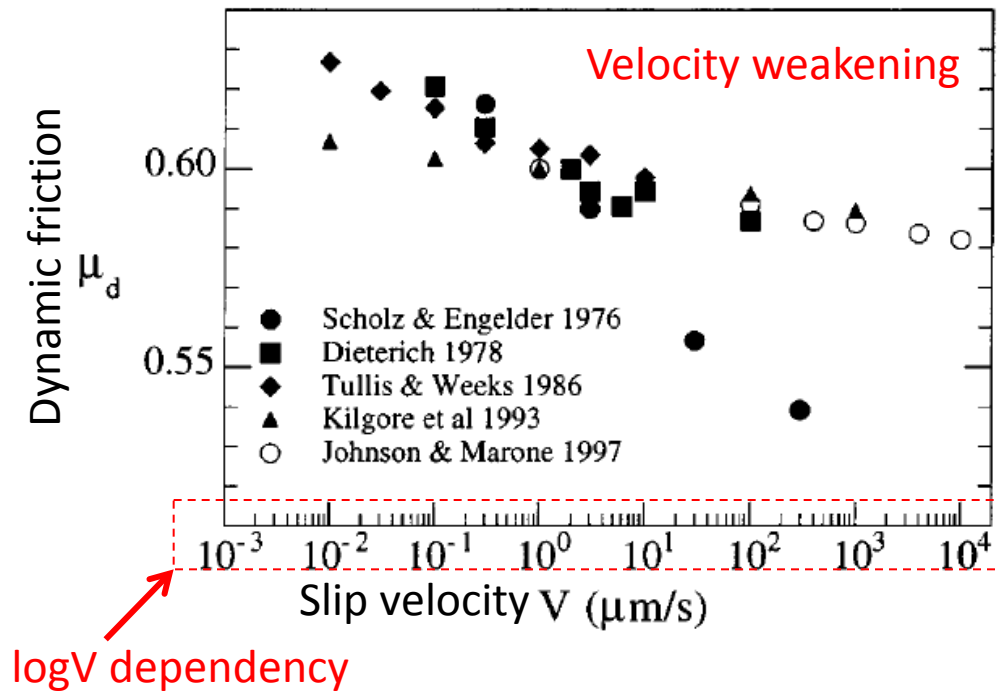


- Static friction  $\propto \log(\text{time})$



- Friction decreases to dynamic one with displacement

# Feature 1/3: Stable dynamic friction $\propto \log(\text{slip velocity})$

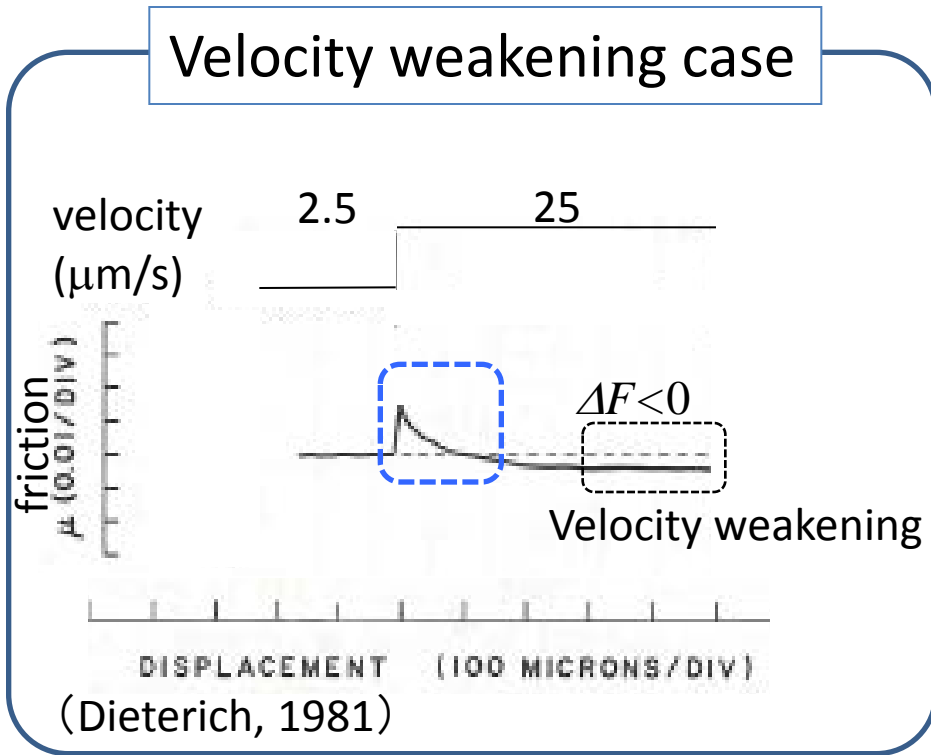


(Marone, 1998)

- Rock samples loaded with constant velocity
- Friction weakens or strengthens with velocity depending on the tested condition

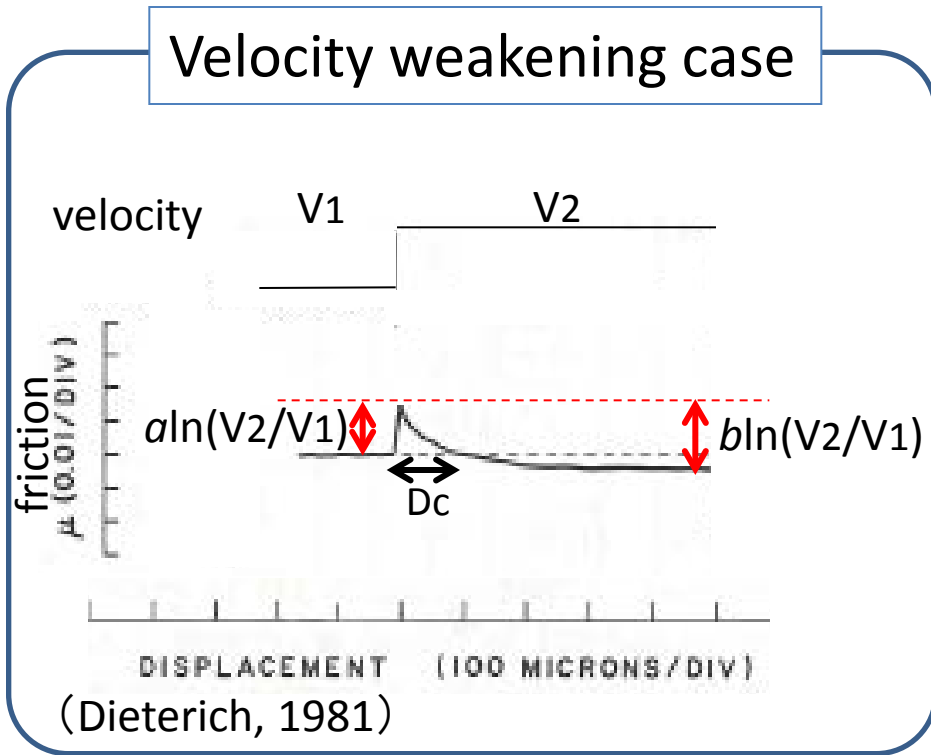
ex. Interface sand  
without sand: weaken  
with sand: strengthen

## Feature2/3: frictional jump $\propto \log(\text{velocity step})$



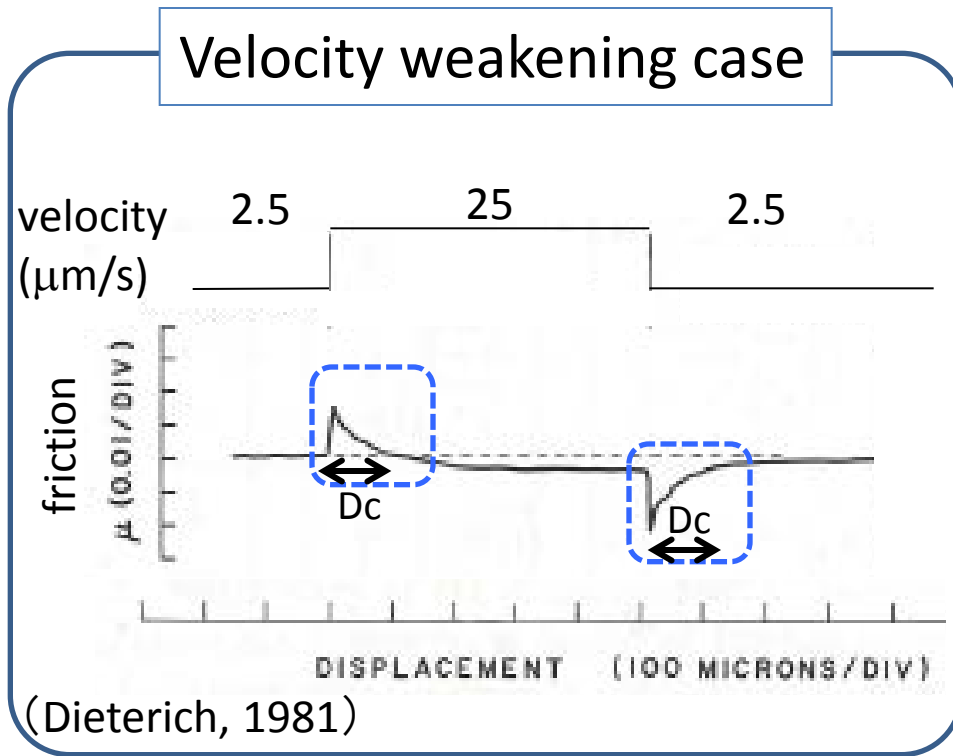
- Loading velocity step causes instantaneous jump of dynamic friction
- Following the jump, the friction transitions to the stable one
- Both jump and relaxation depend on  $\ln(\text{velocity step})$

## Feature2/3: frictional jump $\propto \log(\text{velocity step})$



- Loading velocity step causes instantaneous jump of dynamic friction
- Following the jump, the friction transitions to the stable one
- Both jump and relaxation depend on  $\ln(\text{velocity step})$

# Feature3/3: symmetric relaxation with constant displacement



- Both case of velocity increase and decrease has frictional jump and relaxation with constant displacement ( $D_c$ )

vel. increase: jump up

vel. decrease: jump down

# Empirical equation of the friction law

Empirical equations of  
rate- and state-dependent friction law

$$\textcircled{1} \mu = \mu_o + a \ln\left(\frac{V}{V_o}\right) + b \ln\left(\frac{V_o \theta}{D_c}\right)$$

$$\textcircled{2} \frac{d\theta}{dt} = 1 - \frac{V\theta}{D_c} \quad \text{or} \quad \frac{d\theta}{dt} = -\frac{V\theta}{L} \ln\left(\frac{V\theta}{L}\right)$$

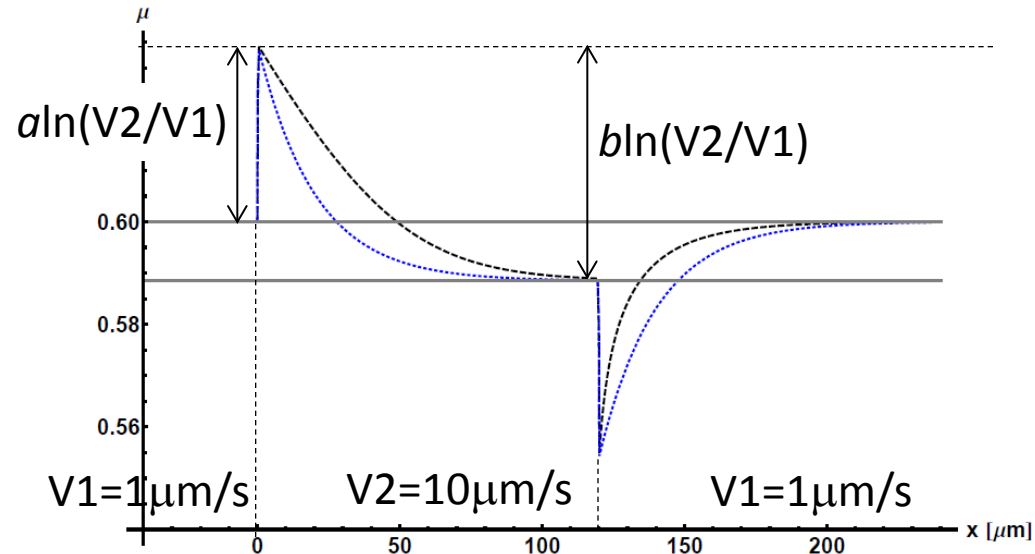
(Dieterich, 1979)

(Ruina, 1983)

☺: Static friction      Dynamic friction

$\mu$ : shear stress     $t$ : time     $V$ : slip velocity  
 $\mu_o$ : reference friction for  $V_o$   
 $D_c$ : characteristic slip distance  
 $\theta$ : state variable     $a, b$ : positive parameters

Simulated frictional change  
with displacement



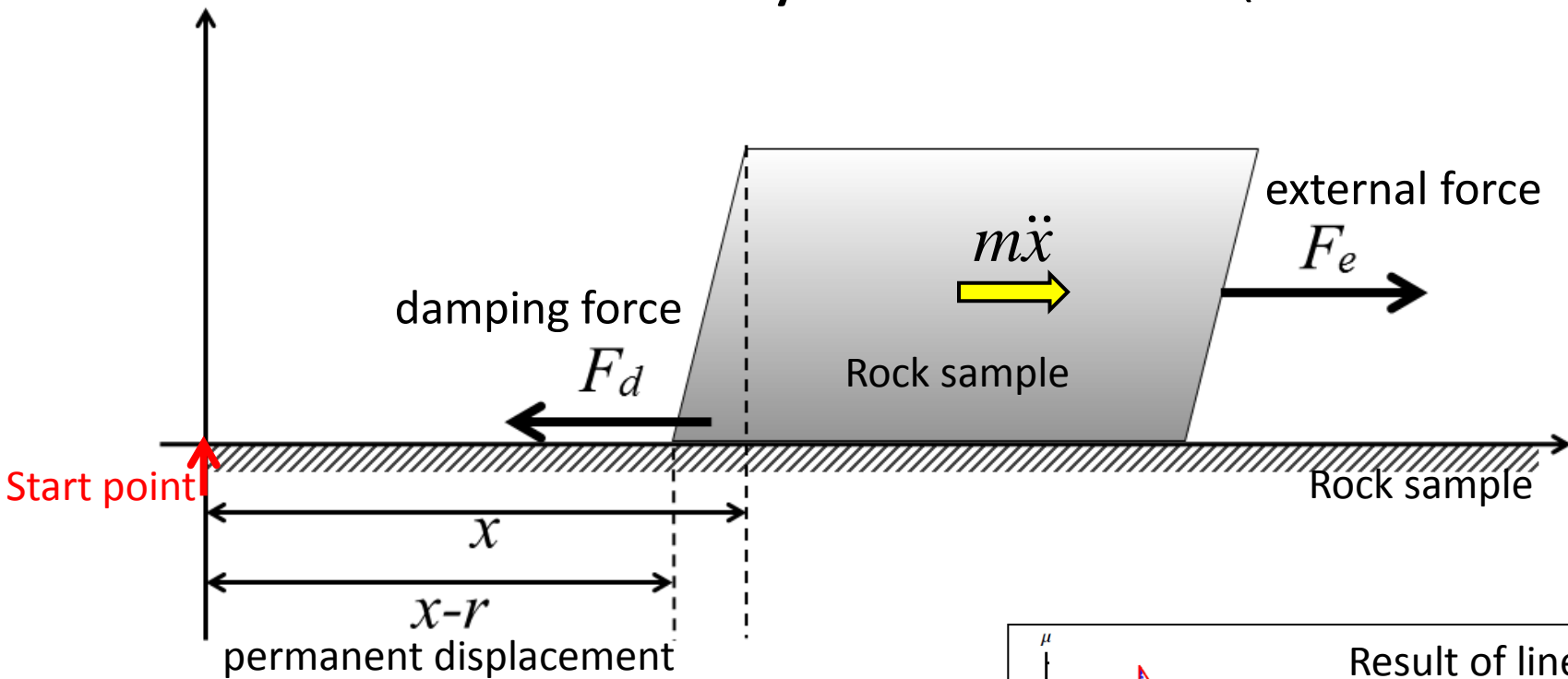
- Neither of them can reproduce both (static & dynamic) friction.



- We will reproduce the experimental result with **thermodynamics**.

friction = dissipative event -> thermodynamic issue

# Previous thermodynamic model (Mitsui and Van, 2014)

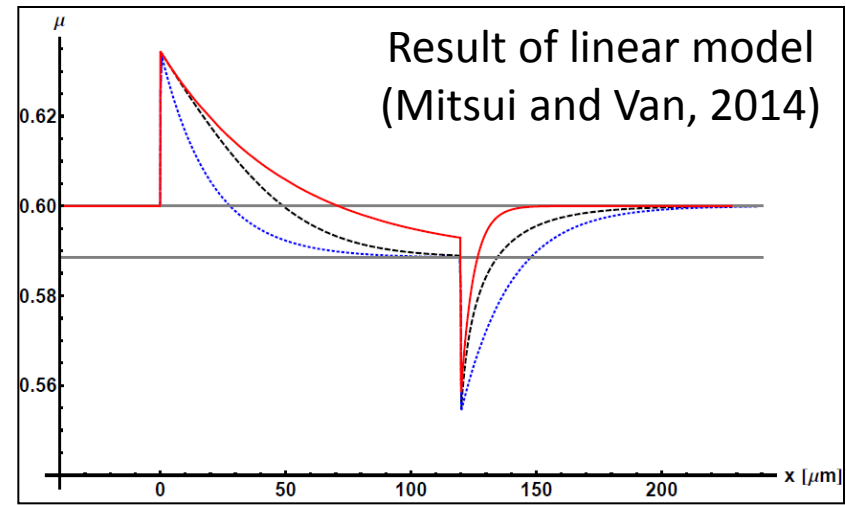


equation of motion :  $m\ddot{x} = F_e - F_d$

total energy :  $\dot{E} = F_e \dot{x} = F_e V$

entropy :  $S \left( \underset{\substack{\uparrow \\ \text{internal energy}}}{U} = E - mV^2/2 - \underset{\substack{\uparrow \\ \text{elastic modulus}}}{kr^2/2} \right)$

entropy balance :  $TS\dot{(U)} = F_d V - kr\dot{r} \geq 0 \quad \because \text{2nd law of thermodynamics}^{23}$



# Improvement of thermodynamic model

- Important feature

1. instantaneous jump

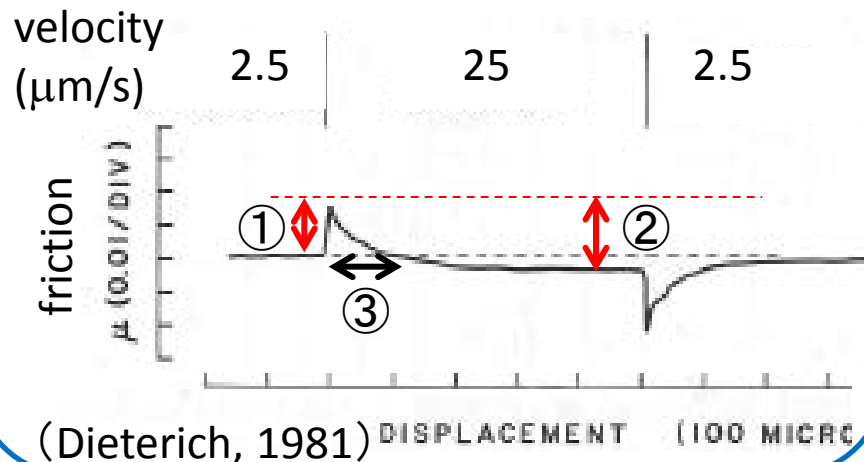
$$a \ln(V_2/V_1)$$

2. following relaxation

$$b \ln(V_2/V_1)$$

3. symmetric relaxation with disp.

Dc



(Van, Mitsui, Hatano, 2015, arXiv:1501.04608v1)

- introduced elements

1. partial steady state

$$U = E - mV^2/2 - kr^2/2$$

↓

$$U = E_0 - m(V - V_0)^2/2 - kr^2/2$$

2. logarithmic increment

based on thermal activation theory  
(chemical reaction: Eyring, 1936;  
rock friction: Nakatani, 2001)

$$\Delta\mu(V - V_0) \rightarrow \Delta\mu \ln(V/V_0)$$

3. factor of slip reduction

in elastic displacement

$$\frac{dr}{dt} \rightarrow \frac{dr}{d(x - \alpha r)} = \frac{\dot{r}}{V - \alpha \dot{r}}$$



# Improved constitutive equations

entropy balance :

$$\frac{T\dot{S}(U)}{\sigma_n A} = \mu V - \kappa r \dot{r} \geq 0$$

cf. Ruina law (1983)

$$\frac{dr}{dt} \rightarrow \frac{dr}{dx} = \frac{\dot{r}}{V}$$

Improvements

1. partial steady state
2. logarithmic increment
3. factor of slip reduction

$$\frac{T\dot{S}(U)}{\sigma_n A} = \mu_0 V_0 + \underbrace{\Delta\mu}_1 \ln(V / V_0) - \kappa r \frac{\dot{r}}{\underbrace{V - \alpha \dot{r}}_3} \geq 0$$



constitutive equations:

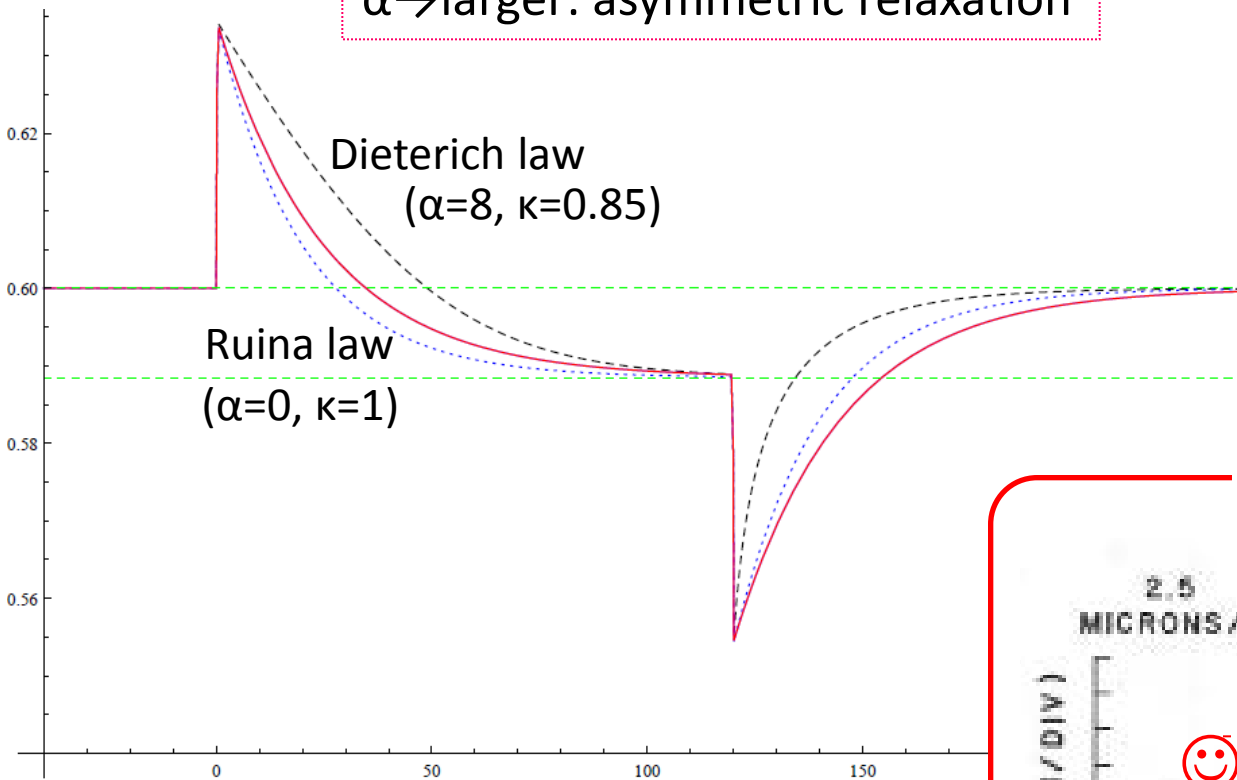
$$\begin{cases} \Delta\mu = l_1 \ln(V / V_0) - l_{12} \kappa r \\ \dot{r} = V \frac{l_{21} \ln(V / V_0) - l_2 \kappa r}{1 + \alpha(l_{21} \ln(V / V_0) - l_2 \kappa r)} \end{cases}$$

# Results

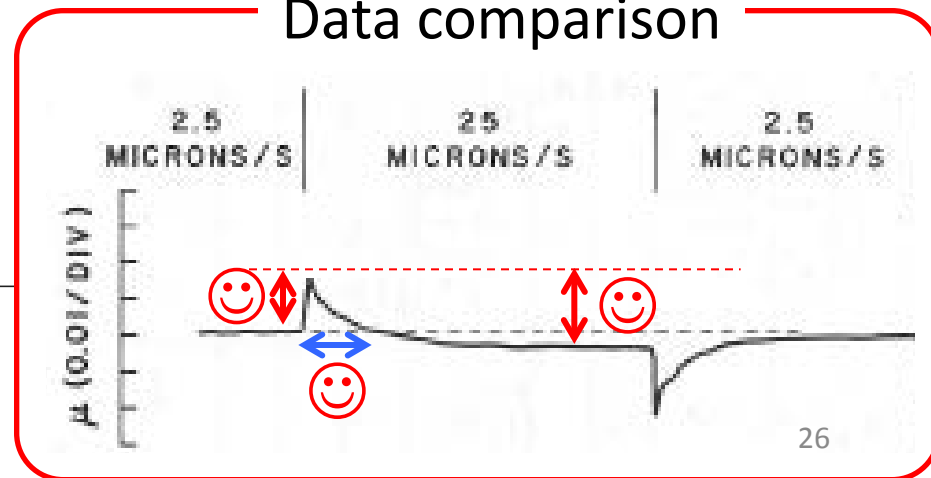
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$$\begin{cases} \alpha = 1, \kappa = 0.8 \\ l_1 = a = 0.015, l_{12} = b = 0.02 \\ l_{21} = l_2 = 1/L = 20 \mu m \end{cases}$$

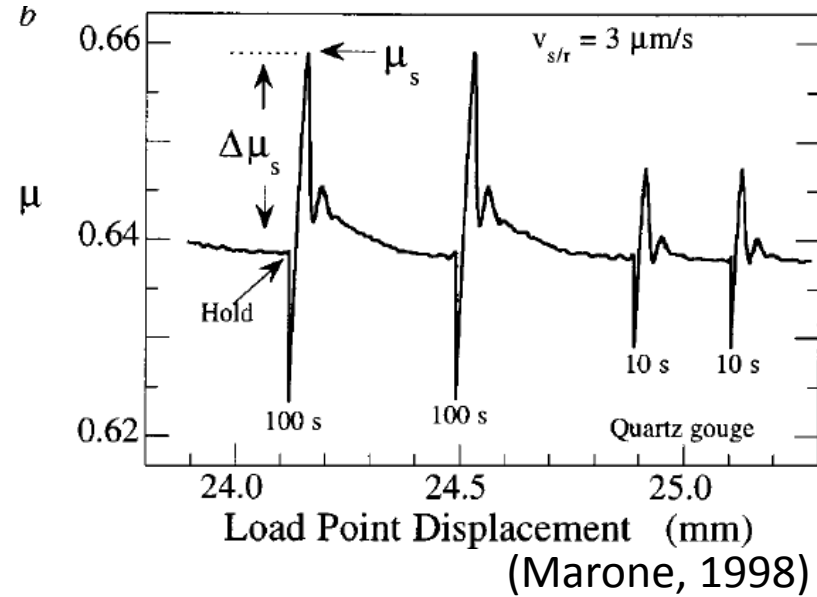
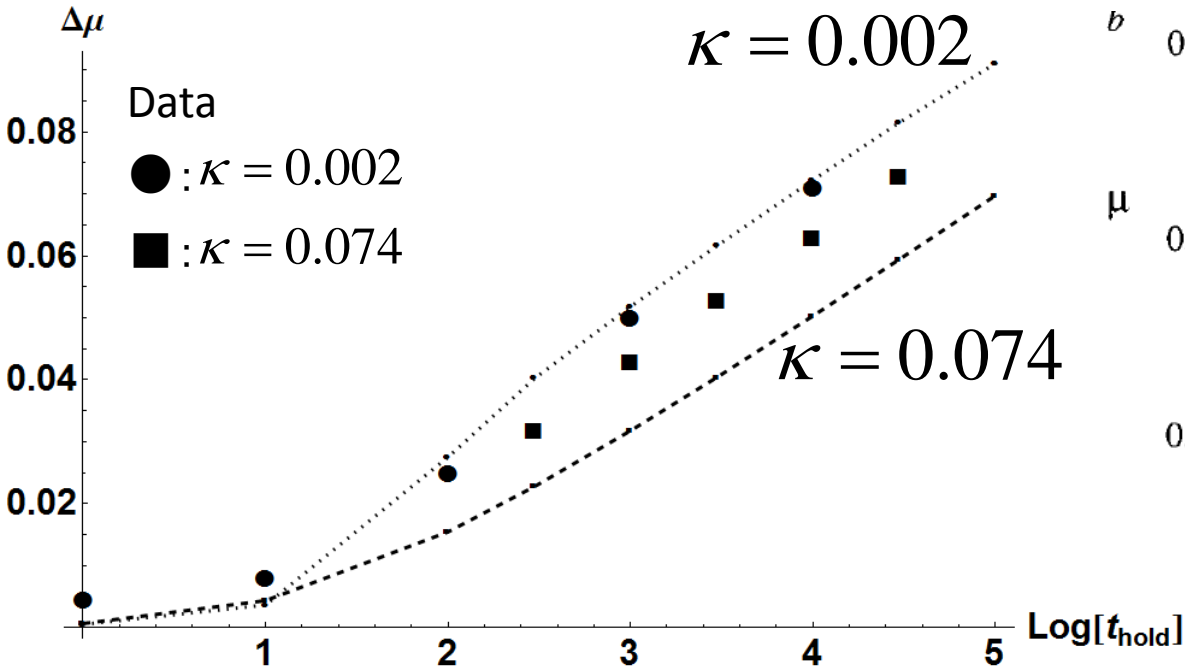
$\alpha \rightarrow$  larger: asymmetric relaxation



## Data comparison



# Static friction



- log(t)-like increase in static friction  $\Delta\mu$  is reproduced
- Both dynamic & static friction are reproduced with one set of constitutive equations

# Summary

- First motive: to understand mechanism of earthquakes  
↓
- Current motive: deformation theory of medium under stress  
object: static & dynamic friction of rocks  
(quasi-thermostatic condition)

Results:

1. friction at reference velocity can be explained by using partial steady-state condition of internal energy
2. logV dependencies of friction are reproduced by the logarithmic increments of entropy production
3. symmetric relaxation can be explained by introducing a factor of slip reduction in elastic evolution
4. Above three elements reproduce log-t increase of static friction

Advantage:

simple model can be applied to geophysics with upscaling

Future plan: physical bases of assumptions in this model, etc.